

Secure Multi-Party Computation with Service Contract Automata

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By combining research from model-based software engineering, dependable computing, and formal methods, it is possible to create a contract-based design methodology to enforce security accountability and reputation of distributed digital entities provided by potentially mutually distrusted organisations.

Our society is increasingly dependent on heterogeneous digital infrastructures, for example in the healthcare, financial and transport domains. These infrastructures are examples of systems of systems, i.e., they are realised through the composition of several sub-systems provided by potentially mutually distrusted or competing organisations. An example is the ERTMS/ETCS Level 3, a new railway signalling system where virtual positioning is replacing legacy physical systems, and the geolocation sub-system is provided by a third party (e.g., European GNSS service). Moreover, emerging computing paradigms (e.g., fog, mobile-edge or cloud computing, to mention a few) rely on components discovered and accessed over the internet. The composed behaviour needs to be validated to guarantee overall security, as well as safety and interoperability requirements.

In these emerging multi-party paradigms, no assumption shall be made about third-party systems, which are accessed as a black box. Thus, standard monolithic verification techniques used for validating digital entities cannot be applied to ensure the overall security of these digital infrastructures. Indeed, novel formal verification techniques must cope with the unwanted scenario where a verified system does not comply with its expected behaviour (called contract), either unintentionally or maliciously, or when the necessary security measures are not in place. For cyber-physical systems, we also cannot make assumptions about the open physical environment in which these systems are operating, whose behaviour (e.g., delays of radio communications, geo-positioning uncertainty) could be tampered with by attackers to drive an unprepared system to unsafe configurations to carry out the attack.

Service contracts [1] have been introduced in the literature as a methodology for designing systems where the requirements and obligations of each party are rigorously specified and rendered as formal specifications, e.g., automata (see Figure 1). The security threats are thus considered from the early design phases of a system. This can reduce costs by detecting design flaws as early as possible, for example, unsecure assumptions on other components or the environment (e.g., stochastic distribution on delays or positioning errors). Contracts are digital entities that must be composable to predicate over their aggregate multi-party behaviour. Firstly, it is necessary to check whether the requirements of each

contract are satisfied in the composition by some other contract. Traces leading to violation of the requirements must be pruned to obtain a composition where all involved parties adhere to the shared behaviour. Starting from a raw composition of contracts, this contract agreement can be synthesised automatically [2]. The contract agreement is then proposed to each involved party for validation or further formal verification, before starting their interactions, to ensure the correctness and security of their composed behaviour. Due to the stochastic, physical nature of phenomena involved in a cyber-physical infrastructure, a challenge is to investigate novel formalisms and verification techniques for specifying and verifying contracts expressing both the discrete and continuous aspects under analysis, as well as the stochastic physical phenomena involved.

During the computation, the agreement is realised through coordination of distributed software entities, to allow them to fulfil both their specified requirements and declared obligations. The coordination is generally achieved using a choreographic or orchestrated approach [3], and the requirements for realising a choreography are more stringent because each party must be able to fulfil its requirements and duties independently of the other entities involved in the overall computation. This amounts to project the global agreement to each local component, and if the proper conditions are satisfied, using the local contract agreement instead of the global one to check that each component fulfils its agreed behaviour. On the other hand, an orchestration drives the involved parties to realise their agreed computation, at the cost of extra coordination interactions. In the orchestrated approach, the orchestration is responsible for guaranteeing that the contract agreement is realisable. Thus, the orchestration needs to be a trusted software component.

The key aspect is that the multi-party computation can be monitored at runtime by exploiting the contract agreement each party has signed beforehand, to detect possible contract breaches in case obligations are not fulfilled, providing log information for post-mortem analyses. Indeed, it is assumed that each party can fulfil its contract and is responsible for violations. In this scenario, it becomes possible to identify the organisations liable for providing services breaching the contract they have agreed upon. This is at the basis of a methodology for formally specifying systems able to guarantee the necessary security accountability and reputation mechanisms for digital organisations.

An open-source API available at [L1] has been produced by the author for developing contract-based applications using a model-driven state-based design approach for software applications built around their specified contract. An open-source graphical application for designing contract specifications, composing them and synthesising a coordination policy in agreement is available at [L2], which has been developed using the API in [L1].

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Links:

[L1]: <https://github.com/davidebasile/ContractAutomataLib>

[L2]: <https://github.com/davidebasile/ContractAutomataApp>

References:

[1]: Basile, D., 2016. Specification and Verification of Contract-Based Applications (Ph.D. thesis, Department of Computer Science, University of Pisa). <https://etd.adm.unipi.it/t/etd-07052011-105210/>

[2]: Basile, D., ter Beek, M.H., Degano, P., Legay, A., Ferrari, G.L., Gnesi, S. and Di Giandomenico, F., 2020. Controller synthesis of service contracts with variability. Science of Computer Programming, 187. DOI: <https://doi.org/10.1016/j.scico.2019.102344>

[3]: Basile, D., ter Beek, M.H. and Pugliese, R., 2020. Synthesis of Orchestrations and Choreographies: Bridging the Gap between Supervisory Control and Coordination of Services. Logical Methods in Computer Science, 16. DOI: [https://doi.org/10.23638/LMCS-16\(2:9\)2020](https://doi.org/10.23638/LMCS-16(2:9)2020)

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Figure 1: An example of a real-time service contract automaton.

