

1 **Vibrational imaging for label-free cancer diagnosis and classification**

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18 **Abstract**

19 The first key step in the detection and classification of most cancers is the microscopic assessment of thin tissue
20 slices, the so-called “histopathology”. This procedure is still nowadays, similarly to 150 years ago, performed by
21 staining the tissue with two or more dyes able to bind to specific biological structures, followed by visual inspection
22 by the histopathologist under the bright-field optical microscope. This approach involves long manual procedures
23 which can be accompanied by human errors, subjectivity, and lack of reproducibility.

24 Vibrational microscopies are capable of directly providing chemical and biomolecular information on tissues,
25 identifying them through their fingerprint vibrational spectra without the need of staining and thus constitute
26 powerful tools for label-free and objective tumour identification. The two most established techniques,
27 spontaneous Raman scattering and infrared absorption microscopy, suffer respectively from long acquisition times
28 and low spatial resolution. These limitations can be overcome by novel and more technically demanding approaches
29 such coherent Raman scattering and photothermal infrared microscopy.

30 Here we present an extended overview of the major advances in the field of vibrational imaging for cancer diagnosis.
31 We start from a detailed description of the different technologies and then present examples of their applications
32 to tissue imaging for cancer assessment. We critically compare the presented approaches, discussing the steps
33 required to bring these powerful technologies from bench to bedside.

34
35 **Keywords:** hyperspectral, tumours, Raman, FT-IR, SRS, CARS

1. Introduction

Approximately 19 million new cancer cases and 9.6 million cancer deaths have been reported in 2018, according to the most recent report on the global burden of cancer worldwide [1]. In this context, even if prevention and therapeutic interventions have been dramatically improved in the last decades, both incidence and mortality are rapidly increasing, mainly due to increased lifespan and population growth, and diagnosis still plays a major role. Underdiagnosis (failure to recognize carcinoma), overdiagnosis (false positive report) and misdiagnosis (incorrect identification of the tumour type) are associated to late or wrong interventions, unnecessary invasive procedures and enormous costs for national healthcare systems [2,3].

Despite the promising use of blood-based cancer biomarkers - with the approval of just few of them by the Food and Drug Administration (FDA) for clinical use [4] - and the massive investment on non-invasive imaging approaches as screening tools, tissue biopsies are still the current diagnostic gold standard. Biopsies provide access to the most complete morphological, molecular, and genetic information of the investigated lesions, required for the identification of its benign or malignant nature, and for its classification. According to the current guidelines from the World Health Organization (WHO), for the diagnosis of most tumours, the microscopic examination of the tissue (histopathology) is still among the first fundamental diagnostic steps [5–7].

Histopathology was born in 1838, when Johannes Müller pioneered the use of the microscope in pathology, focusing “On Nature and the Structure Characteristics of Cancer”, the first book in the field [8]. And this is still the basic principle of histopathology to date: the detailed examination of the histological (tissue) sample by a medically qualified pathologist who formulates a pathological report based on morphological evidence, compared to those reported on available guidelines. In the standard histopathologic workflow, the tissue samples collected from different organs of the patient (so-called biopsies) are chemically processed for fixation (usually overnight), cut into thin slices, chemically stained, positioned within microscope slides, then visually inspected by the histopathologist, usually a few days after sample collection.

The sample preparation workflow is fundamental to guarantee the final quality of the histological assessment. The tissue itself cannot be observed as it is, for many reasons. First, soft tissues must be cut into thin slices (a few μm thickness) to permit sufficient light transmission. In turn, this requires tissues to be embedded into a denser material (usually paraffin wax) to preserve their structure during the cutting procedure. Second, biological structures and biomolecules need to be preserved from the decay induced by interaction with microorganisms or enzymatic autolysis, which requires their stabilization to enable long-term use and make them compatible with specific staining or labelling procedures. In the standard slide preparation protocol, tissues are first saturated with formalin and then embedded in a paraffin wax block, according to the so-called formalin-fixed paraffin embedded (FFPE) procedure. The obtained tissue block is then cut by a microtome into thin slices, which are subjected to the staining process. The FFPE protocol is the most widespread approach and provides the highest quality for histologic images; in addition, FFPE samples are very stable and can be archived for decades in the so-called “biobanks”, for further consultation during patient treatment and for legal purposes. On the other hand, FFPE is laborious and time consuming and the process denatures the tissue proteins, preventing their identification by labelled antibodies.

An alternative tissue preparation protocol consists in rapidly cooling the excised tissue (fresh or snap freezing) for fixation and slice cutting. Frozen tissues can be cut equally well by a dedicated microtome, called cryostat, and subjected to standard staining procedure, bypassing the lengthy FFPE approach thus possibly saving up to 2-3 days. This method is typically used in an intraoperative setting when a rapid lesion assessment is required to guide the

1 surgical intervention. In this case, the samples are processed and examined immediately (between 20 to 40 min),
2 using approaches which deliver quick information but with a poorer morphological quality, due to a limited fixation
3 process and consequent suboptimal staining results. On the other hand, snap freezing protocols preserve the native
4 non-denatured structure of proteins and preserve most of lipid vacuoles, which are normally removed during FFPE
5 protocols due to the extended use of solvents. Despite these advantages, fresh frozen slices are typically used only
6 for intraoperative assessment and not for routine diagnosis because, for observation of stained tissue slices using
7 standard light microscopies, the morphological and staining quality (see below) guaranteed by the FFPE procedure
8 is more important than the preservation of biochemical features guaranteed by snap freezing. However, a higher
9 priority to fresh-frozen samples and their benefits could be given with the advent of new imaging approaches based
10 on the direct detection of biomolecules, such as those based on vibrational contrast, described in the next sections.

11 Once the tissue has been fixed and cut into thin slices, the detailed morphological features are still almost invisible,
12 due to the lack of an intrinsic contrast detectable by the sole visible light, so that staining with suitable dyes is
13 required. The haematoxylin and eosin (also known as H&E) staining technique is the gold standard in histopathology
14 laboratories since nearly 125 years [8] and allows the pathologist to distinguish a wide range of normal and
15 abnormal cell and tissue components. Haematoxylin marks the cell nuclei in purple/blue, while eosin gives a pink
16 colour to the cytoplasm and the extracellular connective tissue matrix, with other tissue structures assuming
17 different hues and combinations of these colors.

18 Tissue staining gives a “structural” information on the tissue, showing its general morphology, the cells distribution
19 and the nuclei to cytoplasm ratio, i.e. the so-called histoarchitecture. Once the staining raises the suspicion of a
20 certain disease, more specific stains or labelling procedures can be applied, for example using antibodies targeted
21 to specific antigens (e.g., proteins, nucleic acids) in the tissue, in the so-called immunostaining approaches. The
22 antibody can be visualized by conjugating it either to a fluorophore such as rhodamine or fluorescein (a method so
23 called “immunofluorescence”) or, more commonly for diagnosis, to an enzyme able to produce a coloured
24 precipitate (a method so called “immunohistochemistry” (IHC)). Immunostaining provides a biological information
25 on the sample, allows identifying the distribution and concentration of specific biomarkers, and is typically applied
26 to confirm the diagnosis or to accurately determine the tumour type (grading and staging). However, it is an
27 expensive and long procedure, sometimes based on several optimization steps. Furthermore, for every biomarker
28 to be detected a different immunostaining experiment needs to be performed on a dedicated tissue slice.

29 Traditionally, H&E-stained or immune-labelled tissue slides are diagnosed by direct visual inspection under the
30 microscope. This approach, besides its subjective nature, requires the action of the pathologist, a highly specialized
31 professional figure. Though representing the current state of the art in pathological diagnostics, H&E and immune
32 staining approaches are neither quantitative nor objective, as they rely upon the opinion of the pathologist. The
33 ideal diagnostic approach for tissue samples would thus include fast sample preparation, reproducibility, and an
34 objective and accurate evaluation.

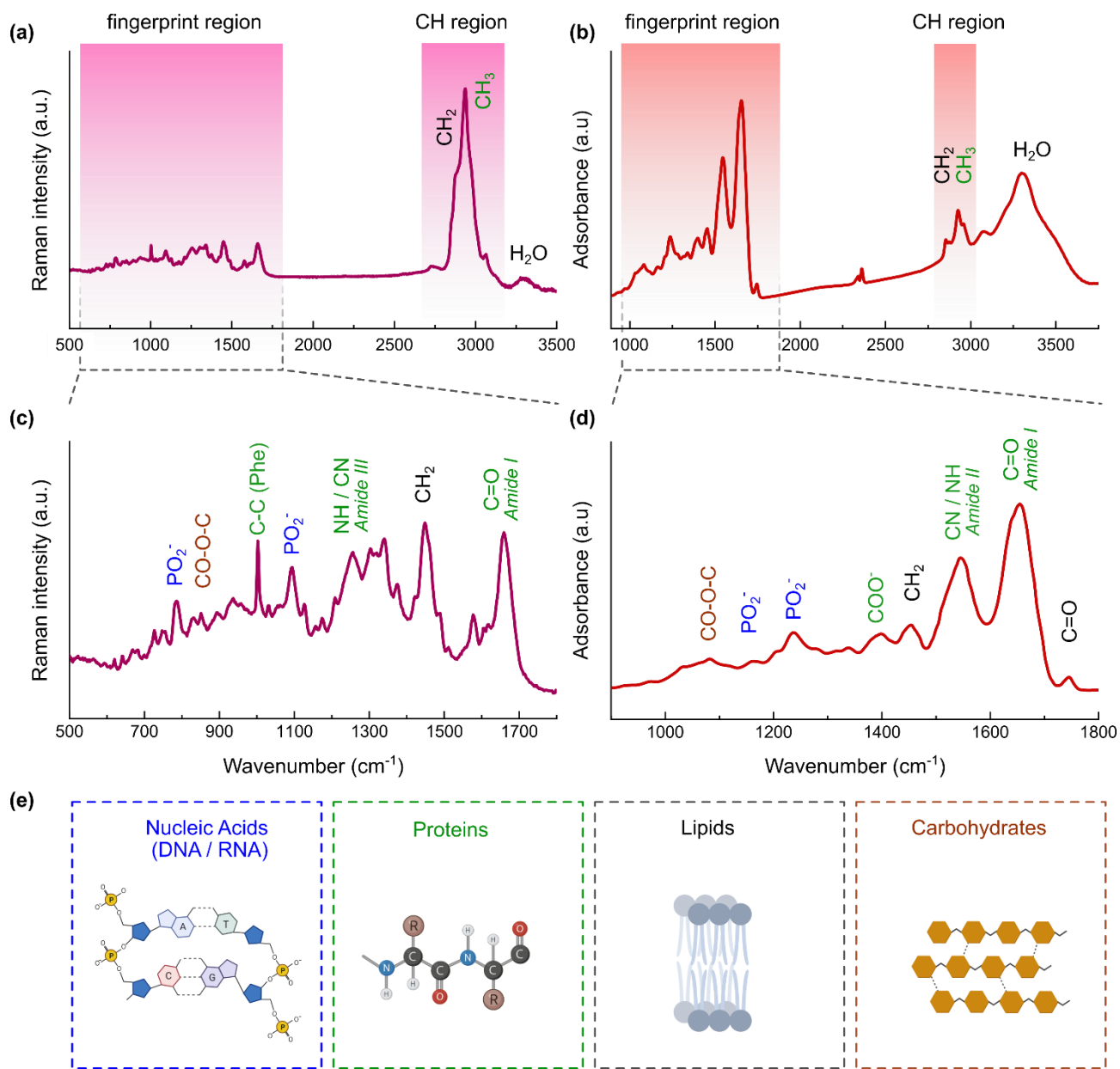
35 Very recently, a number of limitations associated to H&E (or similar) staining procedures have been overcome by
36 the introduction of digital pathology (DP), which performs high resolution scanning of the tissue slide and generates
37 a digital image consisting of a matrix of optical density data [9]. In a digital microscope, also known as whole-slide
38 scanner (WSS), a high-resolution image is acquired over a comparatively small field of view (FOV) of the tissue slide,
39 of the order of 200×200 μm, and multiple images obtained by translating the slide are stitched together to
40 reconstruct a whole-slide image (WSI) in a tile-based mosaic pattern. The WSI provides to the pathologist in principle
41 the same information that he/she would obtain by visual inspection under the microscope, but with important

1 advantages: i) the digital image, despite its large size (several GBs), can be easily transmitted over large distances,
2 enabling prompt diagnosis of samples collected in remote areas, provided that a whole slide scanner is available
3 (telepathology); ii) the same image can be submitted to several pathologists, enabling them to compare their
4 diagnoses and improve accuracy/objectivity through a consensus report; iii) WSI data can easily be stored and
5 retrieved for later consultation, in a much more convenient way than the physical tissue slides in the biobank. DP
6 has only very recently gained FDA approval for diagnostic use, after a multi-center study involving 1992 patients
7 with different tumor types and 16 surgical pathologists showed it not inferior to traditional microscope based
8 approaches [10].

9 Most importantly, the digital images provided by DP can be analyzed using computer algorithms, which can provide
10 spatial relationships between different cellular or stromal components, such as cell nucleus, cytoplasm and
11 membrane, allowing for more precise association of the tissue morphology to a specific phenotype or pathology.
12 Artificial intelligence (AI) may be particularly powerful in this context, especially machine learning (ML) approaches
13 that, by continuously feeding data to the machine and going through a sequence of training cycles, train it to make
14 safe predictions [11]. Of particular interest are deep learning (DL) approaches, which make use of neural networks
15 (NNs) connecting an input layer to an output layer through a series of hidden layers. DL has already been applied to
16 the analysis of DP data. While DP can alleviate some of the shortcomings of histopathology, at least by improving
17 objectivity, the information content is fundamentally similar to that of H&E - and mainly of morphological nature –
18 and also issues related to sample preparation are identical.

19 In the last three decades vibrational spectroscopies have shown the capability to directly provide chemical and
20 biomolecular information (and image contrast) on tissues and cells, identifying them through their fingerprint
21 vibrational spectra without the need of staining and labelling, and virtually without any additional sample
22 preparation step (here we suggest three general review articles on vibrational based approaches for biomedical
23 applications [12–14]). Vibrational-based microscopy approaches are non-contact, non-invasive and non-destructive
24 methods. Every component of a biological specimen is characterized by a vibrational spectrum made up of several
25 peaks with different frequencies and amplitudes, each representing a specific chemical bond found within the
26 tissues and cells being measured (see **Fig. 1**). This includes the four main biological macromolecules (i.e. nucleic
27 acids, proteins, lipids and carbohydrates) but also the so called “small molecules”, generally defined as smaller than
28 900 Da (i.e., g/mol) (e.g. small hormones, metabolites, etc.) that are hardly visible by standard staining or
29 immunolabeling approaches. The vibrational spectrum is a superposition of all these peaks and provides a detailed
30 picture of the biochemical composition of the cells and tissues being measured. These endogenous and chemically
31 specific molecular fingerprints thus become reliable biomarkers, allowing crucial properties/phenotypes of cells
32 (e.g., subtype, differentiation, cell cycle state) and tissues (e.g. normal, cancerous, extracellular matrix content) to
33 be identified, and used for cancer diagnosis and classification.

34



1

2 **Fig. 1** representative biological Raman (a) and IR (b) spectra in the respective typical full ranges and the corresponding
 3 fingerprint region (b and d, respectively). The peak assignments are reported for the most representative and abundant
 4 chemical bonds in biological samples, belonging to the four major biological molecules (e). Both Raman and infrared (IR) spectra
 5 were plotted using the same x-axis orientation for clarity even if IR are typically plotted with decreasing wavenumbers. The
 6 Raman spectrum was collected by the authors using a home-built spontaneous Raman microscope (Prof. Cees Otto group,
 7 Twente University, NL; ref. [15]. The IR spectrum was collected using a FT-IR microscope and kindly provided by Prof. Nick Stone
 8 and colleagues (Exeter University, UK). Both spectra are the average of multiple spectra, wavenumber and intensity calibrated,
 9 without further processing steps. a.u.: arbitrary units. Created with BioRender.com.

10 Measuring the vibrational spectrum at every pixel allows one to identify simultaneously the above-mentioned
 11 target molecules or macromolecules and to map their distribution within tissues in a completely non-destructive
 12 and label-free way. This information can then be used to generate false-color images, possibly mimicking those
 13 obtained by the standard H&E approach, and to which histopathologists are used. This approach is called virtual
 14 histopathology, as it enables to obtain images comparable to H&E staining but without the need to add any labels

1 to the tissue slide. Virtual histopathology has the potential to work on fresh unprocessed samples, which is
2 especially important for an intra-operative setting; in addition, it provides a digital information that can be achieved
3 and shared, similar to DP, avoiding the operator-dependent staining procedure and thus enhancing reproducibility.
4 However, it fundamentally delivers the same kind of structural information on the tissue architecture that is
5 provided by H&E, or by similar approaches. Recording the full vibrational spectrum (or even single disease-related
6 frequencies) for every pixel of the image has however the potential to deliver an information which goes well
7 beyond that provided by standard approaches. This so-called “spectral histopathology” approach would disclose an
8 unprecedented level of detail on the biochemical composition of the cells and tissues, combining the structural
9 information of H&E with the detailed biomolecular information provided by the biochemical profile of the sample.

10 Spectral histopathology, being an imaging approach, sets rather demanding requirements on the vibrational
11 microscopy technique: i) high spatial resolution (up to 400-500 nm), comparable to that of standard H&E, in order
12 to possibly visualize the internal structure of cells; ii) broad spectral coverage to enable molecular identification; iii)
13 high acquisition speed, enabling to scan a tissue slide, or a diagnostically significant portion of it, in a time of the
14 order of minutes to a few hours, compatible with the standard histopathology workflow.

15 Coming back to vibrational spectroscopies enabling spectral histopathology, we can introduce two main
16 complementary players: Raman microscopy, also called spontaneous Raman (SR) microscopy, and infrared (IR)
17 absorption microscopy. Raman microscopy (better detailed in **section 2.1**) measures the inelastically scattered light
18 (Stokes) from vibrations which involve a change in the molecular polarizability (the so-called Raman-active modes)
19 (**Fig. 2a**). IR microscopy (better detailed in **section 2.3**) directly measures the absorption in the mid-infrared range
20 ($\approx 2.5\text{-}25\ \mu\text{m}$ wavelength) of vibrational transitions which involve a change in the dipole moment (the so-called IR-
21 active modes) (**Fig. 2d**). While the selection rules for IR and Raman active transitions are different and (generally)
22 complementary, both yield comparable spectroscopic information on the bio-chemical nature of the interrogated
23 sample (between $500\text{-}3200\ \text{cm}^{-1}$) (see **Fig. 1**).

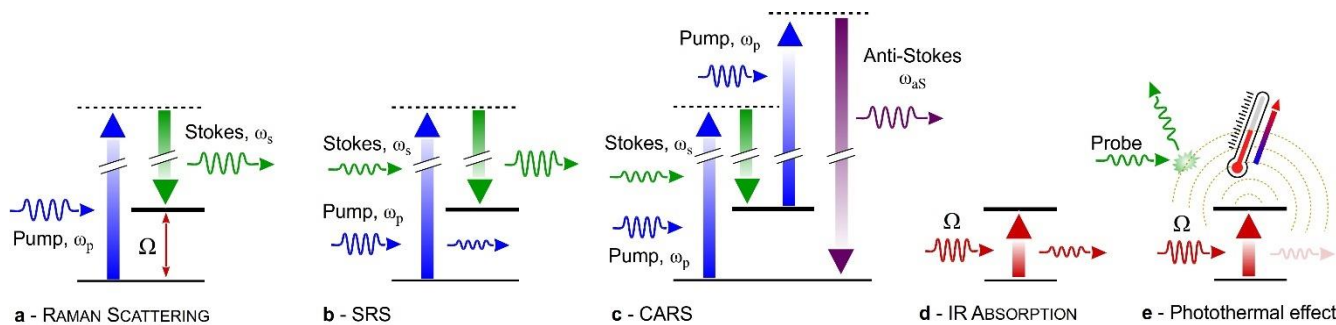
24 SR and IR microscopy each have advantages and drawbacks. In a nutshell, SR provides very good spatial resolution,
25 as it makes use of visible light which can be focused to diffraction-limited spots of 500 nm or smaller, combined
26 with very rich chemical information, as it records a full vibrational spectrum, with little or no interference by water
27 signals. On the other hand, it comes with a very low acquisition speed due to the very small cross-section of the SR
28 process (only one over $10^9\text{-}10^{12}$ incident photons is inelastically scattered), preventing acquisition of high-spatial
29 resolution images in a short time. IR microscopy, on the other hand, exploits the very large absorption cross sections
30 of vibrational transitions to produce intense signals, allowing in principle high acquisition speeds; however, the long
31 IR wavelengths and the low numerical aperture of IR objectives typically limit the spatial resolution to 4-5 μm , which
32 is about one order of magnitude worse than for SR and standard H&E staining and comparable to the size of a cell,
33 thus preventing the imaging of intra-cellular structures. In addition, the IR absorption of water is significant in a
34 rather large part of the fingerprint region, thus limiting the study of water-containing samples (e.g. cells or
35 fresh/frozen tissues).

36 There are however more advanced vibrational microscopy techniques that, at the price of an increased technical
37 complexity, overcome some limitations of SR and IR microscopies. Coherent Raman Scattering (CRS) microscopy,
38 including stimulated Raman scattering (SRS) and coherent anti-Stokes Raman scattering (CARS) (better detailed in
39 **Section 2.2**) generates the Raman signal from a coherent superposition of the molecular vibrations induced by two
40 synchronized ultrashort laser pulses of different color, the pump (at frequency ω_p) and the Stokes (at frequency ω_s)

1 (Fig. 2b,c). When the difference between pump and Stokes frequencies matches a vibrational frequency Ω , then all
 2 molecules in the focal volume are resonantly excited and vibrate in phase. This vibrational coherence enhances the
 3 Raman response by many orders of magnitude with respect to the incoherent SR process, thus decreasing the
 4 acquisition times by several orders of magnitude.

5 Photo-thermal IR (PT-IR) microscopy (better detailed in the Section 2.4) is a very recent variant of IR microscopy
 6 which uses a pump-probe approach, imaging the local thermal effect induced by the absorbed IR radiation using a
 7 visible probe beam. In PT-IR microscopy, an IR pump beam heats the sample by selective resonant excitation of a
 8 vibrational transition (Fig. 2e). The heating results in a change of the sample refractive index, inducing a phase shift
 9 on a co-propagating visible probe beam that is measured by the detector giving a signal proportional to the
 10 absorbed IR power. The PT-IR approach elegantly combines the high spatial resolution (<400 nm) given by the visible
 11 probe beam with the vibrational sensitivity afforded by selective IR excitation of the molecular vibration of interest.
 12 CRS and PT-IR microscopies are currently under intense technological development, with rapid improvements in
 13 acquisition speed, sensitivity and spectral coverage being constantly reported.

14



15

16 **Fig. 2:** sketch of the transitions involved in the different vibrational spectroscopies of a level of frequency Ω . Dashed lines
 17 represent virtual levels involved in the transitions. **a** Spontaneous Raman scattering; **b** Stimulated Raman Scattering (SRS); **c**
 18 Coherent anti-Stokes Raman Scattering (CARS); **d** infrared (IR) absorption; **e** Photothermal effect, the energy stored after IR
 19 absorption produces localized temperature increase.

20

21 This paper aims at extensively reviewing the state of the art of label-free vibrational spectroscopies for biomedical
 22 applications and their application to virtual and spectral histopathology for label-free tumor identification. Section
 23 2 discusses in detail the physics, the operating principles, the performance, and the limitations of the four
 24 vibrational microscopy techniques introduced above: SR, CRS, IR and PT-IR. Section 3 presents examples of
 25 application of vibrational microscopies to tissue imaging and cancer diagnosis by a quasi-historical approach, thus
 26 focusing on the most relevant steps in this field. Finally, Section 4 briefly compare the state of the art of the different
 27 techniques and devises some perspectives for future developments.

28

1 2. Vibrational microscopy techniques

2 2.1 Spontaneous Raman microscopy

3 SR microscopy exploits the Raman effect, i.e., an inelastic frequency shift on the scattered light relative to the
4 incident radiation originated from an exchange of energy between photons and molecular vibrations. This inelastic
5 light-matter interaction is the result of three simultaneous events: (i) the annihilation of a photon from the incident
6 field with energy $\hbar\omega_p$ upon interaction with the molecule; (ii) a vibrational transition of the interacting molecule
7 with energy $\hbar\Omega$; (iii) the spontaneous emission of a second red-shifted “Stokes” photon with energy $\hbar\omega_s$. A classical
8 description cannot fully explain the SR effect, yet it is adequate to illustrate its conceptual basis. Within the classical
9 approximation, the electric field $E = E_0\cos(\omega_p t)$ of a monochromatic plane wave of amplitude E_0 and frequency ω_p
10 drives the electron-cloud of the molecule, inducing an electric dipole μ :

$$11 \quad \mu(t) = \alpha(t)E(t) \quad (1)$$

12 where $\alpha(t)$ is the polarizability of the molecule [16] (**Eq. 1**, this and most equations reported in this sub-section
13 were adapted from [17]); the driven dipole in turn radiates a light field. The nuclear motions of the optically
14 perturbed molecule are responsible for the time-varying $\alpha(t)$, making it dependent on the molecular coordinate
15 $x(t)$. Assuming that the nuclei of the molecule vibrate near their equilibrium positions according to a harmonic
16 motion $x(t) = x_0\cos(\Omega t)$ of amplitude x_0 and frequency Ω , a Taylor expansion allows to express the polarizability
17 around its equilibrium configuration α_0 as:

$$18 \quad \alpha(t) \approx \alpha_0 + \left(\frac{\partial\alpha}{\partial x}\right)_{x=0} x(t) \quad (2)$$

19 As we assumed small nuclear displacements, we neglected high order terms in **Eq. 2**. By inserting **Eq. 2** into **Eq. 1**
20 and making use of basic trigonometry it is easy to show that the induced dipole moment contains three different
21 frequency components, namely ω_p , $\omega_p - \Omega$, and $\omega_p + \Omega$. As a consequence of the radiative nature of an oscillating
22 dipole, the first term leads to the generation of light with the same frequency of the incident radiation, i.e. ω_p ,
23 known as elastic (Rayleigh) scattering. The second term generates red-shifted light known as Stokes radiation, while
24 the third term causes blue-shifted light known as anti-Stokes radiation. Thus, relative to the monochromatic
25 excitation field, the inelastically scattered radiation either increases or reduces its frequency by an amount equal
26 to that of the vibrational mode of the interacting molecule, i.e., $\omega_p \pm \Omega$. Since the population of scatterers follows a
27 Boltzmann distribution, with lowest energy levels occupied at thermal equilibrium, the Stokes component results
28 to be much more intense than the anti-Stokes component, which is why Stokes photons are typically detected in
29 SR microscopy.

30 It is useful to express the intensity of the SR signal at the Stokes frequency in terms of a SR cross section $\sigma_{SR}(\omega_s)$,
31 which is similar to the absorption cross section in Lambert-Beer’s law:

$$32 \quad I_{SR}(\omega_s) = Nz\sigma_{SR}(\omega_s)I_0 \quad (3)$$

33 where N is the volume density of scatterers and z is the sample thickness. Due to the very small Raman-scattering
34 cross section ($\sigma_{SR}(\omega_s)$), typically around 10^{-30} cm², the number of SR photons is typically a minimal fraction of the
35 Rayleigh scattered photons or the photons emitted by fluorescence [18]. Therefore, the Rayleigh scattering and
36 fluorescence background may hamper the detection of SR scattering. The low scattering cross section also
37 drastically reduces the acquisition speed of SR relative to other imaging techniques, such as fluorescence

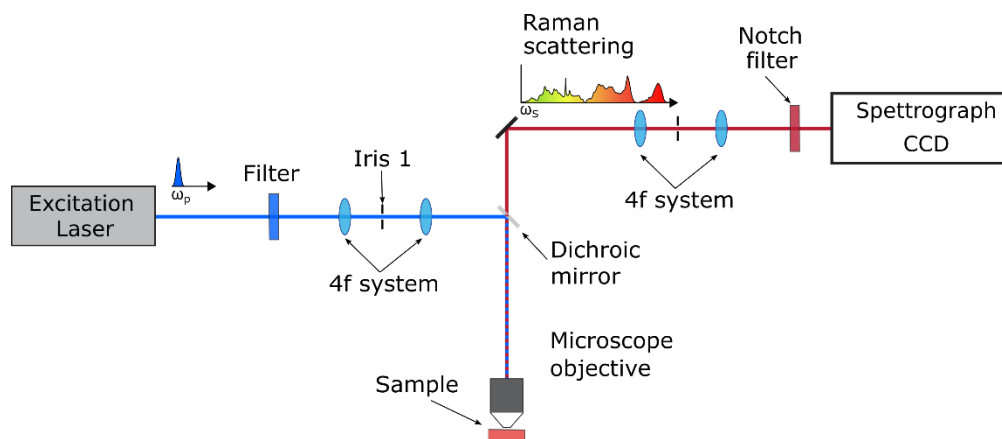
1 microscopy. Nevertheless, SR microscopy has the remarkable advantages of combining high spatial resolution
2 ($\approx 300\text{-}400\text{ nm}$) with rich spectral information and of being technically simple to be implemented.

3 Although Brillouin [19] and Smekal [20] theoretically predicted the inelastic scattering of light, it was Raman and
4 Krishnan [21] who experimentally observed such effect using as a light source a focused sunlight beam. The
5 invention of the laser in the early '60s [22] spurred an ever growing development of Raman spectroscopy. By the
6 end of that decade, the progress in Raman spectroscopy allowed the observation of the Raman effect with a
7 diffraction-limited spatial resolution, starting the field of Raman-microspectroscopy. Thus, by the mid-1970s, the
8 first reports on the development and application of Raman-microscopy emerged [23]. At the end of the very same
9 decade, this progress led to the first commercial Raman microscopes [24].

10 The conceptual scheme of a basic SR microscope in the so-called point scanning configuration is rather simple and
11 consists of four fundamental elements, as illustrated in **Fig. 3**: a relatively intense monochromatic laser beam, a
12 high numerical-aperture objective to tightly focus the beam and collect the generated SR signal, a sequence of long-
13 pass optical filters to remove the Rayleigh-scattered light, and a grating-based dispersive spectrometer (typically
14 associated to a CCD detector) to record the SR spectrum. This configuration provides an SR spectrum for each
15 raster-scanned position of the sample. This architecture has not changed significantly in the last four decades;
16 however, technological advances (see Ref. [25] for a detailed discussion) have allowed increasing the acquisition
17 speed by nearly three orders of magnitude. The monochromatic excitation beam is generated by a continuous wave
18 laser of a few tens of mW power, usually in the visible and near infrared range (e.g. 532, 633, 785, 1063 nm),
19 depending on the application and on the setup configuration. For most studies on tissue samples, near-infrared
20 wavelengths (e.g., 785 nm) are preferred as they reduce auto-fluorescence of the sample.

21 A high numerical aperture (NA) microscope objective is used to illuminate the sample and to collect the backward
22 scattered SR light (epi detection), which is then directed to the spectrometer. Epi detection is preferred because it
23 is simpler, requiring only one microscope objective, and because the spatially incoherent SR light is radiated
24 isotropically in all directions, including the backscattered light which is easily collected by the same objective. The
25 geometry of point-scanning microscopes is well suited for confocal SR microscopy [26,27], in which an iris,
26 conjugated with the object plane and with the entrance slit of the spectrometer, reduces fluorescence background.
27 Thus, with synchronized readings of spatial coordinates and spectra, point-scanning microscopes generate a Raman
28 spectrum per point of the image with diffraction-limited spatial resolution and spectral-resolution down to 1 cm^{-1} .
29 This rich dataset, containing one spectrum per image pixel, is known as hyperspectral data cube or hypercube. The
30 point-scanning architecture is the conventional one used for SR microscopes, as shown in **Fig. 4a**. Alternative SR
31 modalities are line scanning and wide-field-excitation (see **Fig. 4b,c**).

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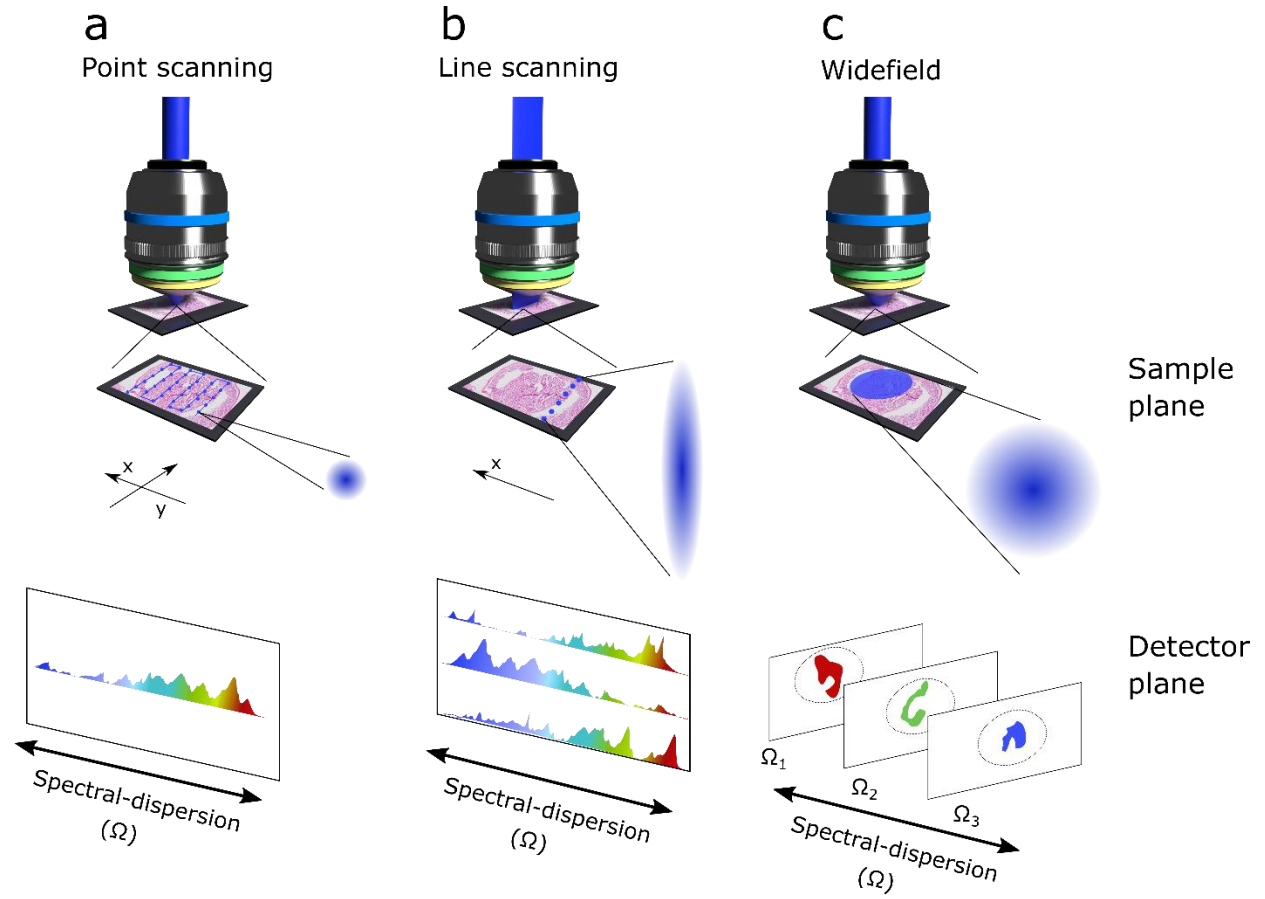
2 **Fig. 3** Schematic lay-out of a SR microscope. Adapted with permission from [28]. CCD: charge coupled device.

3 *Line-scanning* microscopes focus a line of light onto the specimen and acquire the SR signal simultaneously from all
 4 illuminated points. There are two common approaches to generate a line profile at the focal plane. The first one
 5 employs a galvanometric scanner that quickly moves a tightly focused beam over a line on the sample plane, with
 6 a scanning rate higher than the sampling rate of the detector. The second approach attains the line illumination by
 7 focusing with a cylindrical lens. In both approaches, collection optics images the line-shaped SR signal onto the slit
 8 of a dispersive spectrometer in such a way that a matrix-detector, typically a CCD, may register the Raman-
 9 spectrum along one direction (e.g. rows) and the spatial location along the other direction (e.g. columns). This
 10 allows a parallel measurement of the SR spectra of all points of the illuminated line before moving the excitation
 11 to a second line (push-broom imaging). To this end, either a single-axis galvanometer scanner moves the excitation
 12 line, or a mechanical stage displaces the specimen. In both cases the scanning is uniaxial. In the geometry shown in
 13 **Fig. 4b** the scanning takes place along the x -axis. As compared to a point-scanning configuration, line-scanning
 14 increases the acquisition speed of the Raman hypercube. In particular, if a point-scanning microscope performs
 15 $N \times N$ measurements to retrieve the Raman hypercube, its line-scanning counterpart requires only N measurements.
 16 However, due to the line profile of the excitation and of the scattered light, line-scanning microscopes are not
 17 entirely confocal, hampering the rejection of fluorescence and out-of-focus contributions. The implementation of
 18 line-scanning Raman microscope dates back to the 1970s, but it was not until the recent development of two-
 19 dimensional CCDs that applications with substantial impact on the biomedical sciences were shown [29]. Stone and
 20 collaborators, and Renishaw Plc. (UK), reported a similar line-mapping approach based on the use of an expanded
 21 line-focused laser coupled with a CCD readout synchronized with the movement of the stage [30]. Fujita and
 22 colleagues [31,32] have also demonstrated the potential of the line-scanning architecture by employing it to
 23 observe molecular dynamics in living cells.

24 *Wide-field-excitation* SR microscopes, shown in **Fig. 4c**, distribute the excitation light homogeneously over the
 25 sample plane, while a CCD camera records the SR signal at a specific vibrational frequency. Early reports on the
 26 applications of this architecture selected the imaged Raman bands using narrow-band tunable lasers coupled with
 27 narrow-band fixed filters, rotating filters, or dispersive gratings [28,33]. The introduction of liquid-crystal tunable
 28 filters [34] and acousto-optical tunable filters [35] invigorated the development of wide-field-excitation SR
 29 microscopy, as these technologies allow automatized imaging at Raman-bands of interest with enhanced spectral
 30 resolution. Schlucker et al. [36] systematically compared wide-field Raman-microscopy with point-scanning and
 31 line-scanning regimes. The researchers noted that, despite the necessity to collect several images at different

1 vibrational frequencies to assemble an entire Raman-hypercube, wide-field SR microscopy, at a specific Raman
 2 band, outperforms single-point and line-scanning architectures in terms of speed and image quality. To date,
 3 widefield-excitation for SR microscopy has found limited applications in biosciences, succeeding only in imaging
 4 tissues containing calcified material, which produces strong Raman signals [37,38].
 5 Despite their appealing characteristics, modern SR microscopes still suffer from one main pitfall: due to the low
 6 Raman cross-sections and the lack of coherence among the individual dipole moments that originate the scattered
 7 photons, they are still slow for tissue imaging.

8



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10

11 **Fig. 4** Architectures for Raman-microscopy. **a** point-scanning, **b** line-scanning, and **c** wide-field excitation. The second row
 12 shows a magnified view of the sample-plane and the irradiance on the sample. The third row depicts the spectral
 13 information obtained from each architecture.

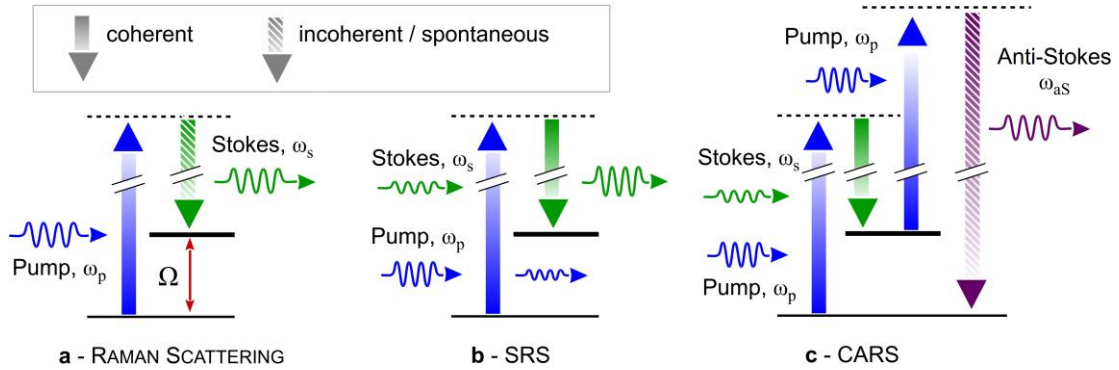
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1 **2.2 Coherent Raman microscopy**

2 **2.2.1 Fundamental principles**

3 CRS is a class of third-order nonlinear optical processes which generates the Raman signal from a coherent
 4 superposition of oscillating molecular dipoles in the sample, illuminated by two synchronized ultrashort laser
 5 pulses of different frequencies, the pump (at frequency ω_p) and the Stokes (at frequency ω_s). When the
 6 difference between pump and Stokes frequencies matches a vibrational frequency Ω , i.e. $\omega_p - \omega_s = \Omega$, then all
 7 the molecules in the focal volume are resonantly excited and vibrate in phase. This vibrational coherence is the
 8 key aspect, which differentiates CRS from the incoherent SR process, as it enhances the Raman response by many
 9 orders of magnitude, decreasing the acquisition times from seconds down to microseconds per pixel. The two
 10 most widely employed CRS techniques are CARS [39] and SRS [40,41] (**Fig.5**). In SRS (**Fig. 5b**) the coherent
 11 interaction with the sample induces stimulated emission from a virtual state of the sample to the investigated
 12 vibrational state, resulting in a Stokes-field amplification (Stimulated Raman Gain, SRG) and in a simultaneous
 13 pump-field attenuation (Stimulated Raman Loss, SRL). In CARS (**Fig. 5c**) the vibrational coherence is read out by
 14 a further interaction with the pump beam, generating a coherent radiation at the anti-Stokes frequency $\omega_{aS} = \omega_p$
 15 $+ \Omega$, which is detected by spectrally filtering it from the co-propagating pump and Stokes beam.

16



17

18 **Fig. 5** sketch of the transitions involved in coherent CRS based approaches, compared with those involved in
 19 spontaneous Raman scattering. Dashed lines represent virtual levels involved in the transitions. **a** Spontaneous Raman
 20 scattering; **b** Stimulated Raman Scattering (SRS); **c** Coherent anti-Stokes Raman Scattering (CARS).

21

22 CARS and SRS are four-wave-mixing (FWM) processes, of the type $\omega_1 + \omega_3 = \omega_2 + \omega_4$, mediated by the third-order
 23 nonlinear optical response of the sample, which can be generally written as:

24
$$\chi^{(3)}(\omega) = \chi_{NR}^{(3)} + \chi_R^{(3)}(\omega) \quad (4)$$

25 where $\omega = \omega_p - \omega_s$ (this and most of equations reported in this sub-section were adapted from [17,42]). The term
 26 $\chi_{NR}^{(3)}$, also known as non-resonant background (NRB), describes the non-resonant electronic interactions of the
 27 pump and Stokes fields with the molecules under study and with the surrounding environment, and is typically
 28 assumed to be real and frequency independent. The resonant term $\chi_R^{(3)}(\omega)$ is the complex vibrational
 29 susceptibility, which contains the chemical information on the sample, and can be written as a sum of Lorentzian
 30 responses:

$$\chi_R^{(3)}(\omega) = \sum_i \frac{A_i}{\Omega_i - \omega - i\Gamma_i} \quad (5)$$

where for the i^{th} vibrational resonance, the amplitude $A_i \propto \sigma_i N_i$ is proportional to the cross section (σ_i) and to the volume concentration of molecular bonds (N_i), Ω_i is the vibrational frequency, and Γ_i the corresponding linewidth.

In a generic FWM process, the third-order polarization at frequency $\omega_4 = \omega_1 + \omega_3 - \omega_2$ can be expressed as:

$$P^{(3)}(\omega_4) \propto \chi^{(3)}(\omega_1, \omega_2, \omega_3, \omega_4) E_1(\omega_1) E_2^*(\omega_2) E_3(\omega_3) \quad (6)$$

and the equation describing the evolution of the light field at ω_4 along the propagation direction z can be written as:

$$\frac{\partial E_4}{\partial z} = -i \frac{3\omega_4}{4cn_4} P^{(3)}(\omega_4) e^{i\Delta k z} \quad (7)$$

where c is the speed of light, n_4 the refractive index of the medium at frequency ω_4 and $\Delta k = k_4 + k_2 - k_1 - k_3$ is the so-called wave vector mismatch.

In the CARS process one has $\omega_1 = \omega_3 = \omega_p$, $\omega_2 = \omega_s$, $\omega_4 = 2\omega_p - \omega_s = \omega_{as}$. In a tight focusing configuration characteristic of microscopy, leading to a short interaction length $L \sim 1 \mu\text{m}$, one can neglect the phase mismatch between the interacting fields ($\Delta k L \approx 0$) and write the anti-Stokes field as:

$$E_{as}(\omega_{as}) \propto -i \chi^{(3)}(\omega_p - \omega_s) E_p^2(\omega_p) E_s^*(\omega_s) L \quad (8)$$

Since the anti-Stokes field is at a different frequency with respect to pump and Stokes, its intensity can be directly measured following spectral filtering and is:

$$I_{CARS}(\omega_{as}) \propto \left| \chi^{(3)}(\omega_p - \omega_s) \right|^2 I_p^2(\omega_p) I_s(\omega_s) L^2 = \left[\left| \chi_R^{(3)}(\omega_p - \omega_s) \right|^2 + \chi_{NR}^{(3)2} + 2\chi_{NR}^{(3)} \text{Re} \left[\chi_R^{(3)}(\omega_p - \omega_s) \right] \right] I_p^2(\omega_p) I_s(\omega_s) L^2 \quad (9)$$

Equation 9 shows both the advantages and the drawbacks of CARS. On the one hand, CARS has the important advantage of being a background-free process, as its signal is measured against a zero linear background, thus making its detection very easy. On the other hand, the NRB significantly affects the CARS spectrum, by introducing both a frequency independent term ($\chi_{NR}^{(3)2}$) and a dispersive interference term $2\chi_{NR}^{(3)} \text{Re} \left[\chi_R^{(3)}(\omega_p - \omega_s) \right]$ that distorts the typical Lorentzian peaked lineshapes of SR spectra.

One can consider two limiting cases. If $\chi_{NR}^{(3)} \ll \chi_R^{(3)}$ Eq. 9 can be simplified in the following form:

$$I_{CARS}(\omega_{as}) \propto \left| \chi_R^{(3)}(\omega_p - \omega_s) \right|^2 I_p^2(\omega_p) I_s(\omega_s) L^2 \quad (10)$$

In this regime, the CARS spectrum is dominated by the resonant term and presents the expected peaked lineshapes. However, the CARS signal scales as N^2 , where N is the number of vibrational oscillators in the focal volume, so that its sensitivity rapidly drops with decreasing oscillator concentration, making it difficult to quantify molecular concentrations and to detect the less abundant bonds such as those that occur in the fingerprint region. If, on the other hand, $\chi_{NR}^{(3)} \gg \chi_R^{(3)}$ one can approximate the CARS signal as follows:

$$I_{CARS}(\omega_{aS}) \propto \left[\chi_{NR}^{(3)2} + 2\chi_{NR}^{(3)} \text{Re} \left[\chi_R^{(3)}(\omega_p - \omega_S) \right] \right] I_p^2(\omega_p) I_S(\omega_S) L^2 \quad (11)$$

In this case, despite the presence of a large background and of a severe lineshape distortion, the CARS signal scales linearly with N , making this regime more favorable for the detection of the weak signals in the fingerprint region. In this regime the NRB can act as a local oscillator (LO), intrinsically phase coherent with the resonant vibrational signal of interest and allowing its amplification through the product of $\chi_R^{(3)}$ by $\chi_{NR}^{(3)}$. In this regime, however, in order to distinguish the resonant signal from the NRB, it is necessary to detect the complete CARS spectrum (see **Section 2.2.3**) and not just the response at a single frequency.

For the case of SRS, one can write (considering SRG detection) $\omega_1 = \omega_2 = \omega_p$, $\omega_3 = \omega_S$, so that $\omega_4 = \omega_S$ and the phase matching condition $\Delta k = 0$ is automatically satisfied. The nonlinear signal then becomes:

$$\Delta E_S(\omega_S) = -i \frac{3\omega_S}{4cn_S} \chi^{(3)}(\omega_p - \omega_S) |E_p(\omega_p)|^2 E_S(\omega_S) L \quad (12)$$

and is emitted at the same frequency and with the same propagation direction as the Stokes field, so that the detector measures the overall Stokes intensity:

$$I_S(\omega_S) = |E_S(\omega_S) + \Delta E_S(\omega_S)|^2 \cong |E_S(\omega_S)|^2 + 2E_S(\omega_S) \text{Re}[\Delta E_S(\omega_S)] \quad (13)$$

where we have assumed $\Delta E_S \ll E_S$. In this way, the nonlinear signal ΔE_S is superimposed to the Stokes field E_S , which allows its amplification (self-heterodyne detection).

The SRG signal, i.e. the differential Stokes intensity in the presence and absence of pump, thus becomes:

$$SRG = \Delta I_S(\omega_S) = 2E_S(\omega_S) \text{Re}[\Delta E_S(\omega_S)] \propto \text{Im} \left[\chi_R^{(3)}(\omega_p - \omega_S) \right] I_p I_S L \quad (14)$$

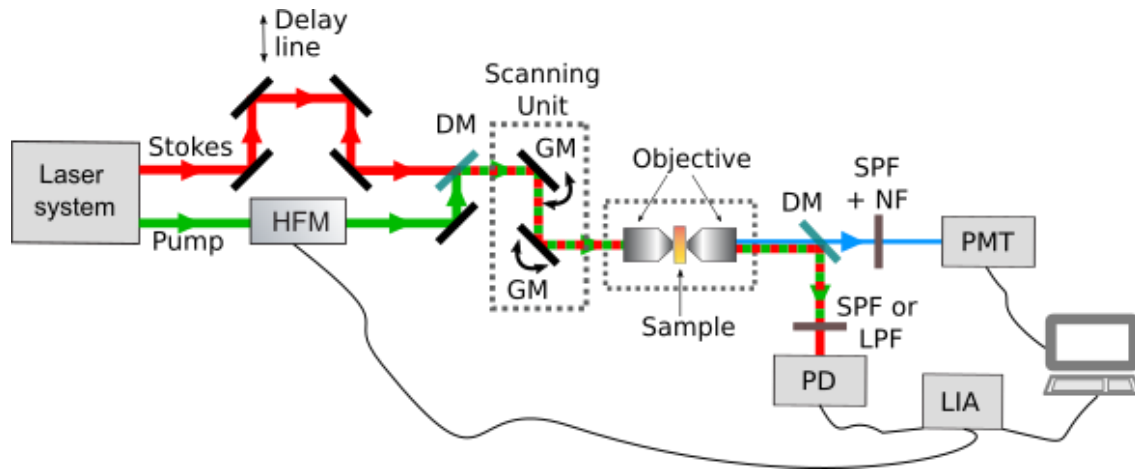
The SRS signal is thus proportional to the imaginary part of the third-order susceptibility tensor $\chi^{(3)}$. Since the NRB is a real quantity, SRS is inherently free from NRB. Furthermore, thanks to the heterodyne amplification, SRS scales linearly with N , thus allowing the detection of low-concentration species and signals in the fingerprint region. On the other hand, SRS requires the detection of a weak differential SRG(SRL) signal sitting on the large linear background given by the Stokes(pump) light. Extraction of this signal (which can be as small as 10^{-4} - 10^{-5}) calls for the use of sophisticated techniques, involving high-speed modulation and lock-in detection, to overcome the laser fluctuations and achieve shot-noise limited detection. Such techniques are challenging to be implemented at high speeds, with integration times of few tens of microseconds, and over a broad spectrum, required to extract the entire Raman fingerprint of the molecules. It is worth noting that, since $\text{Im}[\chi^{(3)}]$ is proportional to σ_{SR} , SRS spectra faithfully replicate SR spectra, allowing the Raman database to be used to interpret SRS measurements.

Taken together, CARS and SRS each present advantages and drawbacks, which make one or the other technique preferable according to the configuration and the sample to be studied. In the following sub-sections, we will discuss experimental implementations of CARS and SRS relevant to histopathology, both in the narrowband and in the broadband configurations.

2.2.2 Narrowband CARS/SRS microscopy

1 Narrowband (single-frequency) CARS/SRS is the simplest and most widely employed CRS configuration, and for
2 this reason its experimental layout is rather well established. **Figure 6** reports the typical experimental setup of
3 a narrowband CARS/SRS microscope. The two imaging modalities share many common elements, such as the
4 laser source and the microscope architecture, and differ essentially in the detection chain. Narrowband pump
5 and Stokes pulses, generated by a suitable laser source, are synchronized by an optical delay line, collinearly
6 combined by a dichroic mirror and sent to a scanning unit, consisting of two galvanometric mirrors, and to a first
7 microscope objective, which focuses them on the sample. So-called scan and tube lenses are in general placed
8 between the galvanometric mirrors and the objective in order to conjugate the mirrors with the back aperture
9 of the objective in a standard 4-f configuration. In the transmission configuration, the light transmitted by the
10 sample is collected by a second microscope objective. In the case of CARS, the anti-Stokes light is spectrally
11 selected by a sequence of short-pass filters and detected by a photomultiplier. In the case of SRS, a high-
12 frequency modulator (either electro- or acousto-optic) is inserted in the pump (Stokes) beam path and the
13 transmitted Stokes(pump) beam, spectrally selected by a series of long-pass(short-pass) filters, is sent to a
14 photodiode followed by a lock-in amplifier (LIA), which synchronously demodulates it and measures the SRG
15 (SRL) signal. Typically, modulation frequencies of the order of 1-40 MHz are used in SRS, which allow working in
16 a region of low relative intensity noise of the laser source, approaching shot-noise-limited detection. For CARS,
17 also the so-called "epi" configuration can be used (not shown in **Fig. 6**), in which the back-scattered light is
18 collected by the focusing objective and then sent to the detection chain via a dichroic beam splitter. While epi
19 CARS is commonly used for thick tissues[43] epi SRS, although possible, is more challenging to implement [44].
20 Single-frequency CARS/SRS microscopy require the same laser source, capable of generating synchronized
21 narrowband pump/Stokes pulses, with the following specifications: i) 3-5 ps transform-limited pulse duration,
22 corresponding to $<10\text{ cm}^{-1}$ bandwidth, in order to guarantee the required spectral resolution and at the same a
23 maximized peak power to enhance the nonlinear optical effects; ii) high repetition rate of the order of 40-80
24 MHz, to enable high-speed imaging; iii) at least 100 mW average output power per beam, to allow illuminating
25 the sample with 10-20 mW power level after considering the various optical losses, which is a typical threshold
26 before reaching optical damage in tissues/cells; iv) emission in the near-infrared range (700-1200 nm) to combine
27 high transmission within cells and tissues with reduced multi-photon absorption cross sections; v) fast and
28 automatic tunability of at least one of the pulses, in order to access different vibrational frequencies of interest.
29 Such characteristics are not easy to obtain and a number of laser systems for CRS microscopy have been
30 proposed. Initial configurations relied on electronically synchronized picosecond Ti:sapphire lasers [45] which,
31 due to their complexity, have been rapidly superseded by optical parametric oscillators pumped by picosecond
32 mode-locked neodymium optical parametric oscillators (OPOs), which are the current gold standard for CRS
33 microscopy [46]. These configurations are however bulky, complex and expensive and not suitable for
34 deployment outside research laboratories and in a clinical environment. For this reason, several architectures of
35 fiber-format lasers sources have been proposed. Fiber lasers are compact, alignment free and potentially low
36 cost. One architecture relies on a femtosecond Er: fiber oscillator followed by two Er:doped fiber amplifier
37 branches, from which narrowband tunable pump and Stokes pulses are generated by nonlinear frequency
38 conversion [47,48]. Another approach relies on the combination of a picosecond Yb: fiber oscillator with a fiber-
39 based OPO exploiting third-order nonlinearities [49].
40 Overall, narrowband CRS microscopy is a rather mature technology and has reached very high acquisition speed,
41 with pixel dwell times below $1\ \mu\text{s}$ for both CARS and SRS implementations [50,51], allowing video rate acquisition

1 of images. However, for many applications the amount of delivered information is not sufficient and broadband
2 approaches, described in the following paragraphs, are required.



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5
6 **Fig. 6** CARS/SRS microscope setup. HFM, high-frequency modulator; DM, dichroic mirror; GM, galvanometric mirror; LPF, long-pass filter; SPF, short-pass filter; NF, notch filter; PD, photodiode; PMT, photomultiplier tube; LIA, lock-in amplifier.
7
8 Adapted with permission from [52].

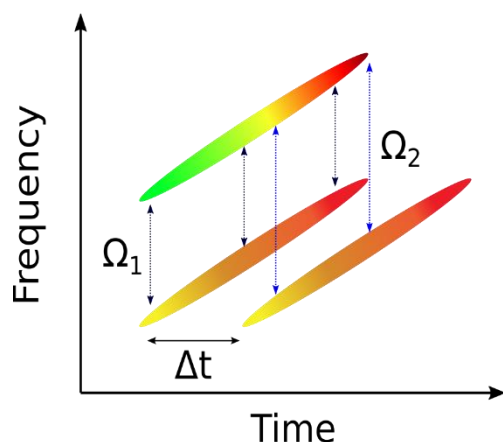
9 2.2.3 Broadband CARS microscopy

11 Broadband CARS approaches can be generally classified as hyperspectral or multiplex. In hyperspectral CARS, the
12 signal at a single Raman frequency is recorded at a given time and the pump-Stokes detuning is swept to record
13 the CARS spectrum sequentially. In multiplex CARS the Stokes pulse is broadband, and the CARS spectrum is
14 measured in parallel using a multichannel detector.

15 One approach to hyperspectral CARS uses the single-frequency CARS apparatus discussed above, employing two
16 narrowband ($\leq 10 \text{ cm}^{-1}$) picosecond pulses, and rapidly tunes the wavelength of one of the pulses to scan the
17 Raman frequency. In another approach, known as spectral focusing (see **Fig. 7**), both pump and Stokes pulses
18 are broadband, with spectra covering several hundreds of wavenumbers and transform-limited durations of $<$
19 100 fs . Before the nonlinear interaction, pump and Stokes pulses are chirped with the same frequency vs. time
20 dependence up to picosecond duration, so that their instantaneous frequency difference (IFD) is kept constant
21 and matches a single vibrational frequency (indicated as Ω_1 in **Fig. 7**). By finely adjusting the relative arrival time
22 of the pulses (indicated as Δt in **Fig. 7**), it is then possible to tune the IFD and thus the Raman detuning (see the
23 new frequency Ω_2 in **Fig. 7**) without the need for tuning the pulse spectrum. Note that the maximum tuning range
24 for the Raman frequency is limited by the pulse bandwidth.

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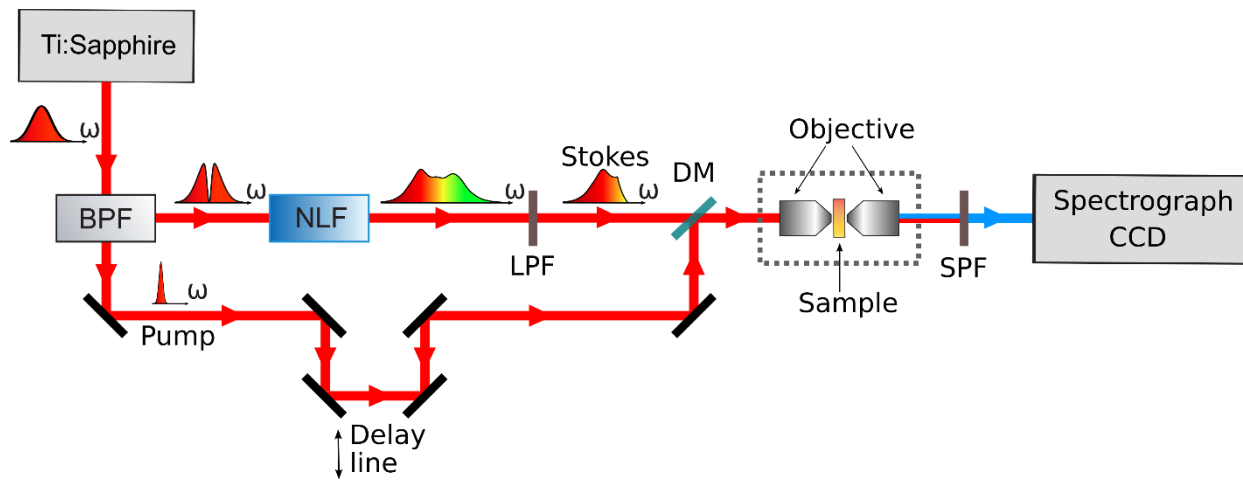


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3 **Fig. 7** Concept of spectral-focusing CARS/SRS, showing the time-dependent frequencies of pump and Stokes pulses and the
4 frequency tuning performed by varying the relative arrival time Δt .

5 Special care must be taken to impart the same chirp onto the two laser pulses [53], to avoid spoiling the
6 spectral resolution. This can be a difficult task: as the two pulses are tuned to different wavelengths, the same
7 optical system employed to chirp the pulses (typically a double-pass grating or prism pair, a prism/lens or
8 grating/lens combination or a long block of highly dispersing glass) could result in different second-order or third-
9 order dispersion contributions. To this aim, a rather complex and expensive but also very powerful solution is
10 the use of a pulse shaper, in which a spatial light modulator is placed in the Fourier plane of a grating [53,54].
11 Several approaches have been proposed to rapidly scan the pump-Stokes delay and thus vary the IFD, including
12 galvanometric mirrors and acousto-optic programmable dispersive filters; these methods are described more in
13 detail in the following paragraph dealing with broadband SRS.

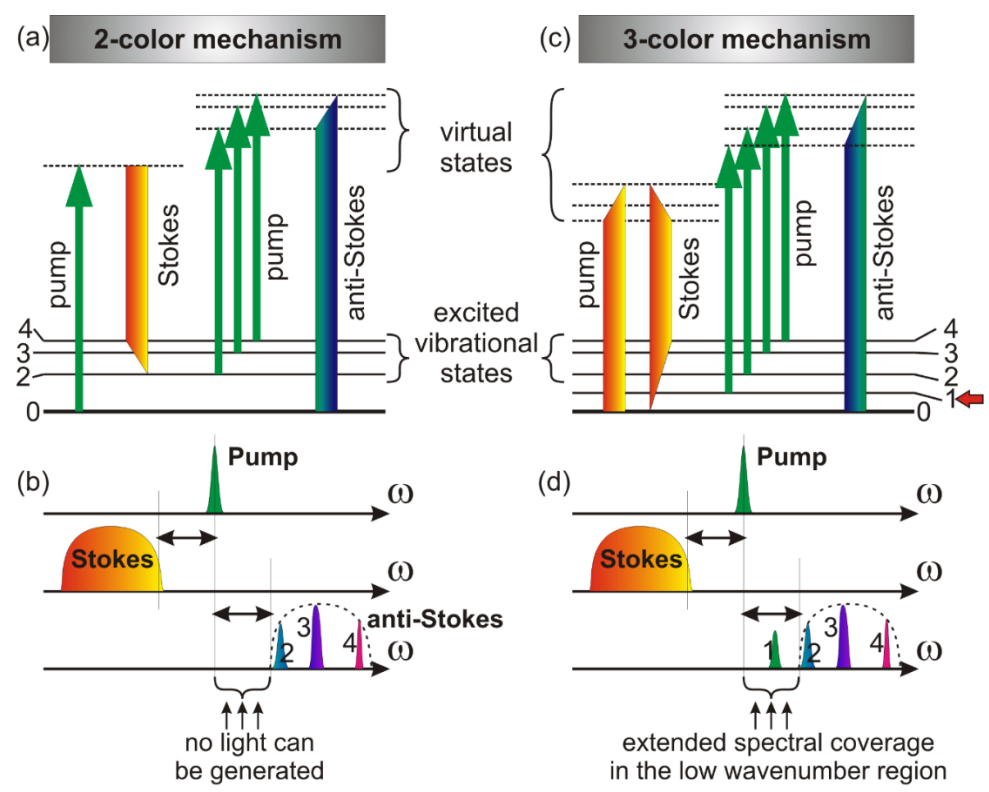
14 In multiplex CARS [55–60], on the other hand, only the Stokes pulse is broadband, while the pump pulse is kept
15 narrowband ($\leq 10 \text{ cm}^{-1}$, corresponding to $\geq 1 \text{ ps}$ duration). In this configuration, schematized in Fig. **Fig. 8**, a band-
16 pass filter (BPF) selects a narrow ($\approx 10 \text{ cm}^{-1}$ bandwidth) spectral component of the output of a femtosecond
17 Ti:Sapphire laser oscillator, serving as the pump for the CARS process. The remainder of the laser output is then
18 sent to a nonlinear fiber (NLF, either a tapered or a photonic crystal one) for spectral broadening. A long-wave-
19 pass filter (LPF) selects the red-shifted portion of the spectrum, to be used as broadband Stokes pulses for the
20 CARS process. A delay line synchronized the two pulses, and a dichroic mirror (DM) combines them in a collinear
21 geometry before entering the microscope stage. After the sample, the generated anti-Stokes beam is then
22 selected using a short-wave-pass filter (SPF) and its spectrum detected using a spectrograph equipped with a
23 multi-channel detector (typically a CCD camera). In this way, the entire CARS spectrum is recorded in parallel
24 over both the fingerprint and the C-H stretching region.



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Fig. 8: Broadband CARS: Schematic setup of a Ti:sapphire-based broadband CARS microscope. BPF, reflective bandpass filter; NLF, nonlinear fiber; LPF, long-pass filter (wavelength); DM, dichroic mirror; SPF, short-pass filter (wavelength).

To enhance the weak signal generated in the fingerprint region due to the low cross section of the Raman signal, Cicerone *et al.* [61,62] employed ultrashort (16-fs) pulses on the sample to take advantage of the interplay of the so-called “2-colour” and “3-colour” CARS schemes, as illustrated in **Fig. 9**. The “2-colour scheme” corresponds to two interactions with the narrowband pump pulse and one interaction with the broadband Stokes pulse. The achievable Raman frequencies correspond to the differences between the narrowband pump frequency and the frequencies contained in the broadband Stokes pulse spectrum.



13

1

2 **Fig. 9 (a-b)** 2-colour and **(c-d)** 3-colour generation mechanisms. Note that only the 3-colour mechanism can access the
3 low-frequency vibrational mode numbered “1” (red arrow).

4 In the “three-color” (also called “intra-pulse”) approach (see **Fig. 9 (c-d)**), two interactions with the broadband
5 pulse impulsively promote molecules to vibrationally excited states, by the so-called impulsive stimulated Raman
6 scattering mechanism [63]. The excitation profile is thus determined by the permutations of all available pump
7 frequencies: for adjacent frequencies, the possible permutations are higher in number, so that the three-color
8 mechanism is more effective for lower vibrational frequencies. This makes it perfectly suited for stimulating
9 Raman transitions within the vibrational fingerprint region. This is also illustrated in **Fig. 9** : the vibrational mode
10 number “1” is efficiently excited (panel (c)) and appears in the CARS signal (panel (d)).

11

12 In both hyperspectral and multiplex CARS approaches, the resonant vibrational signal is mixed with the NRB,
13 which distorts the lineshapes with respect to those measured in SR. This problem is particularly severe in the
14 fingerprint region, where the resonant Raman features are weaker than in the C-H stretching region. For
15 hyperspectral CARS based on spectral focusing, the NRB can be removed using a frequency-modulation approach
16 [64]. In this implementation, a double pass into a Pockels cell, modulated at high frequency, generates two pump
17 pulses with different arrival times on the sample, thus effectively modulating the pump-Stokes IFD in and out of
18 the vibrational resonance. A LIA demodulates the signal and extracts SR-like spectra with largely reduced NRB
19 contributions. On the other hand, NRB can be beneficial in multiplex CARS, acting as an inherently phase-locked
20 local oscillator (LO) for heterodyne amplification of the nonlinear CARS signal (see **Eqs. 9 and 11**) to retrieve the
21 absorptive imaginary part of the nonlinear susceptibility. At the same time, the measurement of the entire CARS
22 spectrum unlocks the possibility to use analytical techniques, such as the Maximum Entropy Method [65] and
23 the time-domain Kramers–Kronig transform [62,66] or artificial-intelligence-based methods [67,68], to retrieve
24 the absorptive imaginary part of the nonlinear susceptibility.

25 Other approaches to broadband CARS, different from the aforementioned hyperspectral and multiplex ones,
26 have been demonstrated, such as time-resolved CARS and Fourier-Transform (FT) CARS, but they have not yet
27 been extensively employed for biological tissue analysis and tumor identification. Briefly, time-resolved CARS
28 [69–71] generates a vibrational coherence in the sample by exciting the Raman modes with two interactions with
29 the pump and Stokes fields, which could be either taken from two independent pulses or from the same
30 broadband pulse with ultrashort ($\approx 10\text{-}20$ fs) duration, via the aforementioned ISRS mechanism. Such coherence
31 lasts for a few picoseconds, as determined by the vibrational dephasing time T_{2v} of the molecules. A delayed
32 probe pulse reads out such coherence, thus generating the anti-Stokes signal. The advantage of this technique is
33 the removal of the NRB, which is a purely electronic process requiring temporal overlap between the
34 pump/Stokes and the probe pulses. The drawback is the rather weak extracted signal, as the vibrational
35 coherence decays in time as $\exp(-2t/T_{2v})$, where t is the delay of the probe with respect to the pump/Stokes
36 pulses. FT-CARS [72–74], on the other hand, is a time-domain technique employing two ultrashort ($\approx 10\text{-}20$ fs
37 duration) pulses with variable relative delay on the sample. The first (pump) pulse excites, via ISRS, those
38 molecular vibrations in the focal spot whose oscillation period is (at least slightly) longer than the pulse duration,
39 thus making the technique suitable mainly for the fingerprint Raman spectral region and not for the high-
40 frequency Raman modes in the CH-stretching region. The second (probe) pulse is then modulated by the time-
41 dependent refractive index generated by the ISRS process. Fourier transform of this temporal trace provides the

1 spectrum of the excited Raman modes. As NRB is a purely electronic process, not involving any interaction with
2 the sample vibrational levels, FT-CARS has the advantage of removing it by excluding the signals around zero-
3 time delay. However, it also has the drawback of requiring short pulses at the sample, which are difficult to
4 handle and can induce damage to cells and tissues.

5

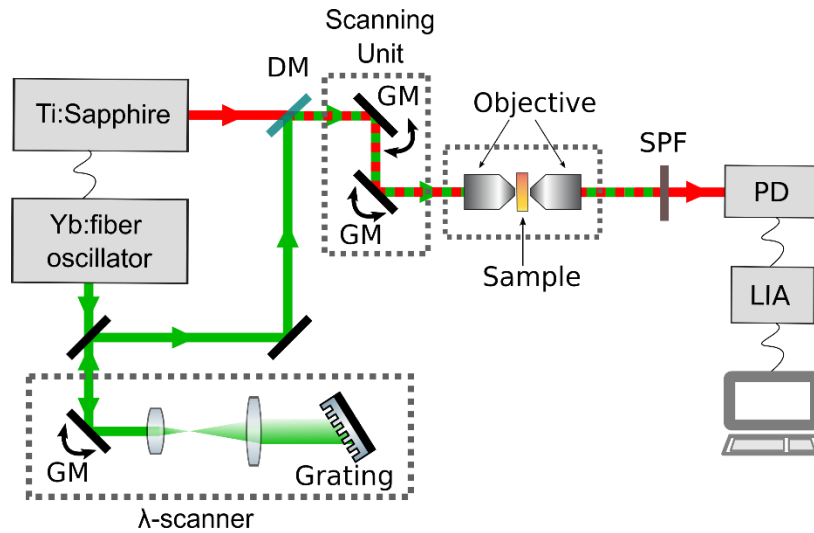
6 **2.2.4 Broadband SRS microscopy**

7 Broadband SRS microscopy is an emerging technology that is undergoing a rapid development. As for broadband
8 CARS, it can be classified in two main categories: hyperspectral and multiplex. In hyperspectral SRS microscopy
9 the frequency detuning between pump and Stokes beams is sequentially scanned, resulting in a single Raman
10 vibrational frequency measured at a time. The large tunability of OPOs [75,76] is particularly suited to the
11 purpose, as well as their favourable noise properties that allow the speed of single-frequency SRS imaging to be
12 pushed up to the video rate [44]. On the other hand, the relatively low tuning speed of OPOs results in a time-
13 consuming approach when broad bands have to be scanned. In this area, excellent results were obtained by
14 Schweikhard and colleagues using a Leica SP8 CARS laser scanning microscope with SRS option (Leica
15 Microsystems, Mannheim, Germany) [77]. This has been the first fully integrated SRS commercial microscope. A
16 PicoEmerald S OPO (APE, Berlin, Germany) provides both the pump beam fixed at 1030 nm and a Stokes beam
17 tunable from 720 to 980 nm. This system allows exciting vibrational frequencies in the spectral range from 4200
18 to 500 cm^{-1} with a spectral resolution of $\sim 12 \text{ cm}^{-1}$. An electro-optic modulator(EOM) modulates the Stokes beam
19 and the SRS signal is acquired in the forward direction through a single photodiode and a LIA.

20

21 The state of the art of hyperspectral SRS microscopy in terms of imaging speed was achieved by Ozeki et al. [78].
22 The experimental setup, presented in **Fig. 10**, employs a narrowband picosecond Ti:sapphire laser at 76 MHz
23 repetition rate as a pump and an electronically synchronized broadly tunable Yb:fiber oscillator with a factor of
24 two lower repetition rate (38 MHz) as a Stokes. This enables lock-in detection of the SRS signal at the maximum
25 frequency with no need for external modulation [79]. High-speed tuning of the Stokes pulse is achieved by a
26 high-resolution tunable bandpass filter, which selects a single wavelength within the 30-nm bandwidth of the
27 Yb:fiber laser by angle tuning of a galvanometric mirror with a millisecond response time [80]. This setup allowed
28 acquiring up to 90 spectral images consisting of 480 x 500 pixels in 3 seconds, over a wavenumber range of 300
29 cm^{-1} with a spectral resolution of $\sim 3 \text{ cm}^{-1}$. In another implementation, Kong et al. [81] performed hyperspectral
30 SRS imaging using a custom-made electronically controlled Lyot filter to quickly command an OPO and tune the
31 output wavelength in a line-by-line mode.

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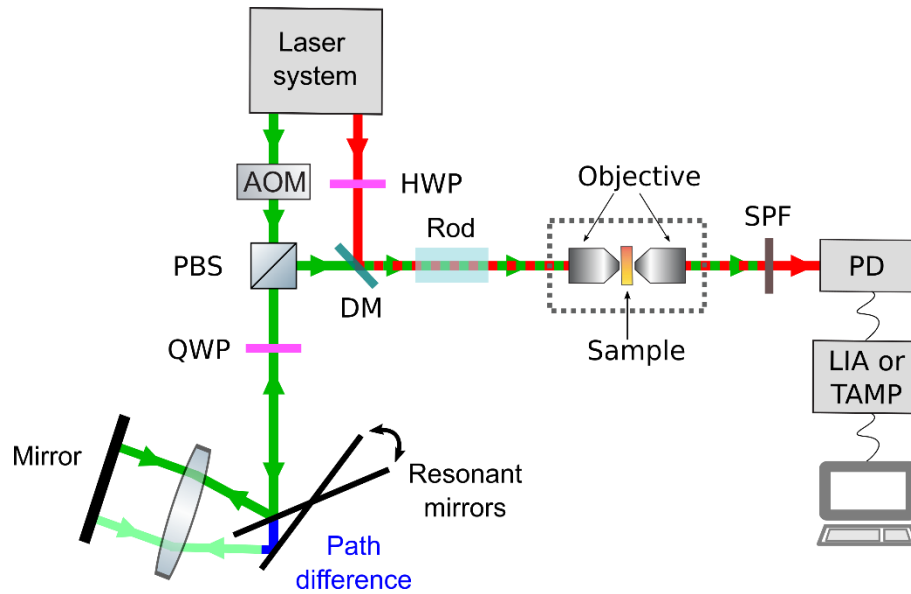


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3 **Fig. 10** Scheme of a fast hyperspectral SRS microscope used by Ozeki and colleagues. DM, dichroic mirror; GM,
4 galvanometric mirror; SPF, short-pass filter (wavelength); PD, photodiode; LIA, lock-in amplifier. Adapted from [78].

5 A different approach to hyperspectral SRS microscopy is based on the previously described spectral focusing
6 concept [75,76], which exploits broadband frequency-chirped pump/Stokes pulses whose time delay is varied to
7 sweep their IFD (see **Fig. 7**). In earlier implementations the detuning was obtained by a motorized translation
8 stage in a frame-by-frame approach that resulted to be detrimental for the overall acquisition speed of the
9 microscope [82]. Recently, taking inspiration from optical coherence tomography (OCT), significant progress in
10 terms of tuning speed has been achieved [83]. As depicted in the sketch of **Fig. 11**, Liao et al. [84] sent the Stokes
11 beam to the edge of a 12-kHz resonant scanning mirror. The light is then focused with a lens on a flat mirror, so
12 that the retro-reflected light experiences a millimeter-scale optical path difference during the scan. The beam
13 crosses twice a quarter-wave plate (QWP), so that after the resonant delay line a polarizing beam splitter (PBS)
14 redirects the beam to the microscope setup. In this way, the authors acquired SRS spectra over a range of ~ 200
15 cm^{-1} with a pixel dwell time of $83 \mu\text{s}$ and 25-cm^{-1} spectral resolution.

16 Another variation of this approach was proposed by He et al. [85]. In this case, the system is based on a rapid
17 scanning optical delay line, already used in OCT, composed of a grating, a lens and a galvanometric mirror in a 4-
18 f configuration. Figueroa and colleagues [86] developed a system based on parabolic fiber amplifier that could
19 cover more than 600cm^{-1} spectral bandwidth at a resolution of $\sim 10 \text{cm}^{-1}$. Fu and co-workers [87] added frequency
20 modulation to a hyperspectral SRS microscope and, in this way, they effectively removed imaging backgrounds.
21 With this setup, they successfully imaged a non-labelled neurotransmitter directly in live tissue.
22



1

2 **Fig. 11** Sketch of the setup for hyperspectral SRS imaging based on spectral focusing, employing a microsecond delay-line
 3 tuning. AOM, acousto-optic modulator; HWP, half-wave plate; PBS, polarizing beam splitter; QWP, quarter-wave plate; DM,
 4 dichroic mirror; SPF, short-pass filter (wavelength); PD, photodiode; LIA, lock-in amplifier; TAMP, tuned amplifier. Adapted
 5 from [84].

6

7 Another approach to achieve fast delay tuning uses acousto-optic programmable dispersive filters (AOPDFs)
 8 [88,89]. This solution is particularly interesting because it does not employ any mechanical element. The working
 9 principle of the AOPDF relies on the interaction, under phase-matched conditions, between an ultrashort laser
 10 pulse and an acoustic wave, both collinearly propagating inside a birefringent crystal. AOPDFs allow sweeping a
 11 range of delays of a few picoseconds at kHz repetition rate. Alshaykh and colleagues [90] developed a
 12 hyperspectral SRS microscope using an AOPDF and succeeded in acquiring 400 x 400 pixels hyperspectral images
 13 in 5.3 s. Recently, Audier et al. [91] created a fast and low-noise SRS imaging platform combining spectral focusing
 14 and optimized AOPDFs. They reported hyperspectral SRS imaging over a 200 cm^{-1} spectral range with 12 μs of
 15 pixel dwell time and demonstrated the possibility to perform label-free histology on human tissues.

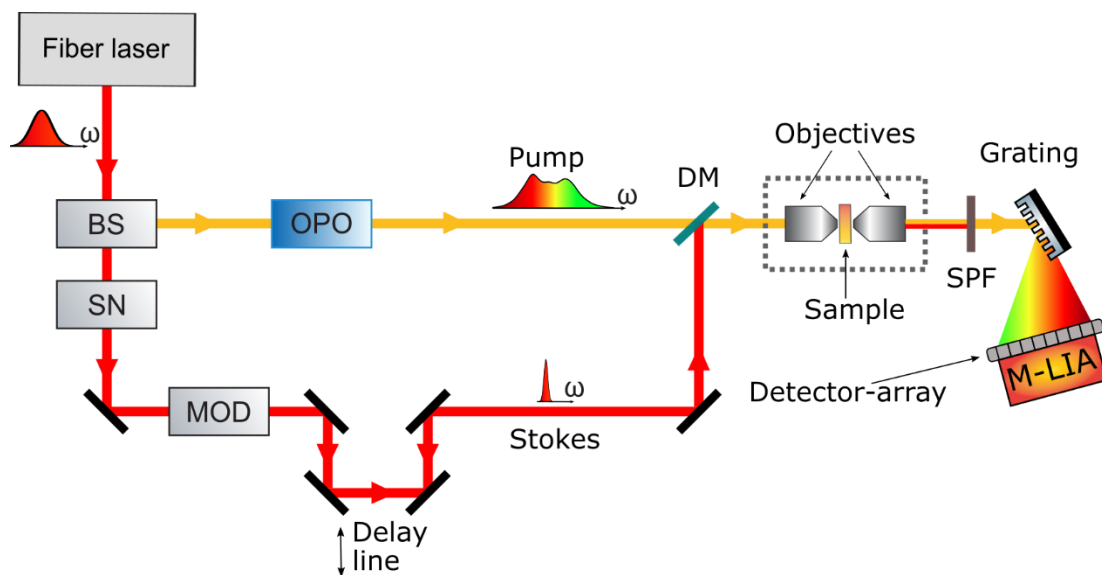
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17 The acousto-optic tunable filter (AOTF) is another device exploited in recent SRS apparatuses that allows
 18 obtaining fast wavelength tunability without any mechanical movement. In an AOTF, an acoustic wave
 19 propagating in a birefringent crystal induces diffraction of an optical wave propagating in the same crystal. By
 20 control of the frequency and the amplitude of the acoustic wave, one can regulate the wavelength and the
 21 intensity of the diffracted one. This technology can be used for both hyperspectral and multiplex SRS
 22 microscopies. In the first case, the hyperspectral image is acquired tuning a single wavelength at a time and
 23 sequentially sweeping the spectral range of interest. In the second case, the image is acquired using multiple
 24 excitation wavelengths at the same time, which are distinguished by applying radio frequency (RF) signals at
 25 different frequencies to the modulator. Fu et al. [92] performed multiplex SRS microscopy employing an AOTF
 26 driven by 8 RF channels with 33 cm^{-1} spectral resolution. The two laser sources utilized were a femtosecond
 27 Ti:sapphire laser for the pump beam and a picosecond Yb laser for the Stokes beam. They decided to use just
 28 three channels of the AOTF, modulated at 125, 100, and 75 kHz, to avoid crosstalk between them. Each channel
 29 was set to excite a different vibrational frequency of the sample under investigation. Then, they applied a 20-

1 MHz modulation to the Stokes beam through an EOM and the detection was performed collecting pixel-by-pixel
 2 the whole SRS signal on a photodiode. At this point, by demodulating with a LIA at 20 MHz and then performing
 3 a real-time digital FT, the three SRS signal components were recovered and multiplex SRS imaging was
 4 demonstrated. More recently, C. Liberale and co-workers [93] demonstrated a broadly tunable SRS microscope
 5 based on a narrowband and fast scanning AOTF filter covering the entire 800-3600 cm^{-1} Raman spectrum with
 6 an enhanced 8 cm^{-1} spectral resolution.

7
 8 Similar to CARS, the multiplex approach allows acquiring the full SRS spectrum in a single shot. Technically, it
 9 requires a modulated narrowband pump and a broadband Stokes beam which are temporally and spatially
 10 overlapped and sent to a microscope. A multichannel detector, either digital or analog, records the broadband
 11 Stokes signal from which, after analog or digital demodulation, the SRG spectrum is extracted. For the case of
 12 SRS, also the combination of a broadband pump with a narrowband Stokes and detection of SRL can be
 13 employed. Digital demodulation employs a spectrometer based on a CCD detector, while analog demodulation
 14 employs an array of photodiodes coupled to a multi-channel LIA. Several multiplex SRS setups have been
 15 proposed that make use of digital demodulation [94–96] but, since no extensive biological applications have
 16 been reported for any of them, they will not be described here. **Fig. 12** shows a general scheme of multiplex SRS
 17 setup based on analog multi-channel lock-in amplifier. A beam splitter (BS) separated the two beams: the
 18 broadband pump is generated using a broadband OPO, while the narrowband ($\approx 10 \text{ cm}^{-1}$) Stokes is retrieved by
 19 simply spectral narrowing (SN) the laser source using an transmission etalon or an ultra-narrowband interference
 20 filter or a spectral filter in the Fourier plane of a 4-f grating or prism system. A acoustic-optical or electro-optical
 21 modulator modulates the narrowband Stokes at high frequency. A delay line synchronizes the two pulses that
 22 are then combined using a dichroic mirror (DM) and sent to the microscope setup. After the sample, a short-pass
 23 filter selects the modulated broadband pump, which is then dispersed using a grating. Its spectrum is then
 24 imaged on a photodiode detector array, couple to a multi-channel lock-in amplifier (M-LIA) [97,98] for analog
 25 demodulation.

26
 27



28
 29
 30

1 **Fig. 12** Multiplex SRS setup. PBS, polarizer beam splitter, SN, spectral narrowing, MOD, modulator; DM, dichroic mirror;
2 LPF, long-pass filter; M-LIA, multi-channel lock-in amplifier.

3

4 A first multi-colour SRS setup was reported by Lu and co-workers [99]. From a broadband femtosecond laser,
5 used as a pump beam, three narrowband peaks are selected employing a grating-based pulse shaper. Each
6 selected peak corresponds to a particular vibrational frequency. On the detection side, the pump pulse
7 transmitted through the sample is again sent to a grating, in order to disperse the three narrowband peaks and
8 to collect each of them on an independent photodiode coupled to a LIA and measure the corresponding SRL
9 signal.

10 Liao et al. [100,101] replaced the LIAs in the detection system with an array of 16 tuned amplifiers (TAMPs),
11 which have a simplified circuitry with respect to commercial LIAs. A TAMP is composed of an LC circuit, a
12 preamplifier, an amplifier, a band-pass filter, a rectifier and, at the end, an analog-to-digital converter (ADC) to
13 measure the demodulated signal. This system permits fast multiplex SRS imaging over 16 channels in the C-H
14 stretching vibrational region with 32- μ s pixel dwell time and it has been used in several different biological
15 applications [101].

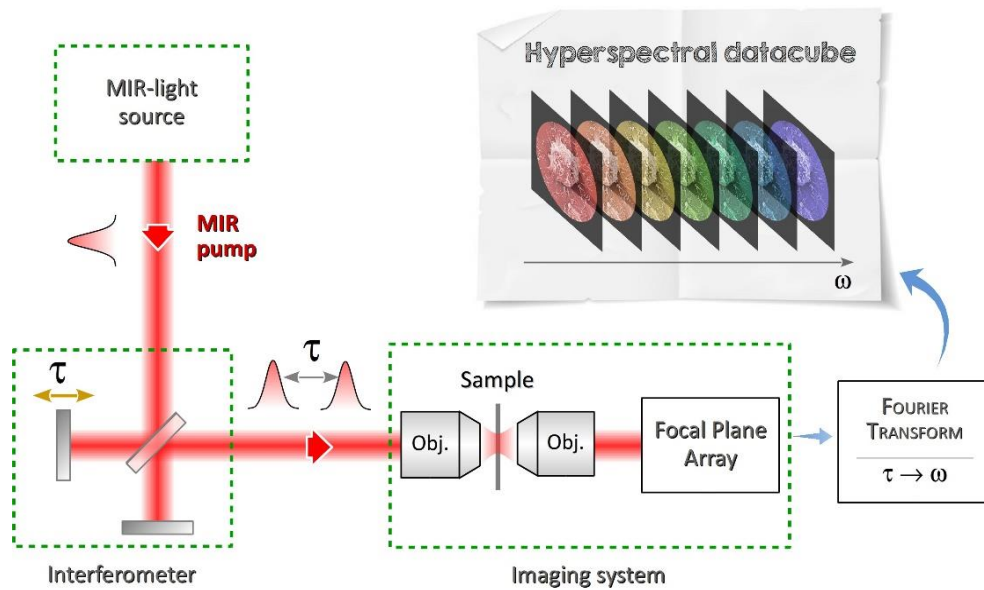
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1 **2.3 IR microscopy**

2 Hyperspectral IR microscopy has the goal of measuring, for every pixel of the image, the vibrational absorption
3 spectrum of a sample. The key parameters qualifying an IR hyperspectral microscope are: (a) the spatial
4 resolution, (b) the spectral resolution and (c) the acquisition time. (a) and (b) contribute to the convergence of
5 numerical methods of image analysis and thereby to reliable chemical characterization [102], while (c)
6 determines the imaging speed of the sample, such as live cells or tissue. One of the challenges of IR spectral
7 imaging is measuring spectra. While spectra in the ultraviolet, visible, or near-infrared ranges are typically
8 measured by frequency-domain spectrometers (in which light is spectrally dispersed by a prism or a grating, and
9 collected by a single scanning detector or an array of static detectors), this is not practical in the IR due to the
10 high read-out noise of the detector. For this reason, spectra in the mid-infrared (MIR) are measured with two
11 alternative approaches. The first one is by illuminating the sample with a tunable monochromatic source and
12 collecting the transmitted/reflected light at a discrete set of frequencies [103]. The second is the time-domain
13 approach known as FT spectroscopy [104]. In this technique the waveform is split in two delayed replicas, and
14 measured by a detector as a function of their delay τ . This produces an interferogram, whose FT with respect to
15 τ yields the intensity spectrum of the optical waveform.

16 Standard IR microscopes are hence composed of three building blocks, sketched in **Fig. 13**: (I) an IR light source,
17 which illuminates the sample; (II) an interferometer which generates the two delayed replicas; (III) an optical
18 imaging system equipped with an IR detector, designed to perform microscopy. In the following, we will detail
19 the properties and the state of the art of these subsystems.



20

21

Fig. 13 sketch of a typical hyperspectral microscope in the IR spectral range

22

(I). *The MIR illumination source*

23

24

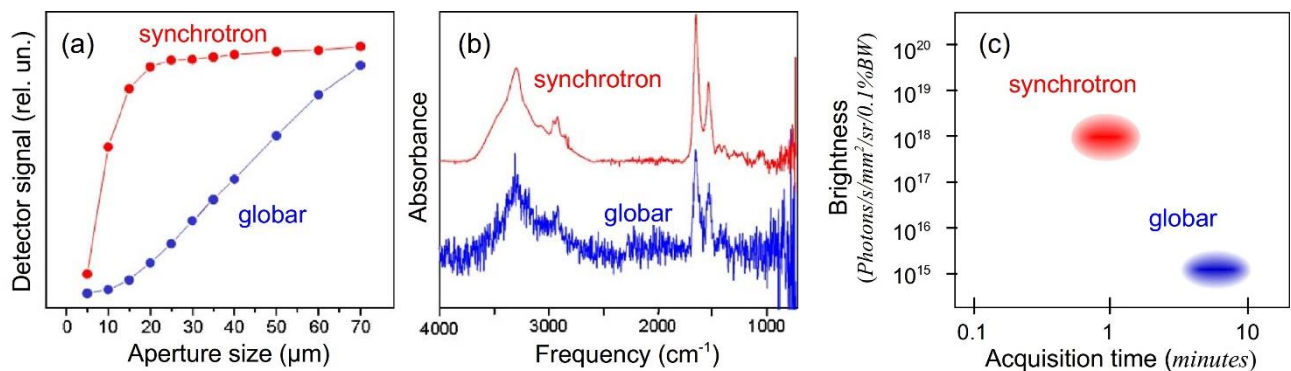
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The IR source illuminating the sample strongly influences the acquisition speed, the spatial resolution, and the bandwidth of the hyperspectral microscope. The first two parameters strongly depend on the brightness of the source, defined as the number of photons emitted per unit time, surface area, solid angle, and bandwidth;

1 in practice, the brightness quantifies not only the total emitted photon flux, but also its directionality. A large
 2 photon flux enables measurements with high signal-to-noise ratio, while high directionality enables sharp
 3 focusing of the light, and hence better spatial resolution of the image. In an ideal far-field system, the best
 4 achievable spatial resolution is fundamentally determined by diffraction and is thus wavelength-dependent; in
 5 addition, it strongly depends on the aperture size and the spatial coherence of the light source [105]. The best
 6 spatial resolution is obtained using infinite apertures and sources with full spatial coherence. Another relevant
 7 figure of merit of the light source is its bandwidth, which directly determines the spectral coverage of the
 8 spectrometer and consequently of the spectral imager: for IR applications, it should at least cover the whole
 9 fingerprint range.

10 Until recently, most IR microscopes, including many commercial products, used a spatially incoherent
 11 illumination based on a Globar. It is a thermal source, typically made of a silicon carbide rod which is electrically
 12 heated up to $\approx 1650^\circ\text{C}$, emitting black-body radiation from 4 to $15\mu\text{m}$ wavelength. This source is very popular
 13 because of its simplicity and broadband emission. However, black-body radiation is spatially incoherent: hence
 14 it cannot be collimated efficiently, deteriorating its brightness and -hence- the spatial resolution of any imaging
 15 application. Coherence, and consequently spatial resolution, can be increased only by decreasing the aperture
 16 size of the source; this, however, drastically reduces the number of photons reaching the sample and degrades
 17 the signal-to-noise ratio of the measurement, which can only be restored by significantly longer acquisition times.
 18 Thermal sources, essentially, force a trade-off between spatial resolution and signal-to-noise ratio. For this
 19 reason, hyperspectral IR microscopes using globars typically require long acquisition times (of the order of 5-10
 20 minutes per image) [102,106–109] (see Fig. 14a).

21



22

23 **Fig. 14** Brightness of MIR sources. **a** Infrared signal through various aperture sizes comparing a synchrotron versus globar
 24 source. **b** Infrared spectra of a single red blood cell collected with a synchrotron versus globar source. The acquisition time
 25 is the same for both spectra; a square aperture of $5 \times 5 \mu\text{m}$ was used. Figures are elaborated with permission from [106]. **c**
 26 Comparison of the brightnesses of different IR sources and their corresponding acquisition time of a spectral image.

27

28 The low brightness of thermal sources induced many groups to explore alternative sources for IR imaging,
 29 from synchrotron radiation [105,110,111], to lasers [112,113]. As opposed to thermal emission, synchrotron
 30 radiation is spatially coherent, which makes its brightness in the IR range about 3 orders of magnitude higher
 31 than that of thermal sources [114,115] (see Fig. 14c). Synchrotron radiation has been successfully applied to MIR
 32 spectroscopy and imaging [105,106,110] showing excellent performances (see Fig. 14b): thanks to its high

1 brightness, acquisition times could be dramatically reduced [116] **Errore. L'origine riferimento non è stata**
2 **trovata.** However, since imaging experiments at a synchrotron facility are obviously unpractical, various groups
3 developed table-top spatially coherent IR sources with comparable brightness: the best candidates are laser
4 sources.

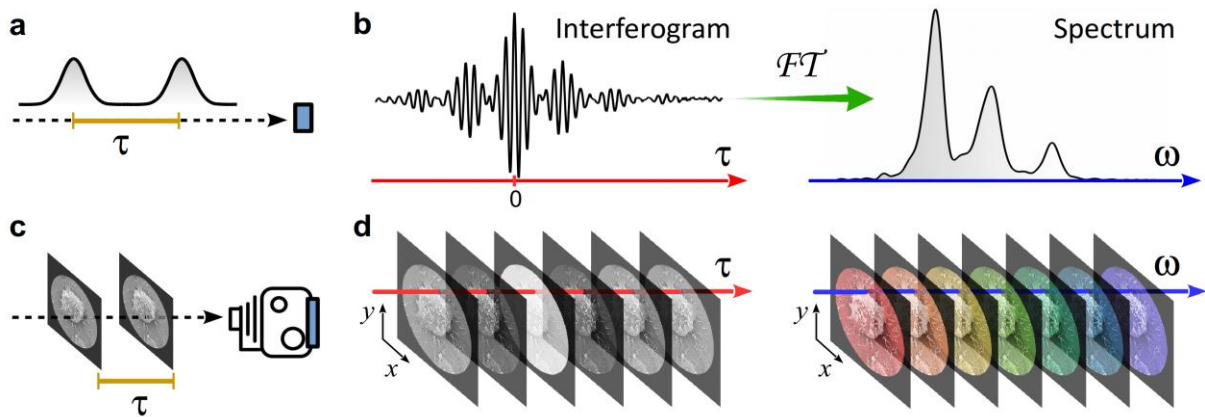
5 Currently, the laser that offers in the IR range the best combination of optical power, compactness and spatial
6 coherence is the Quantum Cascade Laser (QCL), a type of semiconductor quantum-well laser first demonstrated
7 in 1994 [113]. It can be designed to emit narrowband light from 2.6 to 250 μm . IR spectral imaging with QCLs is
8 currently performed by sweeping the laser emission frequency and acquiring various images as a function of the
9 frequency. In practice, this technique samples the IR spectrum over a discrete number of frequencies [103],
10 hence it is called multispectral rather than hyperspectral imaging. The tunability of a single QCL is however
11 limited to $<300\text{ cm}^{-1}$ [117] which is not sufficient to cover the broad fingerprint range ($1000\text{-}1800\text{ cm}^{-1}$) as
12 required in many applications [109]. This issue is overcome by using multiple parallel QCLs, nowadays
13 commercially available (such as MIRcat-QT™ from Daylight solutions, with tunability of 1000 cm^{-1}).

14 (II). *The spectrometer*

15 Spectra in the ultraviolet, visible, or near-infrared ranges are typically measured by frequency-domain
16 spectrometers: light is spectrally dispersed by a prism or a grating, and each frequency is recorded by a pixel of
17 a multichannel detector (based on silicon or InGaAs). Unfortunately, in the IR spectral range, the most suitable
18 detectors are based on HgCdTe (Mercury Cadmium Telluride, MCT), which may provide sensitivity from 2.5 up
19 to 16 μm ($4000\text{-}600\text{ cm}^{-1}$). These detectors, due to the low bandgap of MCT, introduce high read-out noise even
20 at cryogenic temperatures, so that multichannel detectors have low performance, limited number of pixels and
21 high cost. For this reason, spectra in the IR are measured with two alternative approaches. The first one is by
22 illuminating the sample with a tunable monochromatic source, and collecting the transmitted/reflected light at
23 a discrete set of frequencies [103]. The second is the time-domain approach known as FT spectroscopy [104]
24 (see **Fig. 15**). In this technique the waveform is split in two delayed replicas (**Fig. 15a** and measured by a detector
25 as a function of their delay τ . This produces an interferogram, whose FT with respect to τ yields the intensity
26 spectrum of the optical waveform, as sketched in **Fig. 15b**.)

27

28



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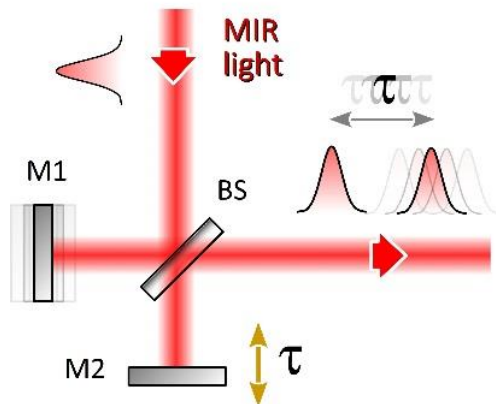
1 **Fig. 15** Fourier transform spectrometer. **a** Two delayed waveform replicas are measured by a point detector. **b** The Fourier
 2 transform of the delay-dependent intensity (interferogram) is the intensity spectrum of the waveform. The same technique,
 3 applied to imaging: **c** Two delayed image replicas are measured by a camera. **d** The approach sketched in **b** can be repeated
 4 for any pixel of the image. The two stacks of images sketched in panel **d** are the (x,y,τ) and (x,y,ω) hypercubes, respectively.

5

6 The spectral resolution of FT spectroscopy is the inverse of the delay scan range and can thus be easily
 7 adjusted; conversely, to record an accurate interferogram, the delay must be controlled to within a small fraction
 8 ($1/100$ or better) of the optical cycle. With respect to frequency-domain spectrometers, the FT approach has the
 9 following advantages: a higher signal-to-noise ratio due to the simultaneous measurement of all spectral bands
 10 (the Fellgett advantage [118]) and a higher optical throughput due to lack of entrance and exit slits (the Jacquinot
 11 advantage [119]). These properties make FT spectroscopy the technique of choice in the IR range [120] **Errore.**
 12 **L'origine riferimento non è stata trovata.**, where the main noise source is readout noise of the detector.
 13 Virtually, all modern IR spectrometers employ the FT approach [121]; for this reason, IR spectroscopy is also
 14 commonly called FT-IR. Another important advantage of FT spectroscopy is that it is suited for wide-field imaging,
 15 since it works also for each pixel of an imaging system, as sketched in **Fig. 15c,d**. For this reason, FT spectroscopy
 16 is the acquisition method used in most IR hyperspectral imaging systems. For the measurement of linear
 17 absorption spectra, the interferometer can be placed at any point between the source and the detector. In IR
 18 hyperspectral microscopes, it is typically placed between the source and the sample.

19 Almost all FT-IR spectrometers, including all state-of-the-art systems reported in the literature and
 20 commercially available (Cary from Agilent, Spotlight 400 from Perkin Elmer, Hyperion series from Bruker), are
 21 based on a Michelson interferometer (see **Fig. 16**), that splits the input beam into two arms, introduces a time
 22 delay between the paths and then recombines the two fields. The main technical problem of the Michelson
 23 interferometer is that any fluctuation of the path-lengths difference translates into a jitter of the time delay,
 24 which spoils the FT accuracy. For this reason, in all commercial systems the precise control of the replicas delay
 25 for stable acquisition is guaranteed by a very robust mechanical setup and auxiliary devices, such as position
 26 tracking with a visible laser beam or active stabilization with feedback control.

Michelson Interferometer



27

28 **Fig. 16** general sketch of a Michelson interferometer, with the basic elements: M1, M2: end mirrors; BS: beam splitter. The
 29 delay between the field replicas is adjusted by translation of M2. The scheme also shows the effect of external perturbations.
 30 As an example, a perturbation on M1 determines a jitter of the pulse delay.

31 (III)- *The optical microscope*

1 The IR optical microscope scheme is similar to a visible light microscope, except that all the optics have to be
2 either reflective or transparent in the IR. In a standard optical microscope operating at wavelength λ , the spatial
3 resolution is determined by the Abbe diffraction limit and is $\approx \lambda/2nNA$, where $0 < NA < 1.4$ is the numerical aperture
4 of the objective and n is the refractive index of the propagation medium. In the fingerprint region ($\lambda = 5\text{-}10 \mu\text{m}$),
5 the best spatial resolution in air is thus of the order of $2.5\text{-}5 \mu\text{m}$. Better spatial resolution is obtained when light
6 propagates in a high refractive index substrate, as in the attenuated total reflection (ATR) modality. In this
7 technique, the sample is in contact with a high refractive index glass (e.g., diamond, germanium, or silicon); the
8 infrared beam enters the substrate at an angle of typically 45° and is totally reflected at the crystal-to-sample
9 interface. In this process a fraction of light, the evanescent wave, penetrates into the sample, at depths which
10 depend on the wavelength, the refractive indices of the ATR crystal, the sample, and the angle of the entering
11 light beam. The penetration depth is typically of the order of a few microns (ca. $0.5 - 3 \mu\text{m}$), thus enabling to
12 measure the very surface of the sample. Thanks to the high value of n , the diffraction limit is reduced by a
13 considerable factor (up to 4 times). Despite the great improvement offered by the ATR approach, the resolution
14 is still not sufficient to resolve sub-micrometer features.

15 Microscopy images are acquired using two possible schemes: either by raster scanning the sample and
16 collecting light with a single MCT detector, or by wide field imaging, which captures the whole image at once by
17 projecting the object image on a 2D multichannel pixelated detector (Focal Plane Array, FPA) [122,123].
18 Compared to the single-point mapping approach, the imaging approach based on FPAs dramatically reduces the
19 acquisition time from hours to minutes [124]. In the IR, each pixel unit of a FPA is a discrete MCT detector. The
20 smallest detail of the sample measured by one detector pixel defines the *pixel-size limit*, which depends on the
21 pixel size and the magnification of the microscope. FPAs became particularly attractive for IR microscopy when
22 the pixel size allowed the microscope spatial resolution to switch from “pixel-size-limited” to “diffraction-limited”
23 [125]. All the reported state-of-the-art microscopes work at the diffraction limit; the most recent improvements
24 only aimed at reducing the pixel-size limit, which currently ranges from $5.5 \times 5.5 \mu\text{m}^2$ to $0.63 \times 0.63 \mu\text{m}^2$ [107,108],
25 well below the diffraction limit. Such pixel size allows image oversampling which contributes to improving the
26 signal-to-noise ratio [107,116,126].

27 Using a combination of 4 different QCLs, each tunable over $\approx 300 \text{ cm}^{-1}$, the SPERO-QT system from Daylight
28 Solutions allows to cover the $950\text{-}1800 \text{ cm}^{-1}$ frequency range. The FPA detector consists of an array (480×480) of
29 micro-bolometers, which do not require cryogenic cooling. Using objectives with 0.7 NA, the achieved spatial
30 resolution is $\approx 5 \mu\text{m}$ at a wavelength of $5.5 \mu\text{m}$. The system was used by Kuepper and coworkers [127] for a
31 feasibility study for the rapid and label-free classification of colorectal cancer tissues. The instrument allowed to
32 obtain a spectral hypercube for a $2 \times 2 \text{ mm}$ field of view (FOV) with 2 cm^{-1} resolution in a time of the order of 1
33 minute (see **Section 3** for more details about applications in cancer detection).

34 A different QCL based system was proposed by Mittal and coworkers [128], using a single pixel confocal setup.
35 The system uses a multilaser source consisting of four QCL modules with beams combined into a single collinear
36 output covering the $770\text{-}1940 \text{ cm}^{-1}$ frequency interval. Imaging is performed by high NA (0.85) aspheric lenses
37 and the sample is moved by high-speed linear translation stages. The transmitted beam is detected by a single,
38 large area, low-noise cryogenically cooled pre-amplified MCT photodiode. To further enhance sensitivity, the
39 QCL is modulated at high frequency (up to 100 kHz) and the MCT output is sent to a lock-in amplifier for
40 synchronous detection. The system is capable of scanning at a speed up to 300 mm/s with a high signal to noise
41 ratio. The low detector noise and the absence of speckle patterns characteristic of wide-field illumination
42 compensate for the loss of the multi-channel advantage of wide-field configurations. The microscope was applied

1 to a comparative study of over 100 breast tumor samples. The rich chemical information combined with the high
2 acquisition speed allowed accurate tumour sub-typing.

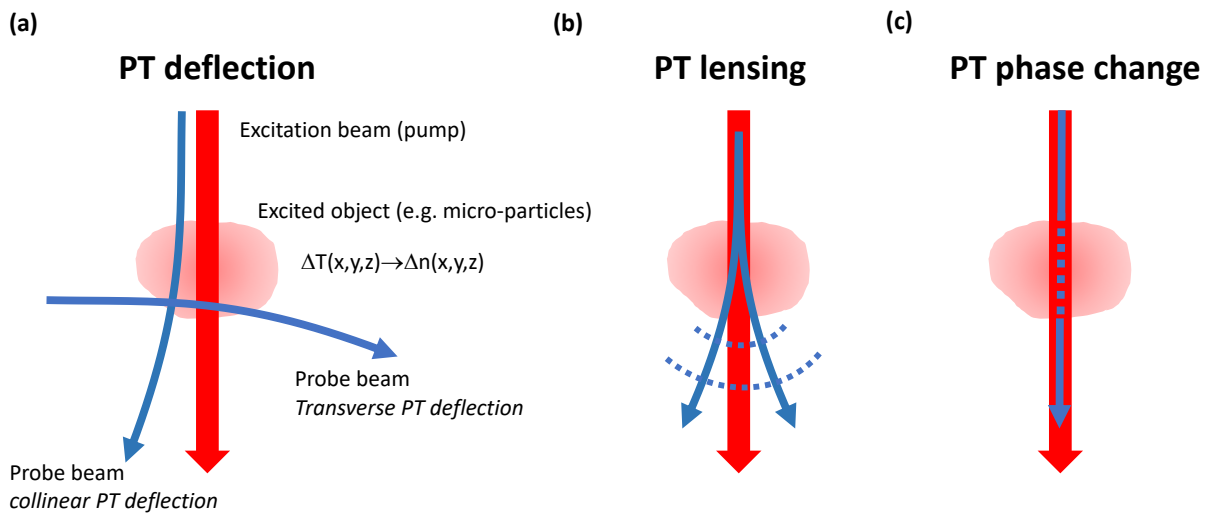
3 The aforementioned QCL-based systems allow to improve the acquisition speed by nearly two orders of
4 magnitude with respect to standard FT-IR microscopes and represent the current state of the art of IR
5 microscopy. The overall speed-up of the acquisition time afforded by the QCLs is an important step towards
6 potential clinical translation of the technique, as it allows larger scale studies in a reasonably short time.

7 Recently, a system overcoming the limitations imposed by the IR detectors in FT-IR microscopy has been
8 proposed [129]. The method makes use of non-linear frequency up-conversion of the IR radiation to shift the
9 detection to the visible spectral range, where low-cost, low-noise and sensitive detectors are available. The
10 system starts with a picosecond Yb:fiber laser producing 15-W average power, 20-ps pulses at 1064 nm and 80
11 MHz repetition rate. A fraction of the laser synchronously pumps an OPO based on MgO-doped periodically poled
12 LiNbO₃ (MgO:PPLN). The idler of the OPO, with a 750-900 mW average power and tunability from 2.3 to 4.1 μm ,
13 is used to illuminate the object. The transmitted beam is then sent to a 4f imaging system, in the Fourier plane
14 of which it is combined with the residual 1064-nm beam and up-converted to the near-infrared by a lithium
15 niobate (LN) crystal mounted on a galvoscaner, to allow angular phase matching of different MIR wavelengths.
16 The up-converted signal is spatially back Fourier transformed by a second lens and finally detected with a
17 standard CCD camera synchronized with the rotation of the up-converting crystal. With a 1° tilt angle of the LN
18 crystal, the system allows to acquire in just 2.5 ms a 64 kpixel image at a single frequency with a spatial resolution
19 of $\approx 35 \mu\text{m}$. The system was used for a proof-of-principle label-free multi-spectral MIR imaging experiment on
20 medical biopsies of cancerous and healthy esophageal tissue samples at 62 frequencies, achieving good
21 agreement with standard H&E and FT-IR images and enabling unsupervised tissue clustering using the *K*-means
22 algorithm.

23

1 **2.4 Photothermal Infrared microscopy**

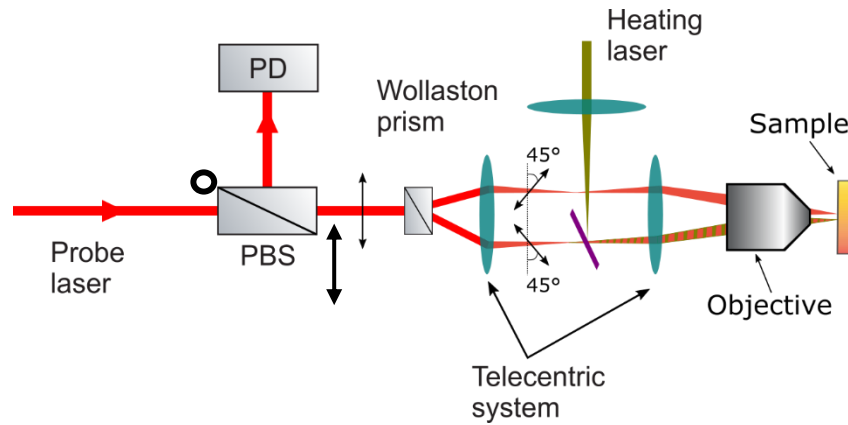
2 In photo-thermal infrared (PT-IR) microscopy a high brightness monochromatic IR beam, typically generated by
3 a QCL laser, resonantly excites a vibrational transition of the sample. The deposited vibrational energy is rapidly
4 (tens to hundreds of picoseconds) dissipated to other vibrational degrees of freedom by intra-molecular
5 vibrational redistribution (IVR), ultimately resulting in a temperature increase of the sample, ΔT , which can be of
6 the order of a few K. Through the thermo-optical effect, the local temperature increase results in a variation of
7 the refractive index of the sample: $\Delta n \cong \frac{\partial n}{\partial T} \Delta T$, which is measured by a visible probe beam. A given molecular
8 species that has been excited in some (x,y,z) position within the sample can thus be identified in so far as the
9 probe beam senses the local index change $\Delta n(x,y,z)$ therein induced by the IR beam, also called pump beam.
10 Depending on the experimental approach, the detection of the refractive index change Δn may exploit deflection
11 or thermal lensing effects, which are related to the index gradient in the plane perpendicular to the probe
12 propagation direction, or phase-shifting effects, which are sensitive to the integrated axial index gradient, as
13 pictorially represented in **Fig. 17**.



14
15 **Fig. 17** Different mechanisms can be exploited to locally probe the thermally-induced refractive index change $\Delta n(x,y,z)$ in an
16 absorbing medium: **a** the deflection of a probe beam collinearly or transversally propagating with respect to the pump; **b**
17 the phase-front distortion and the consequent change of divergence of the probe beam, i.e. a thermal lensing effect, **c**
18 the phase-shift of a probe beam that is co-propagating with the pump.

19 Until the 80s, photothermal (PT) effects were observed on gases, liquids and solids in a variety of arrangements
20 that didn't care about the spatial resolution [130,131], the smallest detected objects being 50- μm -diameter
21 micro-particles and 15- μm -diameter white blood cells [132]. A microscope objective was for the first time added
22 to a PT setup in 1993 to enhance the spatial resolution [133]. Since then, the PT technique has rapidly developed,
23 culminating with the detection of nanometer-sized metal particles in 2002 [134], much smaller than the size of
24 the illuminating spot. Differently from the majority of PT approaches adopted before, which were based on
25 deflection and thermal lensing, the tiny PT signal given by the heated nano-object was interferometrically
26 detected in a polarization-sensitive arrangement illustrated in **Fig. 18**. This achievement attested the capability
27 of PT microscopy to detect objects with diameters orders of magnitude smaller than the pump (and probe) beam
28 diameter, thus far below the diffraction limit [135]. This concept was further expanded later on by wide-field
29 nano-imaging approaches which rely on the quantitative detection of photo-thermally induced phase-shifts via
30 digital holography [136]. In this approach pump and probe beams illuminate a large portion of the sample and

1 the two-dimensional phase-shift pattern imprinted by the sample onto the probe beam is digitally recorded on
 2 a camera sensor by making the probe beam to interfere with an unperturbed reference beam derived from the
 3 same laser source. This mimics holography, the only difference being that the camera must be operated in a sort
 4 of lock-in modality, with “pump-on” phase patterns (hot frames) subtracted to “pump-off” phase patterns (cold
 5 frames), in order to extract the pump-induced differential phase.



6
 7 **Fig. 18** PT setup used for single-point detection of nano-objects. A Wollaston prism splits a horizontally polarized probe laser
 8 (red) into two beams that are focused in different nearby spots by a microscope objective. The heating produced by a pump
 9 laser (green) at just one spot location introduces a differential phase-shift between the two probe beams. This shift is
 10 interferometrically detected by recombining the back-reflected probe lasers to a common vertical polarization state by the
 11 help of a polarizing beam-splitter (PBS) before being sent to a photo-detector (PD). Adapted from [134].

12
 13 Photo-thermally tracked metallic nanoparticles aroused interest in biology as a viable alternative to bulky labels
 14 consisting of fluorescent antibodies, thanks to the absence of photo-bleaching, the chemically inert behavior and
 15 the minimal perturbation to the sample given their much smaller size [137]. The use of functionalized plasmonic
 16 nanostructures as a sensing platform enabled in 2012 the PT detection of single proteins, through the plasmon
 17 resonance shift (and the resulting local temperature change) that occurs when the target molecule binds to the
 18 probed nano-antenna [138]. In other experimental settings no PT medium was exploited, for example to visualize
 19 mitochondria [139] and lysosomes [140] in living cells, or to image H&E-stained biological tissues [141]. In these
 20 cases, the excitation was obtained through electronic transitions in the visible, which give rise to local
 21 temperature changes of several degrees and thus to large PT signals. On the other hand, absorption in the visible
 22 offers relatively poor chemical selectivity, due to the large overlap between absorption bands from different
 23 molecular species in that region. PT-IR microscopy was introduced in 2009 [142] in view of removing this
 24 bottleneck: in PT-IR microscopy an IR pump at a proper wavelength selectively excites a vibrational transition of
 25 a given molecular species, while a visible beam probes the pump-induced local index change with high spatial
 26 resolution. Vibrational excitation of the target molecule in the IR ensures chemically-selective label-free imaging,
 27 similarly to FT-IR, SR and CRS imaging.

28 As compared to FT-IR, PT-IR microscopy exhibits several advantages: i) the spatial resolution is almost one order
 29 of magnitude higher - $\sim 0.5 \mu\text{m}$ against $5 \mu\text{m}$ – because of the much more favorable diffraction limit in the visible,
 30 enabling intra-cellular imaging; ii) the tight focusing of the visible beam results in 3-D sectioning capabilities that
 31 are out of reach in a purely mid-infrared imaging system; iii) PT-IR microscopy exhibits a flatter baseline,
 32 particularly with inhomogeneous samples, since the signal is read out against a zero background and not against
 33 a residual amount of transmitted light; iv) the penetration depth in living samples subjected to water absorption

1 is much larger than in FT-IR microscopy (100 μm rather than 10 μm scale), on the one hand because the large
2 thermal capacity of water mitigates parasitic PT water signals, on the other hand because in a background-free
3 approach a strong PT signal may emerge even at large depths where the IR beam is almost extinguished. As
4 compared to SR, PT-IR microscopy offers a superior imaging speed due to the much larger cross-sections in
5 absorption than in Raman scattering, which result in a stronger signal. As compared to a CRS approach, which
6 produces relatively weak signals in the low-wavenumber region, PT-IR microscopy holds a higher potential for
7 molecular fingerprinting thanks to the capability of direct excitation in the 700-1700 cm^{-1} range.

8 PT-IR microscopy has been mostly implemented so far with optical setups similar to those shown in **Fig. 19** with
9 the sample raster scanned across the pump/probe focus with a piezo stage. Excitation in the IR is typically
10 provided by external-cavity QCLs (ECQCLs) [143–145] or by tunable OPOs [146–148]. ECQCLs offer faster
11 frequency tuning ($10000 \text{ cm}^{-1}\text{s}^{-1}$), narrower linewidths (0.1 cm^{-1}) and straightforward direct intensity modulation
12 at rates beyond 100 kHz, but they suffer from a narrower spectral coverage ($<300 \text{ cm}^{-1}$), which requires the
13 combination of multiple sources to cover the fingerprint region. Differently, OPOs may entirely cover this region
14 with a 10-times higher output power (Watt level), at the price of a fixed modulation frequency (often in the tens
15 of kHz range), a slower tuning speed ($100 \text{ cm}^{-1} \text{ s}^{-1}$) and a broader emission linewidth ($>10 \text{ cm}^{-1}$). The pump laser
16 source is intensity modulated, either directly or externally via an optical chopper or an AOM, to extract the tiny
17 PT signal in a modulation transfer scheme similar to that of SRS, that offers a higher signal-to-noise ratio. The
18 detection system typically consists of an avalanche photodetector coupled with a LIA for demodulation. The
19 interaction of pump and probe beams with the sample may occur either in a co-propagating or in a counter-
20 propagating geometry [149]. The former has the advantage of a straightforward alignment and of an easier
21 implementation of both forward and epi detection schemes for the signal, with epi detection needed for non-
22 transparent media. On the other hand, co-propagation requires the use of reflective objectives with a relatively
23 small numerical aperture (< 0.8) to focus both IR and visible beams on the sample, which is a limitation for the
24 spatial resolution ($\approx 0.6 \mu\text{m}$ for a 785 nm probe, [145]). In a counter-propagating geometry, instead, immersion
25 objectives for the visible beam may optimize the resolution to about 0.3 μm (for a 532 nm probe [148], the issue
26 being in this case the need of a substrate with high transparency in the IR (typically CaF_2 or ZnSe).

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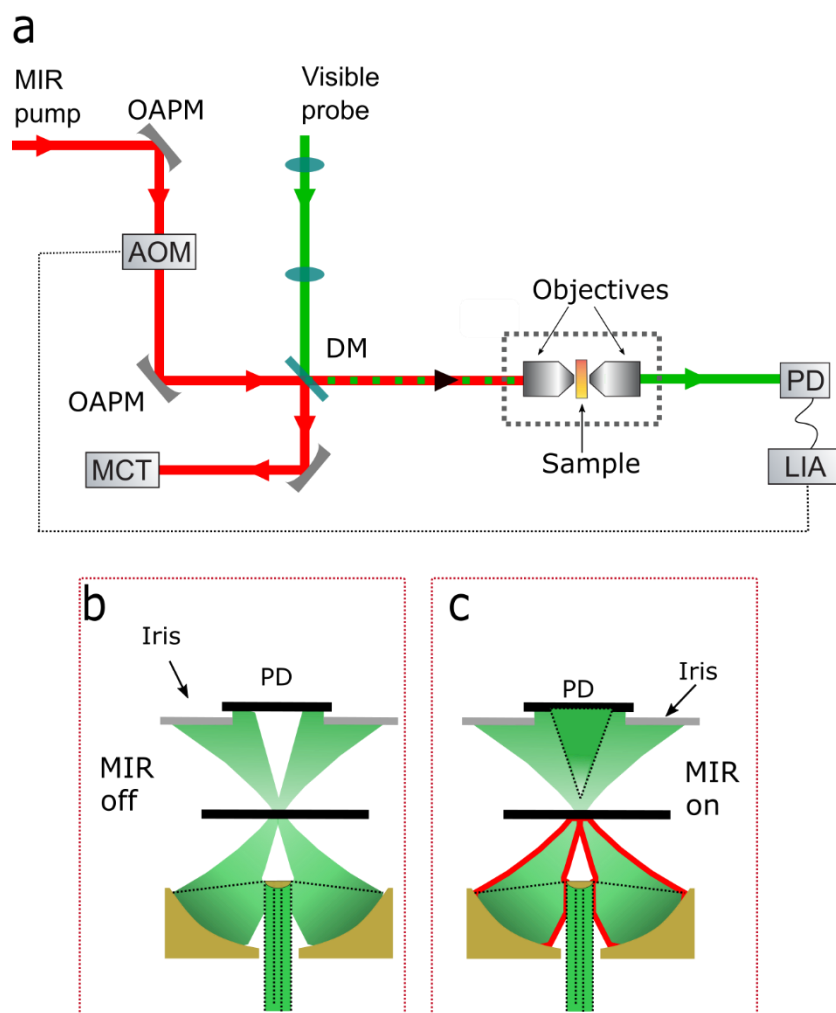
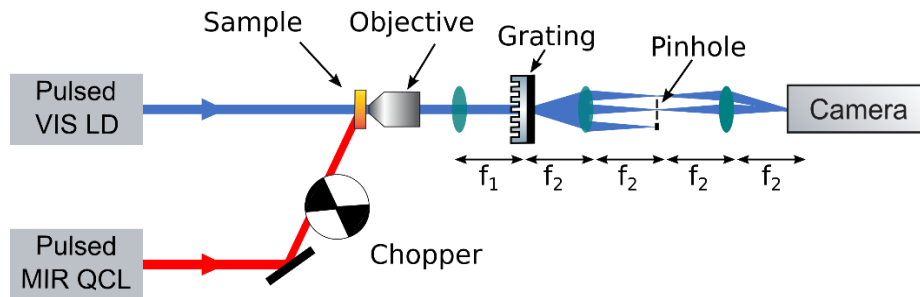


Fig. 19 Schematic lay-out of a single-point PT-IR microscope with forward detection. The IR pump beam is intensity modulated and the pump-induced molecular excitation synchronously detected through the effect that this excitation produces on a collinear visible probe beam. **b,c** A dark-field objective coupled with a diaphragm translates pump-induced local index changes into a modulation of the probe power reaching the photo-detector (PD), as it results by comparing the pump-OFF (b) with the pump-ON (c) case. OAPM: off-axis parabolic mirrors; DM: dichroic mirror. Adapted from [145].

Single-point PT-IR imaging has been successfully applied for the imaging of endogenous lipids and exogenous drugs in live cells [145], for the measurement of active pharmaceutical ingredients and excipients in drug tablets [150], for the characterization of perovskite-based solar cells [147] and for the study of cellular dynamics in oligodendrocytes and live neurons [151]. In live samples, specifically, pixel dwell times of about 1 millisecond have been obtained together with field of views of about $50 \times 50 \mu\text{m}^2$ [151], which implies imaging rates at the 0.1 Hz level. Faster rates, by one order of magnitude in the fingerprint region [146] and two orders of magnitude in the CH stretching region [152], have been recently demonstrated in wide-field geometries such as that shown in **Fig. 20**, which offer a much better spatial overlap between pump and probe beams and therefore a more efficient utilization of the available IR power. Moreover, thanks to the sensitivity of CMOS cameras, effective low-noise integration of the differential PT signal (between pump on and pump off states) may be obtained.

1 Three main geometries have been proposed: i) a counter-propagating epi geometry where the PT signal comes
 2 from the reflectivity change of the sample at the probe wavelength because of the pump-induced thermal
 3 expansion of the sample itself [146]; ii) a co-propagating forward detection geometry (shown in **Fig. 20**) that
 4 efficiently exploits digital holography to convert the phase-shift pattern into an intensity pattern [152,153]; iii) a
 5 co-propagating epi detection geometry where the pump-induced phase-shift is interferometrically retrieved by
 6 translating the sample in the axial direction [154]. A specificity of the wide-field geometry is the need for a probe
 7 beam with low spatial coherence to reduce speckle artifacts in the final image, which leads to the use of LEDs
 8 [153,154], or of pulsed laser diodes [155] or of frequency doubled femtosecond oscillators [152]. For the IR light,
 9 peak irradiation fluences are typically kept at the $10\text{-}50\text{ pJ}/\mu\text{m}^2$ level, thus below the ANSI standard for IR induced
 10 damage fixed at $100\text{ pJ}/\mu\text{m}^2$.

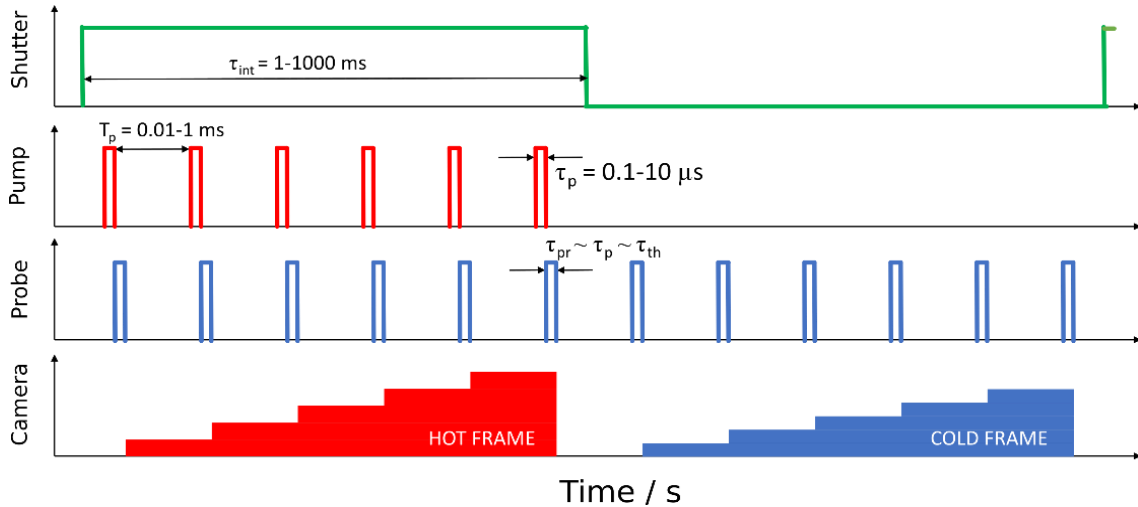


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13 **Fig. 20** Digital-holography applied to PT-IR microscopy. The diffraction from a grating splits the probe beam in several
 14 replicas that are made to interfere onto the camera, with one replica (upper blue beam in the figure) transferring the
 15 sample-dependent phase pattern to the camera and a second replica (central beam in the figure) producing a flat phase-
 16 front reference beam after spatial filtering with a pin-hole. The pump beam is intensity modulated and camera acquisitions
 17 with “pump OFF” must be subtracted to camera acquisitions with “pump ON” for proper normalization and quantitative
 18 phase imaging. Adapted from [155].

19

20 Influential aspects for the design and the performance of a wide-field PT-IR microscope are the duration and the
 21 synchronization of excitation, probing, and framing events, which are schematically illustrated in **Fig. 21**. To
 22 prevent heat diffusion and degraded spatial resolution, the pump pulse duration (τ_p) must be shorter than the
 23 thermal response time (τ_{th}) of the sample, typically in the $1\text{-}100\ \mu\text{s}$ range. In general, as a higher water content
 24 speeds up the thermal response because of the fast thermal diffusivity, sub-microsecond pump pulses are
 25 preferred for live samples. Likewise, probe pulses must be shorter than τ_{th} and sharply follow the pump pulses
 26 to sense the sample at the highest temperature. The maximum repetition rate (f_{rep}) at which pulses can illuminate
 27 the sample is limited by the need for the sample to cool down between excitation events, which results in f_{rep}
 28 equal to the inverse of 4-to-6 times the thermal time constant τ_{th} . PTIR images are formed by subtracting the so-
 29 called cold frames, i.e. the probe intensity patterns acquired by the camera in the absence of pump, from the
 30 hot frames, i.e. those in the presence of the pump. An equal number N of probe events must be then integrated
 31 in hot and cold conditions for the PT signal to emerge from the background, with N depending on the ratio
 32 between probe pulse repetition frequency f_{rep} and camera frame rate f_{fr} . In most cases f_{rep}/f_{fr} ratios of about 10
 33 have been used, one of the limitation being that cameras with large well depth, that are preferred because of
 34 the lowest shot-noise limit, can't be easily operated at high rates ($> 500\text{ Hz}$).



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Fig. 21 Synchronization of pump and probe pulses in PT-IR microscopy. Pump (τ_p) and probe pulse durations (τ_{pr}) are chosen commensurate with the thermal time response (τ_{th}) of the medium, changing from sample to sample, in order to avoid heat diffusion and thus reduced spatial resolution. The probe pulse closely follows the excitation pulse to read out the temperature change at its maximum. The duty-cycle of the excitation, namely τ_p/T_p (with $T_p=1/f_{rep}$) is typically chosen lower than 50 % to avoid cumulative thermal effects. The camera integrates the signal over many pulses, the integration time τ_{int} being ultimately limited by the camera frame rate f_{fr} . As the photo-thermal signal comes out from the difference between pump-ON and pump-OFF images, the pump must be modulated (with a shutter, e.g) at a frequency $\frac{1}{2} f_{fr}$ with a 50% duty-cycle to enable the correct normalization of hot frames with respect to cold frames.

1 **3. Application of vibrational imaging to histopathology**

2 Even if the first example of vibrational spectroscopy analysis of a biomedical tissue - using a Raman microprobe
3 - was reported in 1979 by Abraham and Etz [156], systematic studies on cancer tissue samples have started in
4 the early 90s, revealing the high potential of detecting pathology-related spectral features using the advantage
5 of light-based label-free approaches. At that time, vibrational studies were mainly collecting single-point spectra
6 on pre-selected tissue regions to identify specific biomolecular signatures associated to a particular pathological
7 state, commonly using multivariate analysis, as extensively reported by previous review articles [157,158].

8 In this review we focus on “imaging” approaches for the study and diagnosis of cancer. When speaking about
9 spectral imaging (e.g. SR imaging, FT-IR imaging, CRS imaging, PT-IR imaging etc.) we normally refer to vibrational
10 approaches able to produce false-color images derived from the extraction of spectral data of a relevant tissue
11 region of interest, preserving the spatial information with sufficient resolution.

12 Before tackling the description of the most relevant advances in the field it is worth answering a basic question:
13 why imaging? This is not an obvious or trivial question if one considers that moving from spectra to images
14 generally requires to greatly increase the measurement time, the system complexity, the analytical
15 performances, and the interpretation efforts. In addition, we should also consider that, in some circumstances,
16 pathological signatures could be extracted from body fluids or tissue lysates, thus analyzing the overall
17 biomolecular composition of homogenous samples without the need for imaging techniques [159,160].

18 The first good reason for imaging is “morphology”. The reason why medical doctors still rely on histological
19 sections in the 21st century - the era of omics approaches, system biology and liquid biopsies - is that the
20 appearance, the morphology and the spatial organization of cells and tissue is still of vital importance for the
21 recognition of many tumors. The organization and distribution of cells and biomolecules into a specific tissue can
22 be strongly associated to a given disease. This explains why, for most tumors, the very first diagnostic step is the
23 visual evaluation of tissue samples. A second good reason for imaging is “biomolecular complexity”. Ideal
24 diagnostic tools should rely on the detection of a single, or a few, biomarkers, identified in readily available
25 biological fluids (e.g. blood, urine, saliva etc). Even if hundreds of candidate cancer biomarkers have been
26 reported and proposed, few of them are used in cancer care and, nowadays, there is not any single biomarker
27 able alone to provide a definitive diagnosis. This intrinsically depends on the complexity of cancer biology and
28 mechanisms. As a matter of fact, in most cases, the diagnosis of cancer made by pathologists counts on multiple
29 complex criteria including the presence of specific morphological structures, the presence and percentage of
30 specific cell subpopulations, the size and shape of cells, the alteration of surrounding healthy regions and the
31 local response of immune cells (microenvironment). Only an overall and detailed description and observation of
32 all these features in 2D (and ideally 3D) generally guarantees a correct cancer assessment and diagnosis. The
33 third reason is “translational medicine”, which is strictly related to the first answer. If new technologies want to
34 enter the clinical practice, they should be accepted, understood, and assimilated by the clinical environment and
35 medical doctors. In other words, vibrational images can be easily read by pathologists due to their similarity with
36 standard H&E images and can be potentially introduced in the standard diagnostic pipeline without major
37 changes.

38 These three reasons may help to understand why so many efforts and investments have been made, and are still
39 pursued, to develop and optimize vibrational imaging tools for cancer diagnosis. Vibrational spectroscopy
40 coupled to microscopy can simultaneously provide morphological and biomolecular details with objectivity and
41 reproducibility. At the same time, referring to translational compatibility, vibrational imaging approaches are
42 based on the use of the same samples employed by the pathologist; usually they correspond to thin tissue slices

1 contiguous to those used for the standard diagnosis. In addition, data emerging from vibrational imaging can be
2 easily (computationally) colored thus providing images which very closely resemble standard stained histology
3 slices.

4 In this section we overview the applications of the four vibrational imaging approaches (i.e. SR, CRS, FT-IR and
5 PT-IR) to histopathology for cancer diagnosis and classification. We have chosen to describe the evolution of the
6 technologies, accompanied by improved performances and results, following a quasi-historical criterion, by
7 reporting the most relevant steps in the field.

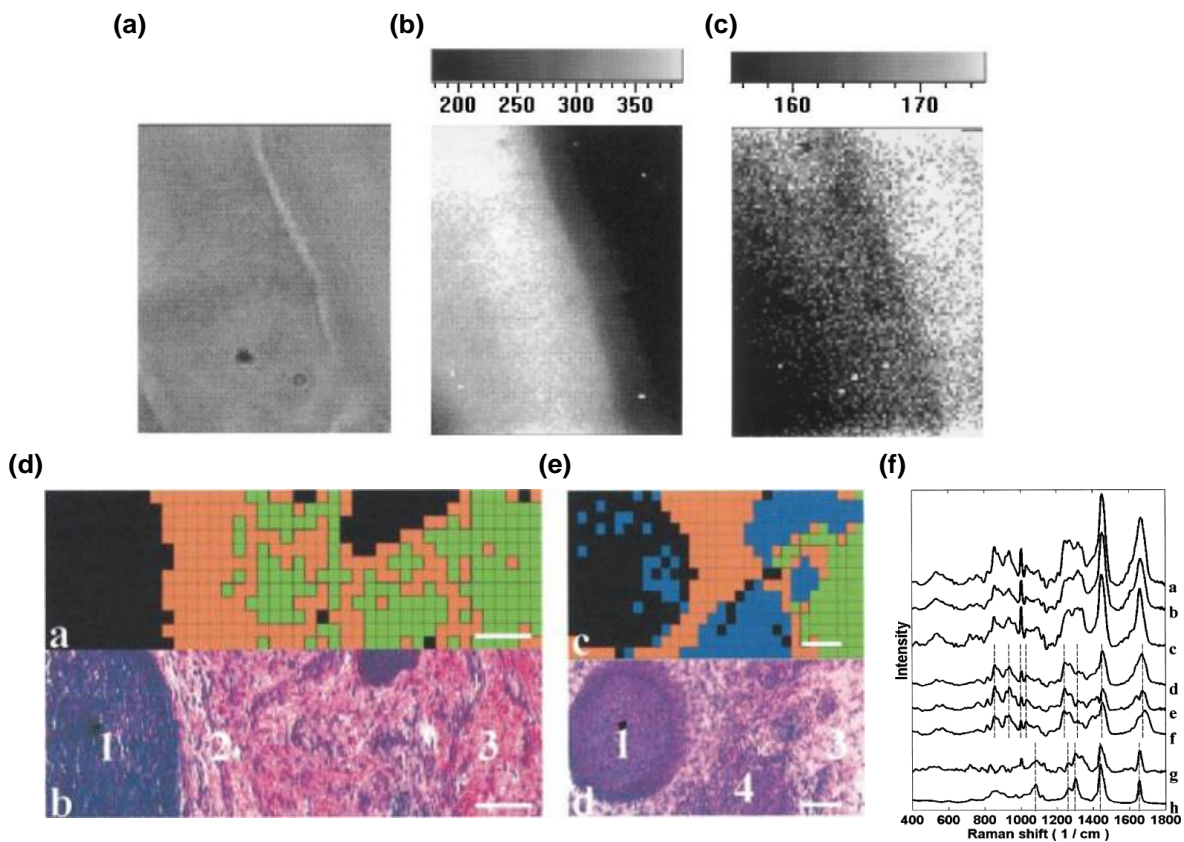
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9

1 3.1 Spontaneous Raman Imaging

2 C. Otto *et al.* were the first to report SR images of tissue samples (1997) by recording the boundary between
3 healthy eye lens and cataract regions [161] (Fig. 22a-c), while the first SR maps on cancer tissue were reported
4 by Puppels and collaborators in 2002 [162] (Fig. 22d-f).

5



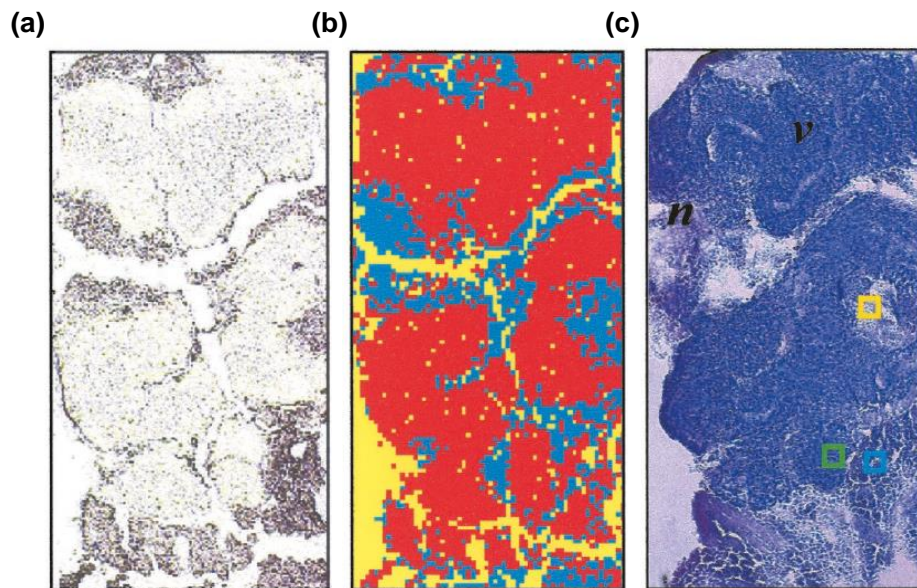
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7 **Fig. 22** Early Raman imaging experiments on human tissues. **a** bright field image of a cataractous human eye lens. **b**
8 univariate Raman image at 1586 cm⁻¹ related to filipine stain for cholesterol. **c** Raman image at 1004 cm⁻¹, related to
9 phenylalanine (endogenous) and showing two different eye regions, with or without cataractous opacity. Scales on the top
10 are related to signal intensity. Adapted with permission from [161]. **d,e** Raman maps of skin cancer (basal cell carcinoma,
11 BCC) (black) surrounded by healthy dermis (orange and green), with H&E stained adjacent sections (bottom). In **e** a
12 different clustering approach also shows inflammatory infiltration (blue). Scale bar: 100 μm **f** shows Raman spectra of
13 clusters reported in panels d,e, including difference spectra and reference spectra. Adapted with permission from [162].

14

15 This pioneering approach aimed to determine the tumour margins by SR spectroscopy by extracting the local
16 tissue composition and heterogeneity in skin cancer (basal cell carcinoma, BCC) biopsies. This clinical need was
17 used as a driver to design one of the first SR imaging approaches. The study by Nijssen *et al.* reported an
18 experimental and data-processing workflow which is not too far from protocols employed nowadays and can be
19 used here to summarize a general approach to SR imaging studies. In detail, the complex workflow included: (a)
20 the use of adjacent cryosections (25 μm thickness) from biopsies (b) placed onto Raman-transparent optical

1 substrates (CaF₂ slides) or (c) placed onto a standard microscope slide for H&E staining, to be used as diagnostic
2 reference. Moreover, (d) for each sample a selected area was scanned (using a motorized stage) in two
3 dimensions with a step size of 10 μm using a Raman microspectrometer coupled with a near infrared (850nm)
4 laser light (100 mW) focused on the sample by an 80x objective. (e) After a proper calibration and pre-processing
5 step the data were first analysed by principal component analysis (PCA) [163] to reduce the number of variables
6 in the dataset. Then, (f) principal components were used as input for K-means clustering analysis (KCA) [164]
7 which, in turn, is able to find groups of spectra with similar features. (g) For each cluster an average spectrum
8 was automatically calculated and (h) a colour was assigned to it to produce false-colours images to be compared
9 with H&E-stained tissue sections. After having defined different clusters, the challenge is to use these data to
10 classify healthy and cancer regions of the tissue. To this aim (i) all clusters detected in 15 tissue samples (each of
11 them also containing cancer regions) were assigned to different tissue areas (BCC (cancer)), dermis (healthy
12 tissue), and epidermis (healthy tissue)). (j) All classified clusters were then again analysed by PCA to reduce the
13 number of parameters representing the spectral variability of the entire dataset. (k) The scores of the first
14 principal components were then used as input for a multivariate model, together with the above-mentioned
15 histopathological classes. In details, a logistic regression was used to distinguish cancer vs healthy clusters. Finally
16 (l) the sensitivity and the specificity of the classification model were obtained by the so called “leave-one-out
17 cross-validation” approach [165]. In this approach, the spectra of all but one cluster mean were used to generate
18 the classification model and the excluded cluster mean was used as a test sample. This procedure was repeated
19 for each cluster of the dataset to define the method accuracy, finally scoring as 100% sensitivity and 93%
20 specificity for the recognition of cancer clusters. In parallel, the same group also reported the capability of Raman
21 imaging to discriminate tumour from necrotic tissue in unfixed human brain tissue slices [166] (**Fig. 23**). This
22 study sets the basis for real-time intraoperative biopsy or surgery guidance by vibrational-based approaches.



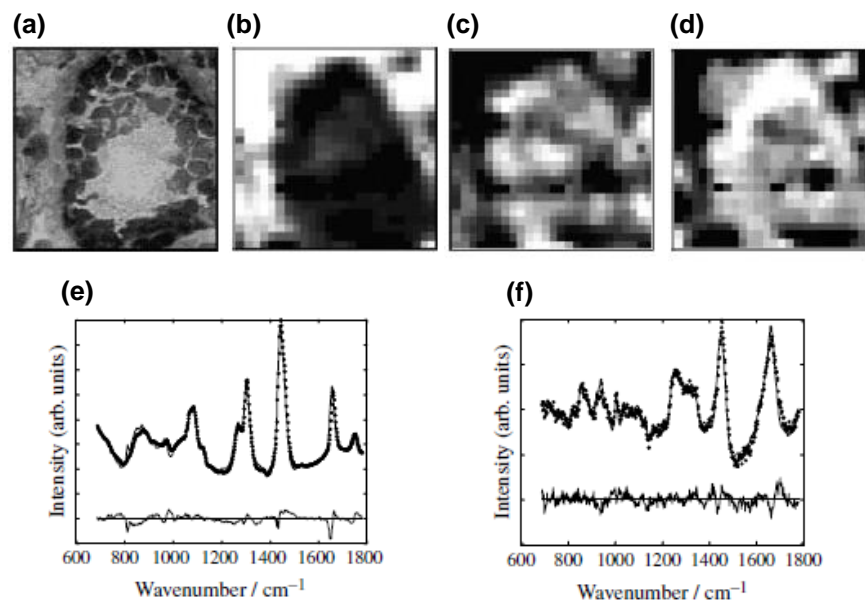
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24 **Fig. 23** Raman imaging of glioblastoma (brain tumor) on human frozen cryosections. **a** bright field image of the unstained
25 tissue section recorded before Raman measurements (size: 1280 x 2420 μm). **b** Raman map obtained after linear
26 discriminant analysis (LDA) used to classify and predict vital (red) or necrotic (blue) regions in human glioblastoma. **c** the same
27 tissue section after H&E staining reporting vital (v) or necrotic (n) regions defined after histologic evaluation. Adapted with
28 permission from [166].

1

2 In the same period the group of Michael Feld from the Harrison Spectroscopy Laboratory (MIT, Boston) started
3 to approach breast cancer diagnosis by Raman imaging, introducing the use of linear combination models to fit
4 tissue spectra with reference spectra derived from various pre-selected tissue morphological structures or
5 components (i.e. epithelial cell cytoplasm, cell nucleus, fat, beta-carotene, collagen, calcium, hydroxyapatite,
6 calcium oxalate dehydrate, cholesterol-like lipid deposits, and water) [167,168]. As an example, **Fig. 24** reports,
7 on the top, Raman images of breast ducts representing the contribution of specific tumour elements in the region
8 being studied (i.e. collagen, cell cytoplasm, cell nucleus) well representing the possibility to automatically
9 distinguish different morphological and biomolecular features. In parallel, the image shows (**Fig. 24** , at the
10 bottom) how a linear combination model can be used to distinguish normal and carcinoma samples starting from
11 the identification (fitting) of representative tissue components. These studies revealed that fit coefficients for
12 fat and collagen are the key parameters in the resulting diagnostic algorithm, for distinguishing cancerous tissues
13 from normal and benign tissues.

14



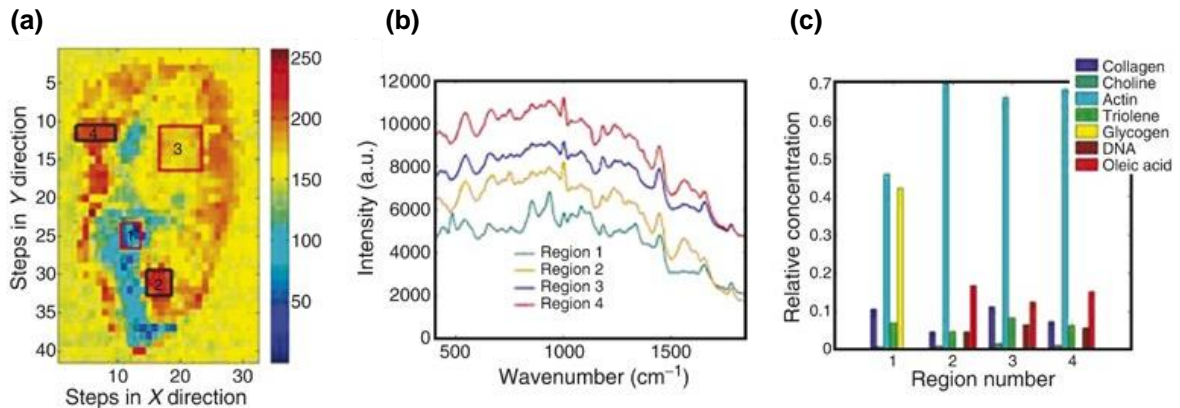
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16 **Fig. 24** Raman imaging of human breast tissue. **a** H&E stained section. **b,c,d** Raman images reporting the contribution
17 (brighter pixels are associated with higher signal) of collagen, cell cytoplasm and cell nucleus, respectively. (size : approx. 70
18 x 70 μm). **e,f** example of normal tissue and tumour (infiltrating ductal carcinoma) spectra, respectively. Bold dots represent
19 data, the lines are the model spectra. Residual plotted below. Adapted from [167] (CC-BY-NC-SA 3.0).

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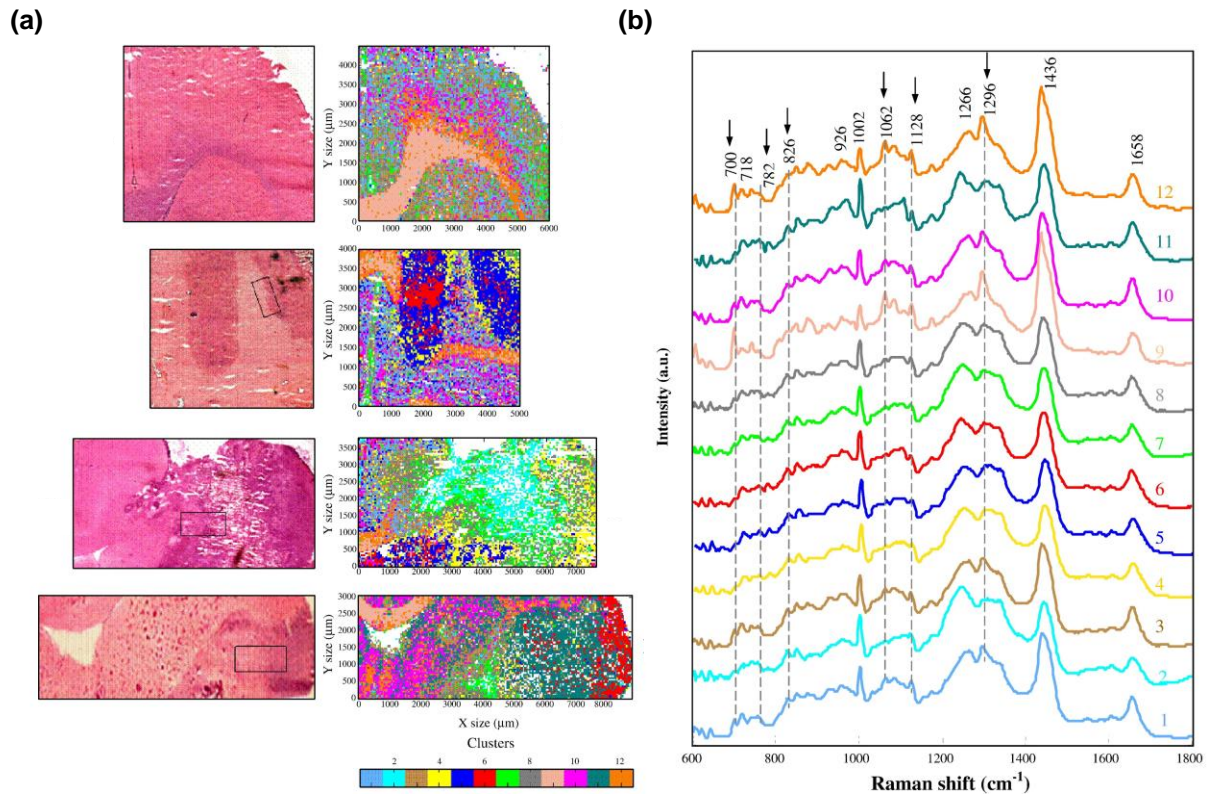
21 With similar approaches, Stone and collaborators used Raman mapping approaches to elucidate biochemical
22 changes in carcinogenesis of oesophagus [169]. In details, 20 μm thick fresh frozen tissue slices were mapped by
23 a 830nm laser at 100 μm step size across the whole sections (n=29) from 22 patients. Thereafter, a partial least
24 square (PLS)-based algorithm was implemented in the data analysis pipeline in order to perform a fitting process
25 using selected biochemical constituents (i.e. collagen, choline, actin, triolein, glycogen, DNA, oleic acid) after
26 having identified the main biochemical changes by PCA. An example of mapping results is reported in **Fig. 25**. In
27 particular, the score map resulting from PCA (scores of the third principal component) enables distinguishing

1 different regions with representative mean spectra (box in the middle). In addition, for each selected
2 representative region, the relative concentration of specific biochemical constituents is depicted (**Fig. 25c**).



3
4 **Fig. 25** Raman imaging of human oesophagus cancer (adeno carcinoma). **a** Raman image reporting the score of principal
5 component (PC3), with selected regions marked. **b** mean Raman spectra from selected regions (panel **a**). **c** relative
6 concentration of selected biochemical constituents from selected regions. Adapted with permission from [169].

7 In 2007, Manfait and collaborators reported Raman mapping data of relatively large tissue regions (with average
8 size of 4x7mm) by collecting Raman spectra with 50µm step size [170] (**Fig. 26**). The clustering analysis of healthy
9 and brain tumour tissue correctly described their peculiar features. Furthermore, false-colour images showed
10 that Raman clusters provide more information than standard H&E staining. In details, the cortex regions (those
11 containing most neurons in brain tissue), when studied by Raman imaging, revealed the presence of four
12 different cortex layers with small but significant biomolecular differences, whereas H&E staining reveals a single
13 uniform layer. This is a good example to understand how much the morphological features extracted from
14 hyperspectral imaging data are strictly related to the specific biochemical and biomolecular composition of the
15 investigated region. In other words, Raman imaging can, in some cases, distinguish different biomolecular – and
16 therefore disease-specific – features, even if their morphology is very similar or identical and, consequently, very
17 difficult to be used for diagnosis by pathologists using standard H&E approaches.



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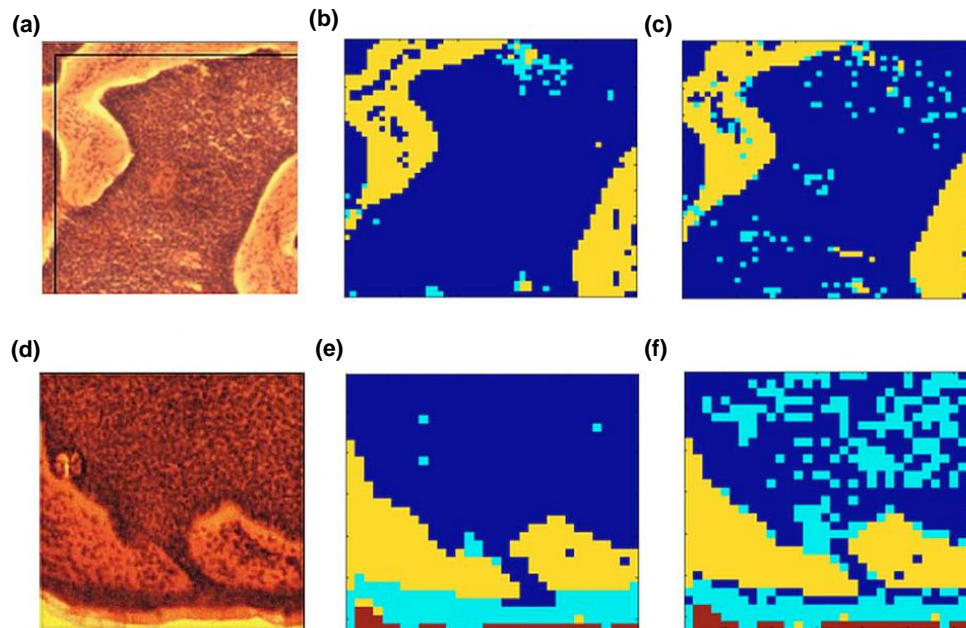
3 **Fig. 26** Raman imaging of human brain tissue sections, including healthy and cancer (glioma) regions. **a** Raman images based
4 on 12-means cluster analysis on sections (right) accompanied by H&E-stained contiguous tissue slices (left). **b** mean Raman
5 spectra of each cluster, with the same colours. Adapted with permission from [170].

6 In parallel with the application of Raman imaging to different tumour types, a challenging frontier emerging in
7 the field was related to data processing and statistical analysis of intrinsically complex imaging data, as a
8 prerequisite to bring Raman imaging closer to the clinical application. For example, most literature reported the
9 use of “unsupervised methods”, such as KCA and PCA, which are limited by the fact that only the information
10 contained in a specific sample can be used for classification, thus inhibiting the use of the same information to
11 automatically classify new samples. At this concern, Nothingher and collaborators started proposing supervised
12 automatic methods for the classification and detection of skin tumour (BCC) in normal skin tissue (i.e. dermis
13 and epidermis) using Raman imaging data [171]. In details, supervised methods are based on the extraction of a
14 relatively large amount of information, from numerous samples, that can be used to both classify this first dataset
15 (so called “training dataset”) but also to provide a classification of new samples (so called “testing dataset”) not
16 previously included. For this purpose, 329 tissue regions (50x50 μm), including both tumour and healthy regions
17 from 20 randomly selected patients, were first studied to extract the corresponding average spectra and to build
18 a spectral database. Then, the authors performed a linear discriminant analysis (LDA) for data classification and
19 validation. LDA is a statistical tool able to provide the maximum separation between diagnostic classes that lead
20 to different decision values and can be easily used to automatically assign every spectrum (including spectra
21 never used to build the classification model) to a specific class (e.g. cancer vs healthy tissue). The input variables
22 required to perform LDA must be numerically smaller than the smallest class contained in the dataset to be
23 classified. A common practice is to use PCA of the entire original dataset to reduce the number of spectral

1 variables (usually between 200 and 1000 depending on the spectral resolution) to an acceptable number (< 20),
2 and this approach, usually called “PCA-LDA”, is now commonly used in the field [172].

3 In a different approach, Nothingher and collaborators used as input variables the area of six selected Raman
4 bands, associated to DNA and proteins, previously identified as significantly different between BCC, dermis and
5 epidermis. According to the authors, this approach was optimal considering that the variability extracted by PCA
6 is not always distributed between different diagnostic classes. In addition, a preliminary qualitative analysis of
7 the dataset may sometimes reveal significant spectral features already associated to different diagnostic classes.
8 After having tested and validated the classification model using the 329 spectra emerging from small tissues, the
9 authors applied LDA-approaches to identify cancer (BBC) on a set of 6 large images (around $500 \times 500 \mu\text{m}^2$). To
10 this aim, they used two different approaches (**Fig. 27**). For the first method (k-means method) the entire dataset
11 was processed by k-means clustering to reduce its complexity while still preserving the spectral separation for
12 the detection of cancer features. Then, for each cluster ($n=11$), the ratios of the six above-mentioned Raman
13 bands calculated on the cluster centroid spectrum, were used as input for the LDA model. As a result, each cluster
14 was automatically assigned to one diagnostic class in the false-colour images. The second method applied the
15 LDA model using the same six Raman bands ratios used before as an input, but directly to the individual spectra
16 constituting the Raman images. In this second method, each spectrum, and not each single cluster, was classified
17 according to the possible diagnostic classes.

18 Even if the k-means-LDA approach showed better performances, both approaches were able to accurately
19 recognize BCC in unknown skin tissue samples that were not used to build and train the classification model. This
20 evidence has been a good demonstration of the possibility to use SR imaging for the automatic recognition of
21 cancer in new samples after a good model training.

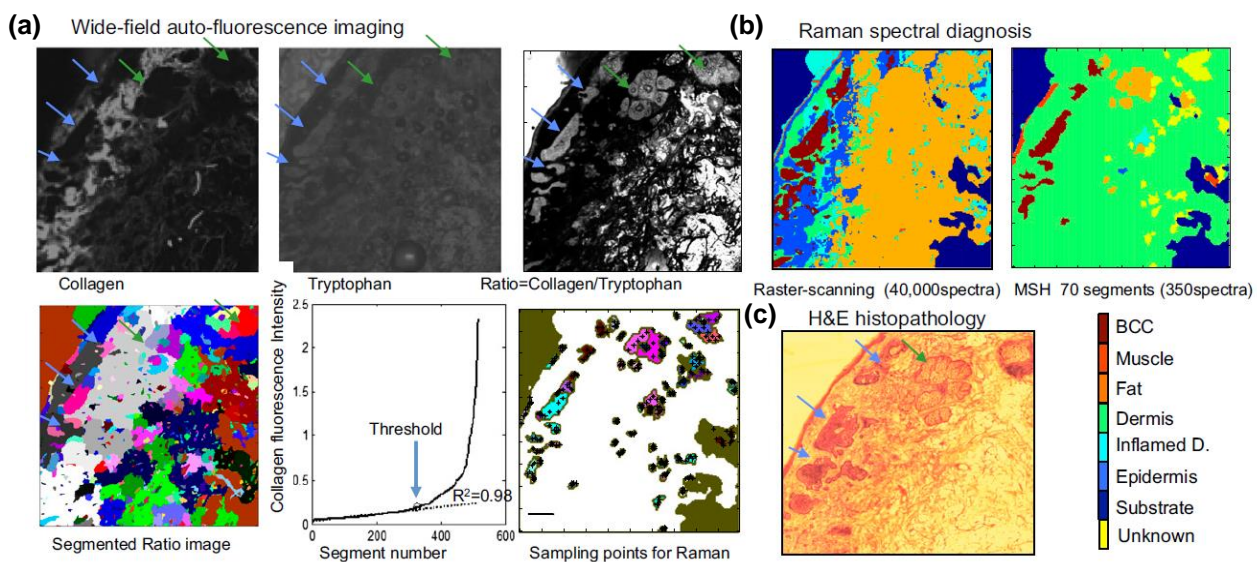


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23 **Fig. 27** Comparison between H&E images (**a,d**) and Raman imaging of human skin cancer (basal cell carcinoma) produced
24 with two different supervised methods. **b, e** Images produced by the *k*-means method. **c, f** Images produced by the direct
25 LDA method. Tissue size: $500 \times 500 \mu\text{m}^2$. Adapted with permission from [171].

26

1 After the first evidence about the efficacy of SR imaging-based tools for the recognition of tumour features and
 2 after the application of Raman imaging on different tumour types, many efforts have been made to move to the
 3 clinics. A very important limitation of SR imaging has always been its intrinsically low acquisition speed. The
 4 collection of SR images with lateral resolution between 10 and 20 μm (i.e. from 2500 to 10000 spectra per mm^2)
 5 usually takes between 40min to $>20 \text{ h}/\text{mm}^2$ (considering at least 1 second per spectrum) due to the intrinsically
 6 weak signal generated by SR. If we consider that histological samples are typically between 30 and 100 mm^2 in
 7 size (reaching millions of spectra), diagnosis of entire tissue specimens, with a spatial resolution almost two
 8 orders of magnitude worse than that achievable with H&E, would require many hours to several days. This is
 9 surely not compatible with intra-operative diagnosis (total time from 30 to 120 min depending of type of tumour)
 10 and still far from standard diagnostic procedures considering that the current protocols to obtain H&E-stained
 11 slices from the excised sample usually takes 12 to 72h. This is also the reason why several reported studies
 12 collected Raman images from small tissue regions (usually of max 1 mm^2) that were previously selected as regions
 13 of interest from samples with full size ranging between 25 and 100 mm^2 [171,173,174]. This approach cannot be
 14 feasible if Raman is to be used as unique diagnostic approach without the intervention of pathologists.

15 Some strategies have been suggested to circumvent the low speed of imaging procedures without necessarily
 16 increasing the acquisition speed or changing the acquisition modality (see “line-scanning” or “wide-field”
 17 modalities in section 2.1). For example, Kong *et al* from the Notinger’s group, proposed the so called “multi-
 18 modal spectral histopathology” (MSH) by applying automated segmentation and pre-selection of diagnostically
 19 relevant tissue sections by using autofluorescence to prioritize sample points for SR spectroscopy [175–177].
 20 After recording wide-field autofluorescence images for the detection of tryptophan and collagen signals, an
 21 unsupervised image segmentation algorithm was used to determine and exclude dermis segments (characterized
 22 by strong collagen-related autofluorescence) thus automatically selecting segments more relevant for the
 23 detection of cancer (BBC)[175]. As an example, on tissue samples of around 1- cm^2 size, a number of spectra
 24 ranging between 500 and 1500 were used to reach 95% sensitivity, thus reducing the total acquisition time to
 25 20-60 min (including 4 min for the autofluorescence collection) (Fig. 28).



26

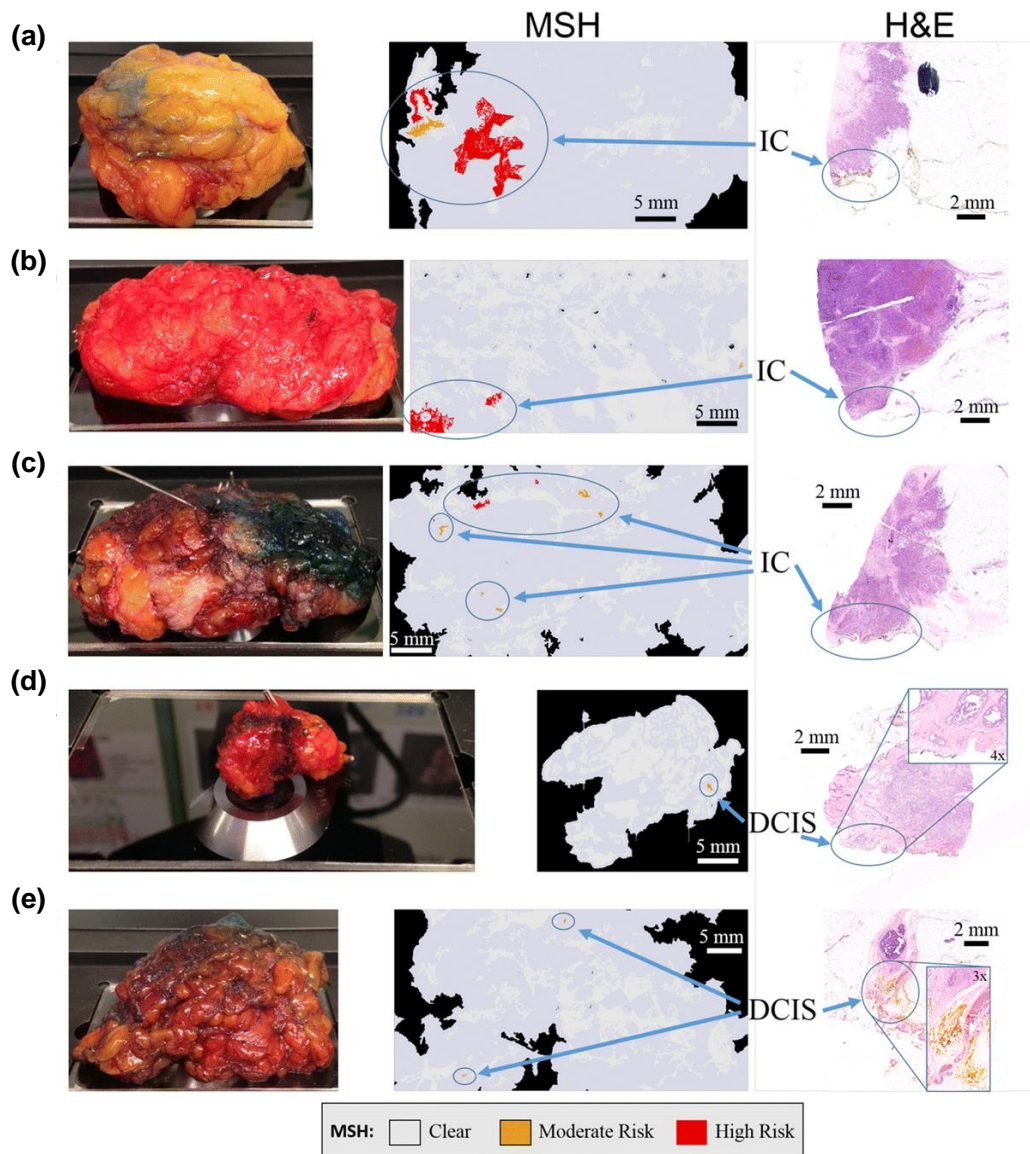
27 **Fig. 28** Example of MSH based on the use of auto-fluorescence to pre-select regions of interest to be further mapped by SR.
 28 a (top) Wide-field auto-fluorescence images of collagen, tryptophan and collagen/tryptophan ratio (from left to right), used
 29 to identify and exclude dermis regions (with high collagen). a (bottom) Segmented image (left) after defining collagen
 30 fluorescence intensity (middle) and segments selected for Raman measurements. a Standard Raman imaging approach

1 obtained by 200 x 200 raster scanning (left) and MSH obtained after Raman measurements on pre-selected segments. c
2 H&E image of adjacent tissue section. Scale bar: 0.5 mm. Adapted with permission from [175]

3

4 A further key advance was the intra-operative Raman-based assessment of surgical margins during breast
5 surgery [177]. In the case of breast surgery, large or very large tissues samples (up to 8x8 cm² area) need to be
6 evaluated during the intra-operative assessment within 30 min, in order to permit the surgeon to evaluate the
7 eventual resection of additional tissue (also called cavity shaves) and reduce the need for re-excision. At the
8 same time, breast cancer, especially the infiltrating variant, may present small and dispersed tumour regions
9 that can be assessed by discrete spatial resolution (10-20 μm). Nothingher and collaborators attempted to
10 answer this need by applying MSH (i.e. the use of autofluorescence to guide Raman spectroscopy) on 51 fresh
11 breast tissue samples (up to 4 x 6.5 cm²) directly obtained from mastectomy from the operating theatre after
12 optimizing and validating the diagnostic algorithm on 71 smaller frozen samples (up to 3.2 x 3.2 cm²). Also, in
13 this case Raman measurement points were identified automatically by autofluorescence-based segmentation
14 and a minimum of two points per segment were selected for Raman measurements using 0.3s as acquisition
15 time. A second Raman acquisition round with doubled acquisition time per spectrum (0.6s) was performed when
16 tumour-related spectra were associated to tissue segments. This approach allowed to analyse the entire surface
17 of large tissue specimens by fewer than 2000 Raman measurements, therefore reducing the acquisition time by
18 up to 200 compared with the typical raster scanning approaches, while still providing good and comparable
19 accuracy performances. The authors introduced a scoring method (i.e. “tumour score”) with optimized
20 thresholds defining moderate or high risk of tumour score to improve the interpretation of emerging results and
21 to easily guide the surgeon about excision strategies (**Fig. 29**). The moderate-risk threshold, used to reduce false
22 negative, made it possible to obtain 91% sensitivity and 83% specificity in the independent validation test on
23 small frozen samples. Finally, fresh, whole breast samples collected and measured immediately after surgery
24 permitted to demonstrate the feasibility of the intra-operative use of the proposed Raman-imaging method,
25 considering an average time of 12-24 min for the whole procedure. This study can be considered one of the
26 current frontiers of SR-based approaches for cancer diagnosis by spectral histopathology, especially considering
27 the unique short acquisition time, compatible with clinical workflow. It is important to note that this has been
28 permitted only by coupling the high chemical specificity and selectivity of Raman spectroscopy (affected by slow
29 acquisition speed) with a complementary approach (i.e. autofluorescence microscopy) to guide the Raman
30 acquisition on selected tissue regions.

31 On the other hand, not all tissues give the chance to clearly pre-select healthy regions as has been done here for
32 skin and breast. The autofluorescence-based approach to pre-select regions of interest is not always accurate
33 and some tumours can be found in regions smaller than 50μm², thus making their recognition by this approach
34 very difficult. In summary, the possibility to obtain spectral information from whole – or relatively large -
35 histological samples with high accuracy and relatively high spatial resolution is still the main challenge for SR
36 microscopy.



1

2 **Fig. 29** Example of MSH on whole breast cancer samples after conservative surgery. **a-c** invasive carcinoma (IC). **d-e** ductal
 3 carcinoma in situ (DCIS). Adapted from [177] (CC-BY 4.0).

4

5 **3.2 Coherent Raman scattering (CRS) imaging**

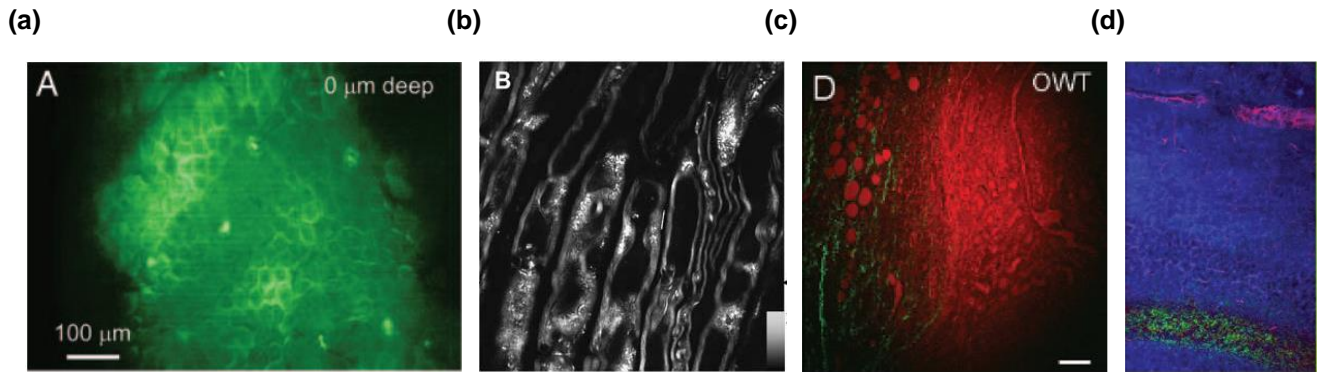
6 As described in detail in **Section 2.2**, CRS imaging, including both CARS and SRS approaches, provides much higher
 7 signals if compared with SR imaging, thus permitting much faster scanning of large samples and imaging speed
 8 up to the video rate. In addition, CRS approaches are intrinsically confocal and allow deep tissue penetration,
 9 without being significantly affected by autofluorescence background. This paved the road to many biomedical
 10 imaging applications that were hardly reachable by other vibrational techniques, including the monitoring of
 11 cellular processes in living cells and living organisms with sub-cellular spatial resolution. At the same time, and
 12 especially when CRS systems were at an early development stage, the fast image acquisition came at the price
 13 of reduced chemical contrast if compared with SR and FT-IR techniques. Several technological and computational
 14 solutions, described in detail in **Section 2.2**, helped to increase the imaging performances and bring them closer

1 and closer to currently unmet clinical needs. In the next paragraphs, we will describe this improvement path and
2 the latest remarkable results obtained in the field of cancer histopathology.

3
4 The first demonstration of CRS imaging for biomedical applications was reported in 1999 by Zumbusch, Holtom
5 and Xie [39], using CARS microscopy to resolve components of living cells. Thanks to nonlinear excitation,
6 enabling intrinsic 3D sectioning, and thanks to high imaging speed, enabling time-lapse imaging on living samples,
7 the first CARS imaging systems could be extensively applied and tested on living cells [178], living animals [179]
8 and ex-vivo thick tissues [180]. These applications are only marginally related to histopathology and have been
9 widely discussed in previous reviews [14,181–183]. Considering that the technical aspects and differences
10 between several proposed CRS imaging systems have been described in detail in **Section 2.2**, we will summarize
11 here only the major results of CRS imaging applied to histopathology, following a chronological criterion, without
12 a precise separation between SRS and CARS approaches.

13 Two CARS studies carried out on fresh tissue samples (skin and spinal cord) by the groups of Xie and Cheng in
14 2005 [180,184], respectively, demonstrated the ability to image tissues of relevant size (squares between 100 to
15 500 μm) at very high speed ($< 1\text{ s}$ per image) and spatial resolution ($< 0.5\ \mu\text{m}$), and with satisfactorily high focal
16 depth ($> 100\ \mu\text{m}$) and axial resolution ($< 2\ \mu\text{m}$) (**Fig. 30a,b**). In addition, both studies demonstrated the capability
17 of CARS to collect strong signals in the *epi*-direction – more compatible for some tissue-based studies - without
18 losing much signal if compared with the standard forward-detection configuration. A few years later, in 2007, Le
19 et al. started cancer studies by CARS microscopy focusing on the mechanisms that link obesity to tumorigenesis
20 [185].

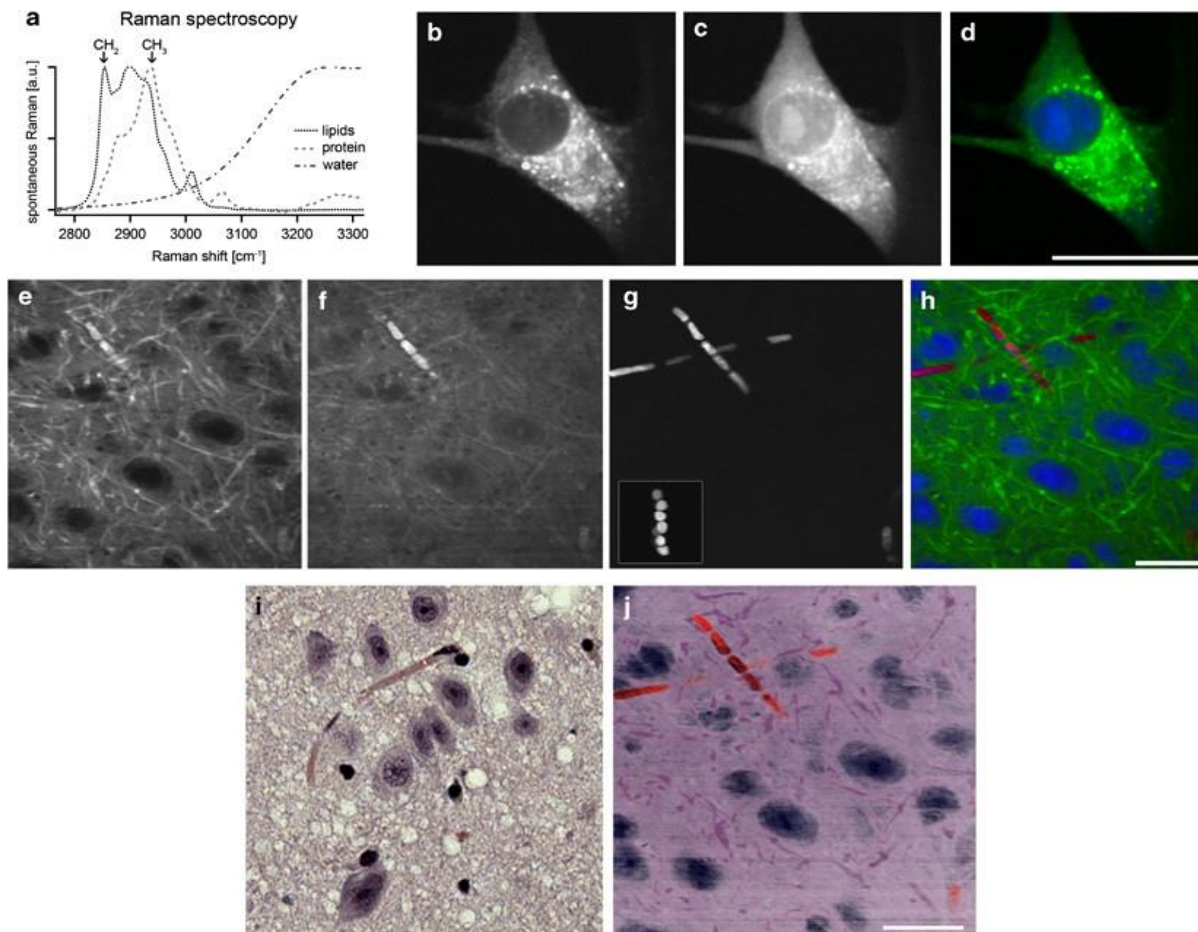
21 Most CARS studies, especially those at the early stage, were focused on lipids detection and therefore applied to
22 the investigation of lipid-rich tissues (e.g. brain, breast or skin) and of diseases where lipids dysregulation is
23 implicated (obesity and tumorigenesis). This is due to the abundancy of CH stretching bonds in lipid molecules
24 associated with strong resonant peaks (i.e. CH_2 stretching band, at $2845\ \text{cm}^{-1}$), where the non-resonant
25 background (NRB) is less affecting the spectral features, as compared to the fingerprint spectral region (see more
26 details in Section 2.2). At the same time, lipids detection might not be sufficient to discriminate relevant
27 biological features and pathological morphologies. For this reason, before the technical evolution of CRS
28 methods – in particular SRS and broadband CRS – some groups coupled CARS with other nonlinear microscopy
29 techniques such as second harmonic generation (SHG) and two-photon excitation fluorescence (TPEF)
30 microscopy, exploiting their high optical and technological compatibility (one of the two pulses used for CRS can
31 be employed for SHG and TPEF). **Fig. 30c** shows one of the first CARS images on histologic tissue sections ($5\ \mu\text{m}$
32 thick), reported by Le et al. [185] for the study of adipocytes in mammary gland tumor tissue. In this case,
33 mammary gland sections were studied by CARS to detect lipids (red), monitoring the symmetric CH_2 stretch
34 vibration ($2840\ \text{cm}^{-1}$), and by SHG to detect Type I collagen fibrils (green). A few years later, also Meyer et al.
35 studied brain tumor tissue sections (20 to $50\ \mu\text{m}$ thick) by coupling CARS, TPEF and SHG [186] (**Fig. 30d**). CARS
36 was used to detect white matter lipids; TPEF was used to detect the autofluorescence of nicotinamide adenine
37 dinucleotide (NAD), elastin, keratin and other molecules relatively abundant in the grey matter; SHG was used
38 to selectively display the collagen contained in the arachnoid membrane, which envelops brain structures.



1
2 **Fig. 30** Early examples of CARS images. **a** CARS image of living mice acquired by selecting the band at 2845 cm^{-1} (lipids).
3 Adapted from [180]. Copyright (2005) National Academy of Sciences. **b** CARS image of axons in a guinea pig spinal cord
4 sample by selecting the band at 2840 cm^{-1} . Adapted with permission from [184]. **c** multimodal image of histologic section
5 from rat tumour. Lipid band in *red* and SHG of collagen fibrils in *green*. Adapted with permission from [185]. **d** brain tumour
6 tissue section studied by a multimodal approach including CARS, TPEF and SGH. Adapted with permission from [186].

7 In parallel, between 2007 and 2009, SRS imaging systems were developed [40,41,187,188] permitting to obtain
8 better vibrational contrast and to overcome some limitations of CARS, first of all the spectral distortion
9 originating from the NRB, as better detailed in **Section 2.2**. Following these technical innovations, Saar *et al.*, in
10 2010, imaged skin of living mice in video-rate frames by showing signal coming from vibrations of lipids (CH_2
11 stretching, 2845 cm^{-1}), water (OH stretching, 3250 cm^{-1}) and proteins (CH_3 stretching, 2950 cm^{-1}) [44].

12 In 2012, Freudiger *et al.* reported multicolour SRS imaging, selecting vibrations from lipids, proteins, water
13 combined with two-photon absorption from haemoglobin of red blood cells, aiming at reproducing H&E staining
14 patterns on fresh 1-mm-thick slices [189]. In this case, the selected molecular features are imaged in different
15 scans, by tuning the system to the corresponding frequencies and by further overlapping the different images
16 using image processing tools. This is a common approach for single-frequency CRS systems that do not provide
17 complete spectra for each imaged pixel, as is the case for SR and broadband CRS imaging systems (described
18 later). The authors were able to obtain images with good contrast from fresh mouse brain tissues, as shown in
19 **Fig. 31**. For a better comparison, the merged images were coloured using pink, blue-purple and red tones,
20 producing images resembling H&E-stained sections, with satisfactory results. After proving the image quality,
21 four common brain pathologies including glioblastoma, metastases, demyelination, and stroke, were
22 investigated, and successfully compared with H&E images.



1

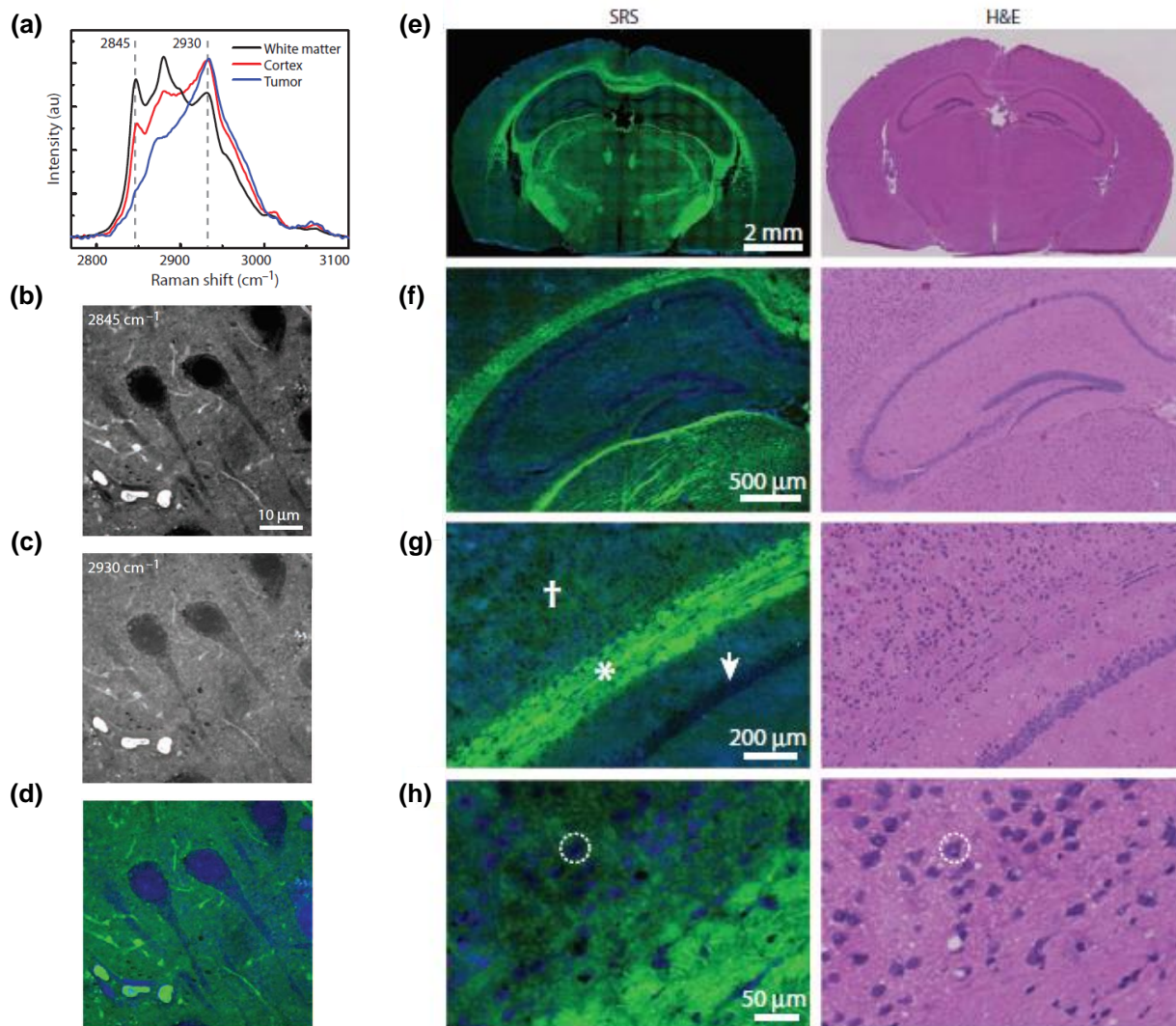
2 **Fig. 31** Early examples of SRS images of cells and fresh 1 mm tick mouse brain tissue slices. **a** vibrational spectra of lipid,
 3 proteins and water. **b, c** SRS image of live neuronal cells by using the Raman shifts at 2845 cm^{-1} (lipids) and at 2940 cm^{-1}
 4 (proteins), respectively. **d** false colour image produced by merging the lipid signals (green, image **b**) with difference
 5 between proteins and lipids (blue, image **c** minus image **b**). **e, f, g** SRS image of fresh *ex-vivo* brain tissue acquired selecting
 6 the band of lipids at 2845 cm^{-1} (**e**), the band of proteins at 2940 cm^{-1} (**f**), and using two-photon adsorption of haemoglobin
 7 (**g**). **h** false colour image generating by merging images **e-g**. **i** H&E stained adjacent tissue slice. **j** same multicolor image as
 8 (**h**) but using a H&E pseudo-color scheme. Scale bar: $25\text{ }\mu\text{m}$. Adapted with permission from [189].

9

10 In the meantime, Chowdary *et al.* [190] reported an interesting hybrid solution derived by coupling CARS and
 11 spectral interferometry (called spectral reconstructed nonlinear interferometric vibrational imaging (SR-NIVI)).
 12 This system can be considered as a broadband CARS apparatus because it provides spectra from 2800 to 3100
 13 cm^{-1} that can be used to extrapolate band intensities of specific molecular vibrations. The authors demonstrated
 14 the ability to distinguish carcinoma from healthy tissue in rat mammary tumour model, used as a proof of
 15 concept, even if at relatively low scan rate (1 ms per pixel, followed by averaging over ten images) and lower
 16 spatial resolution ($5\text{ }\mu\text{m}$), if compared to other CRS approaches tested at that time. Another broadband multiplex
 17 CARS approach, reported by Pohling *et al.*, was tested on fresh mouse brain tissues showing the exceptional
 18 possibility – at that time - to record a full (biologically relevant) spectrum, ranging from 500 to 3400 cm^{-1} , thus
 19 covering both the fingerprint and CH regions [59]. Sample areas of $100\times 100\text{ }\mu\text{m}$ were raster scanned with step
 20 size of $1\text{ }\mu\text{m}$ and acquisition time per pixel between 20 and 200 ms . This configuration, coupled with PCA,
 21 permitted to distinguish grey and white matter as well as different brain tissue layers. On the other hand, the

1 spectral information in the fingerprint region was highly affected by background noise and the imaging speed
2 reached up to 5h/mm², still far from being compatible with clinically relevant applications such as intraoperative
3 tissue assessment.

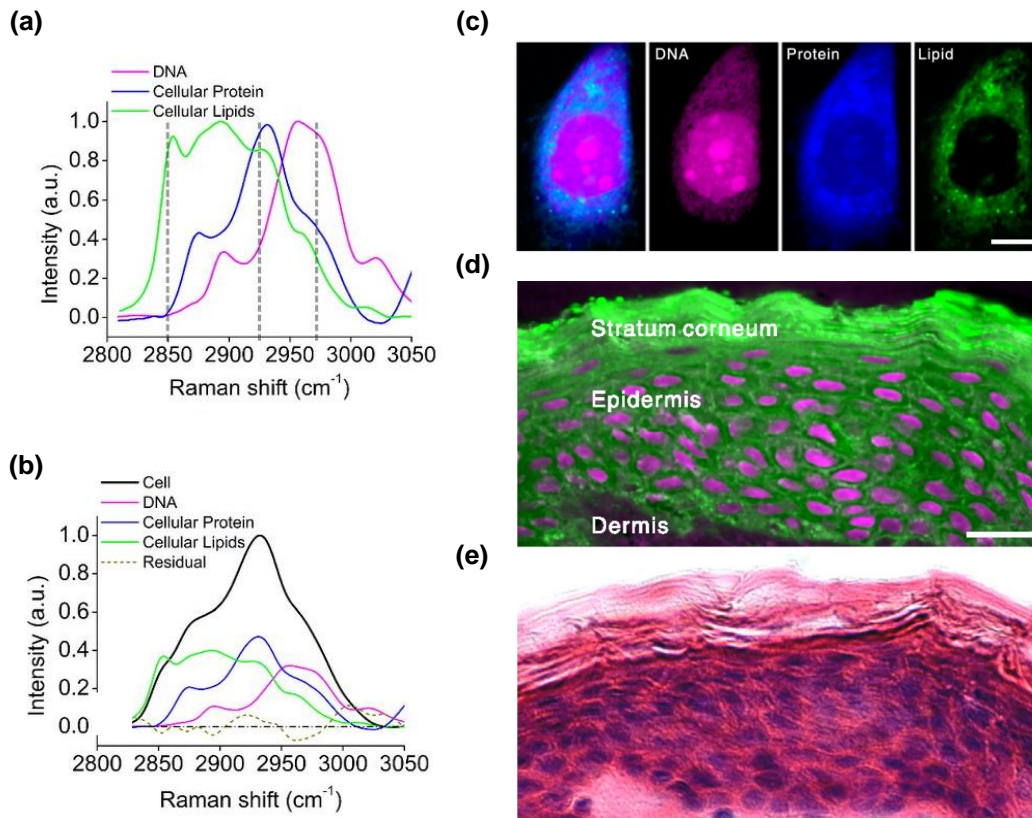
4 Following the demonstration of SRS microscopy, Xie and collaborators started in 2013 to put much effort towards
5 label-free, fast, and accurate cancer assessment at a clinical level. Ji *et al.* reported the use of an SRS microscope
6 in epi-detection mode to perform two-color imaging at 2845 cm⁻¹, which is a suitable region for lipids and
7 therefore for white matter observation, and at 2930 cm⁻¹, which is generally related to proteins and offers good
8 contrast in cellulated parts of brain cortex and tumor [191] (**Fig. 32**). The linear combination of these two
9 frequencies permitted to extract lipid and proteins contributions and to produce two-colors (blue and green)
10 images with good structural and chemical contrast. From the translational point of view, it is important to note
11 that two-color brain images were collected from the study of thin (10 μm), unstained, snap-frozen sections,
12 which were further stained by H&E for comparison. This experimental configuration is basically identical to the
13 protocols used for the intraoperative tumor margin assessment using snap-frozen sections, with the important
14 difference that SRS images do not require any type of staining. As a next step, the authors tested the possibility
15 to detect glioma (brain tumor) by SRS, approaching for the first time a rigorous and relatively extended validation
16 step. In details, seventy-five 350×350 μm² fields of views (and corresponding seventy-five H&E fields of views),
17 collected from 6 mouse brains with glioma, were visualized and blindly classified by three pathologists, yielding
18 to 450 observations. By the observation of SRS two-colors images, the pathologists were asked to distinguish
19 three different tissue categories: 1) normal hypercellular tissue; 2) infiltrating glioma; and 3) high-density glioma
20 (**Fig. 32**). Only very few images were misclassified, and the overall accuracy was 99.5%. Furthermore, also *ex-vivo*
21 human brain tumor samples were studied after surgical excision revealing similar image contrast as observed in
22 mice. This was the first evidence that SRS microscopy can be used for diagnostic purposes for the intraoperative
23 detection of cancer. In this context, Uckermann *et al.* reported CARS images of mouse brain tumor (glioblastoma)
24 by only selecting the CH₂ stretching vibration band (2850 cm⁻¹) showing that this band inversely correlates with
25 tumor features, i.e. producing darker regions in sick areas due to a lower CARS signal [192]. In addition, they also
26 showed that highly cellulated regions, like normal hippocampus, produce a significantly higher CARS signal, thus
27 suggesting that the observed decline of CARS signal is a common and intrinsic tumor feature, compared to both
28 (healthy) grey matter and white matter, mostly associated with tumor-induced changes like nuclear size and
29 nuclear density.



1
2 **Fig. 32** SRS images of mouse brain frozen sections. **a** vibrational spectra of white matter, cortex and tumour. The marked
3 frequencies are those used for two-colour SRS imaging. **b, c** SRS images using lipid signals (2845 cm^{-1}) and protein signals
4 (2930 cm^{-1}), respectively. **d** multicolour image produced by a linear combination of images **b** and **c**. **e-h** SRS multicolour
5 images (left) accompanied by images of tissue slides stained with H&E after SRS measurements. From **e** to **h**, different
6 imaging size was used, from full coronal section to single neurons. imaging scale was reduced till visualizing single
7 neurons. Adapted with permission from [191].

8
9 The aforementioned SRS imaging studies mostly exploited the vibrational band of lipids ($\sim 2850\text{ cm}^{-1}$) or, in some
10 cases, those of proteins ($\sim 2930\text{ cm}^{-1}$) and/or water ($\sim 3250\text{ cm}^{-1}$), to produce pseudo-color tissue images and to
11 study or discriminate cancer. On the other hand, nucleic acids, and in particular DNA, were rarely included among
12 the selected “colors”, mostly due to the intrinsically low scattering properties of nucleic acid bonds in both the
13 fingerprint and CH stretching regions. This has been a limitation considering the functional and structural
14 importance of DNA (and of cellular nuclei) in tumors and, more generally, in all biological systems. At that time,
15 only one study attempted to visualize the DNA phosphate peak in cultured cells detected in the fingerprint region
16 but with scarce contrast [193]. In 2015, Lu *et al.*, from the Xie group, extracted pure Raman spectra of DNA from
17 cellular extractions and pure molecules, thus proving that SRS is able to detect DNA, in particular the CH

1 vibrational signal from deoxyribose (around 2956 cm^{-1}), which differs from the CH response of proteins and lipids
 2 [194]. Then, three Raman shifts (2850 , 2926 and 2967 cm^{-1}) were selected to optimize the detection of the three
 3 biological species (i.e. lipids, proteins and DNA), and linear decomposition approaches were applied after using
 4 premeasured calibration matrixes (**Fig. 33**). This study resulted in the first DNA detection in live cells undergoing
 5 division, in living mouse skin to follow cell division and, finally, in human skin with diagnostic purposes.

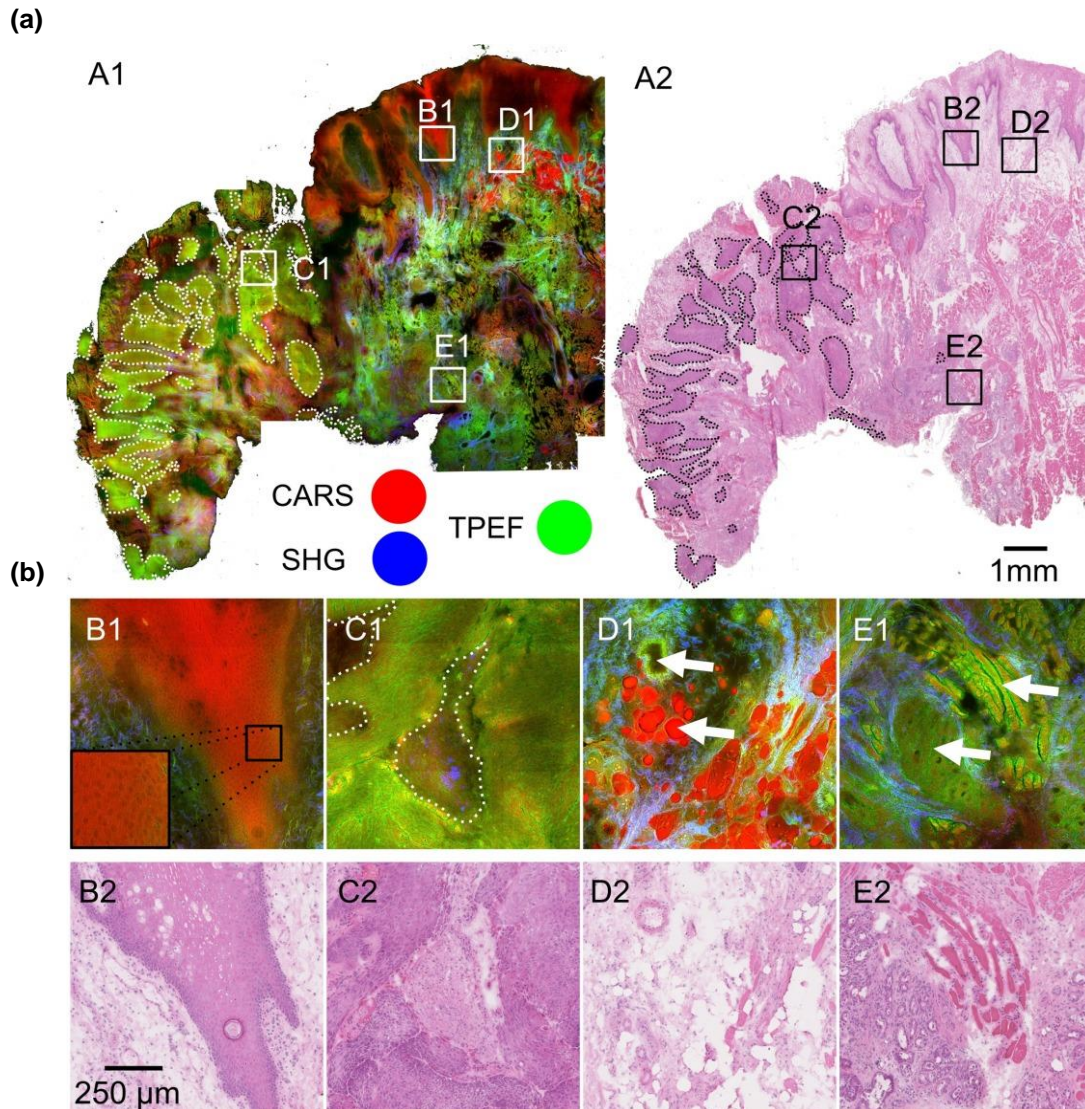


6
 7 **Fig. 33** SRS images of DNA (magenta), proteins (blue) and lipids (green). **a** vibrational spectra of DNA, proteins and lipids
 8 extracted from HeLa cells. **b** Raman spectrum of cell homogenate (black) and linear fitting of DNA, proteins and lipids
 9 signals demonstrating that 90% of these components accounts for around 90% of the total CH stretching vibration of the
 10 cell. **c** SRS images of live cells using the colour scheme mentioned in **a**, including an image presenting the merge of the
 11 DNA, Protein, and lipid channels (left). Scale bar $10\ \mu\text{m}$. **c** SRS images of human skin ($20\ \mu\text{m}$ tick), accompanied by H&E-
 12 stained section (**e**), showing typical cytologic features. Scale bar $20\ \mu\text{m}$. Adapted with permission from [194].

13
 14 In 2016, the SRS-based assessment of 41 brain tumors specimens from 12 patients represented the first clinically
 15 relevant study in the field of CRS-based diagnostics [195]. Both $12\text{-}\mu\text{m}$ thick (snap-frozen) and 1-mm thick (fresh)
 16 brain slices were studied by an SRS microscope able to image $350\times 350\ \mu\text{m}$ fields of view in approximately 1s with
 17 $\approx 0.68\text{-}\mu\text{m}$ transverse resolution. Here, the SRS signals from proteins (2940 cm^{-1}) was obtained after subtraction
 18 of half the signal from lipids (2850 cm^{-1}) and these two channels were imaged as blue and green, respectively. In
 19 parallel, a third channel (magenta), was obtained by selecting the Raman-silent region around 2800 cm^{-1} and
 20 assigned to hemoglobin. Typical morphological features were visible in the SRS image when compared with H&E-
 21 stained sections, including cell density (hypercellularity), necrosis, collagen, and vascular proliferation.
 22 Noteworthy, some histological features, like the boundary between the gray and the white matter, were better
 23 visible in the SRS images than in H&E stained tissue images due to the removal of lipids during sample preparation

1 (i.e. including solvents) before standard staining protocols. Another important observation is that nuclei from
2 individual cells were clearly visible in both SRS and H&E images, even without selecting the specific wavenumber
3 associated with DNA, as optimized by the same authors in a previous study [194].

4 Simultaneously, also CARS imaging was successfully evolved and applied to histopathology, mostly thanks to the
5 integration of CARS, TPEF and SHG, for the reasons mentioned above. The Popp group, in a strong collaboration
6 with clinicians, applied CARS and other nonlinear microscopy approaches for the diagnosis of brain cancer, skin
7 cancer and laryngeal cancer [196–198]. In particular, in 2016, Heuke *et al.* reported the multimodal study of 30
8 frozen tissue sections (20- μ m-thick) from head and neck cancer patients aiming to validate the potential use of
9 nonlinear microscopies – including CARS – as diagnostic tools [197]. Tissue specimens as large as 1.5x1.5 cm were
10 imaged using the three modalities in around 1.5 hours with a lateral step size of 220nm (**Fig. 34**). Multimodal
11 images revealed that cancer regions were mainly associated to an increase of TPEF – most likely from increased
12 cellular NADH – while other regions generally showed higher intensity of CARS and SHG, respectively associated
13 to lipids and collagen. The authors attempted to use TPEF to SHG or TPEF to CARS signal ratios from the whole
14 tissue sample to distinguish malignant features and verified that the TPEF to CARS ratio significantly differs
15 between healthy and cancer specimens. At the same time, this approach was not accurate enough for an
16 automated prediction and for the spatially defined assignment of malignant regions. For this reason, statistical
17 properties of the intensity histogram of the multimodal images (mean, standard deviation, smoothness,
18 uniformity, entropy, etc) were calculated for each imaging modality. A total of 18 image features were then used
19 to classify all 30 multimodal images by LDA. As a reference, a trained pathologist assigned a distinct tissue type
20 (i.e. 8 different classes including benign and cancer tissue) to each region. Overall, the pixel-weighted average
21 accuracy for the identification of cancer vs healthy epithelium vs other tissue types vs background was found to
22 be 74%.

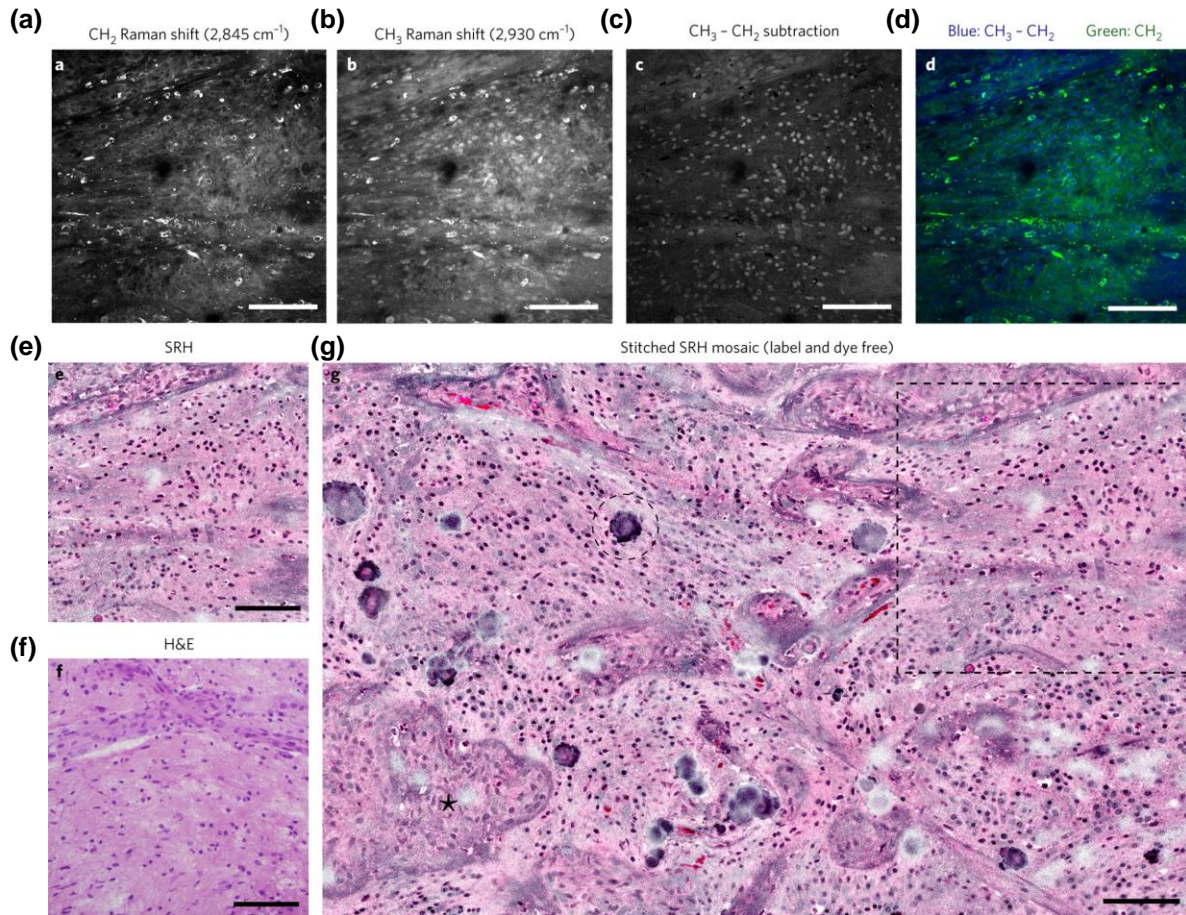


1
2 **Fig 34** Multimodal image of a large (1.5 x 1.5 cm) laryngeal cancer specimen. **a** Coherent anti-Stokes Raman scattering
3 (CARS), second-harmonic generation (SHG), and two-photon excited fluorescence (TPEF) are displayed in false colours as
4 red, blue, and green, respectively (left). The contiguous H&E-stained slice is also reported (right). Cancer regions are
5 framed by with dotted lines. **b** different regions, characterized by different histological features and indicated also in **a**, are
6 reported. Adapted with permission from [197].

7
8 Even if the accuracy reported by Heuke *et al.* was not comparable with the diagnostic performances currently
9 obtained by pathologists on H&E-stained slices, this was one of the first studies attempting to use the spatial
10 information and the identification of specific regions to automatically classify each sample. A few years later, in
11 2019, the same research group presented a new semantic segmentation approach based on fully convolutional
12 neural networks to perform a pixel-wise classification enabling faster and more reliable classification of cancer
13 specimens [199]. In details, 114 images from frozen tissue slices collected from 12 patients were studied ([197])
14 and the overall recognition of four different diagnostic classes was of 86.7%.

1

2 In 2017, a collaboration between Harvard University, University of Michigan medical school and Invenio Imaging
3 Inc. reported the first demonstration of SRS microscopy in clinical setting using unprocessed specimens from 101
4 neurosurgical patients [200]. The consortium focused its effort on improving intraoperative assessment of brain
5 lesions by use of SRS microscopy to provide rapid, reproducible and accurate diagnostic images to support
6 surgical decision making. A portable fiber-based microscope was designed avoiding any optical hardware
7 incompatible with the clinical setting. The two synchronized narrow-band laser pulses (pump and Stokes) were
8 generated by a broad-band supercontinuum derived from a single fiber-oscillator. The SRS microscope enabled
9 an acquisition time of 2 sec for 400x400um frames with step size of 390 nm and axial resolution of 1.8 μm (**Fig.**
10 **35**). The two Raman shifts associated to CH_2 bonds, mainly related to lipids (2845 cm^{-1}), and to CH_3 bonds, mainly
11 related to proteins (2930 cm^{-1}), were selected; the images were then reconstructed using the signal from CH_2
12 bonds as a first channel and the signal from CH_3 bonds minus that from CH_2 bonds as a second channel, similar
13 to what was already reported [195]. In addition, instead of using standard and previously used green and blue
14 colors to represent the chemical contrast given by proteins and DNA, respectively, here the authors used the
15 eosin-like reddish-pink and the hematoxylin-like dark-blue-violet colors to generate virtual H&E staining. The
16 overall time for the acquisition, stitching and recoloring was ≈ 5 min per millimeter square.
17 A total of 12870 frames were collected from 101 patients, corresponding, on average, to around 20 mm^2 and
18 around 100 frames per patients. For each patient, fresh tissue samples (approx. 3 mm thick) were collected and
19 analyzed after standard squash preparation reducing the thickness to $120\text{ }\mu\text{m}$. When available, part of the tissue
20 was fresh frozen and examined using standard diagnostic approaches as a reference. It is important to note that
21 the squash preparation, used here for SRS imaging, is not commonly used in standard diagnosis, not even when
22 performing SR and other vibrational-based imaging approaches. This approach seems to be promising because
23 it does not require sample fixation/freezing and cutting, thus saving time, and avoiding any type of fixation or
24 any procedure that may alter the original tissue composition. On the other hand, when using this approach, the
25 exact comparison with adjacent frozen slices routinely stained with H&E is not feasible and, as claimed by
26 authors, some architectural features (e.g. microvascular structures) may not be well represented.



1
2

3 **Fig. 35** SRS-based virtual staining of fresh human brain sections obtained intraoperatively. **a-c** SRS images produced by the
 4 integration of Raman bands of lipids and proteins, respectively, or by the subtraction of **b** from **a**, thus mainly showing cell
 5 nuclei **(c)**. **d** multicolour image derived by the combination of **b** and **c**. **e** virtual staining applied to image **d**, to be
 6 compared to a similar section of brain tumour stained by H&E procedure **(f)**. **g** mosaic image of several field of view of
 7 imaged tissue, including the field of view reported in panel **e** (dotted square). SRH: SRS-based histology. Scale bar: 100 μm .
 8 Adapted with permission from [200].

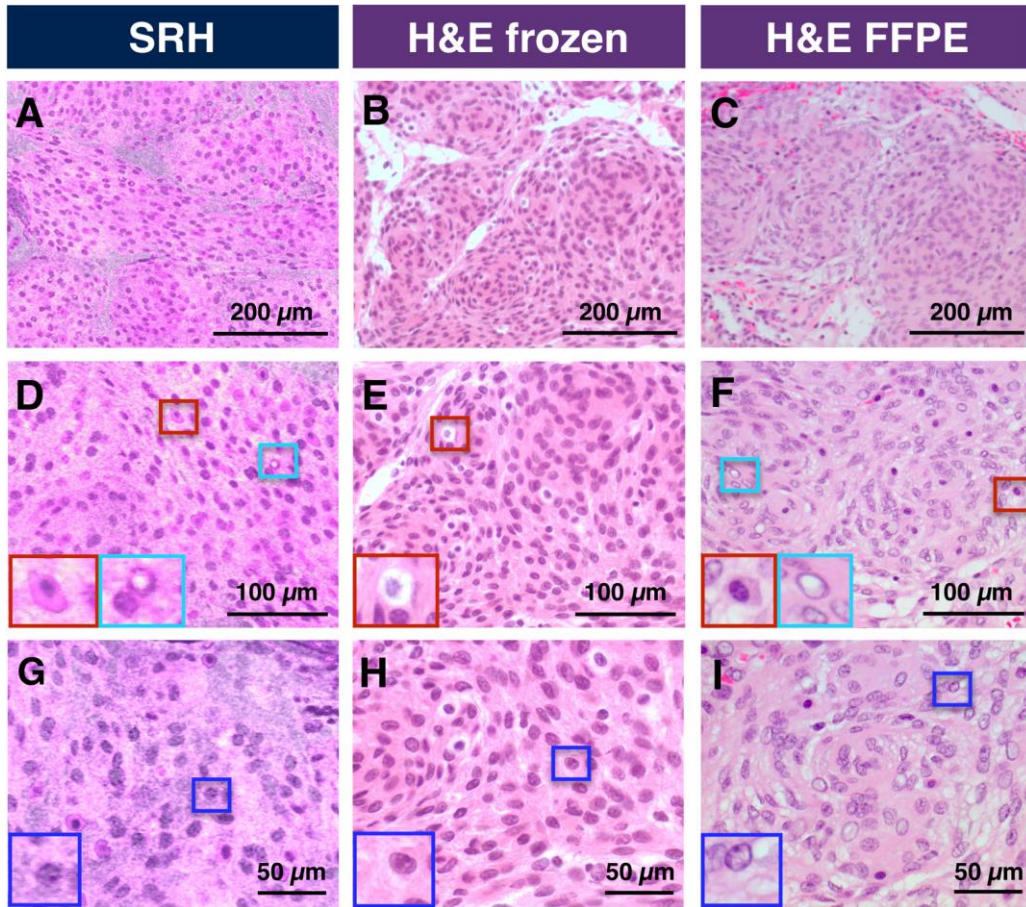
9

10 After confirming the detection of relevant diagnostic-histological features and of typical intratumoral
 11 heterogeneity, quantitative SRS-based diagnosis was evaluated. SRS images from 30 neurosurgical patients were
 12 collected and compared with routine diagnosis performed on adjacent fresh frozen sections. Then, three
 13 certified neuropathologists were asked to provide intraoperative diagnosis based on both SRS and conventional
 14 H&E (frozen) images. The concordance (Cohen's kappa (k)) of diagnostic performances when utilizing SRS versus
 15 standard H&E was very high for the identification of brain tumor lesions ($k = 0.84$ and 1.00 , respectively) and for
 16 the definition of the final diagnosis (i.e. cancer subtype) ($k = 0.89$ and 0.92 , respectively). Overall, the accuracy of
 17 SRS-based diagnosis was 98% in distinguishing pathological lesions and 92.2% in making the correct diagnosis.
 18 Finally, the task of interpreting histopathologic SRS images has been also entrusted to machine-learning
 19 approaches, to verify the possibility of a rapid, objective and automated tool for diagnosis and brain-tumor
 20 surgery. More than 12000 frames ($400 \times 400 \mu\text{m}$ each) from 101 patients were analyzed by a multi-purpose image
 21 classification (called WND-CHARM) [201] that utilized 2919 image features to automatically classify each frame

1 into four diagnostic classes by a machine learning (multilayer perceptron (MLP)) approach. The frames (~3000)
2 from 30 patients that were evaluated by neuropathologist for SRS and H&E comparison were used as a test set
3 using leave-one-out validation. The remaining frames (~7000) were the training set. The result was that cancer
4 vs benign lesions were detected with 100% accuracy by the machine learning approach when considering frames
5 from the same patient sample. In addition, the accuracy for classifying individual frames (cancer vs benign) was
6 close to 95% (94.1% specificity, 94.5 sensitivity). The final diagnosis (i.e. including cancer subtype) at sample level
7 was 90% accurate if compared with the diagnosis provided by pathologists. The same SRS-based approach was
8 further used for the intraoperative diagnosis of pediatric brain tumors with similar results [202].

9 Fu and collaborators also performed SRS-based intraoperative assessment of tumours by applying similar
10 approaches, including pseudo-H&E recolouring strategy and the use of fresh tissue samples pressed between
11 two glass slides, on brain (skull base) tumours [203]. In addition to what was previously reported by Hollon and
12 Orringer [200,202], here authors emphasized the comparison between standard and SRS-based histopathology
13 by validating every step of the typical diagnostic workflow (histological features, differential diagnosis and final
14 diagnosis) . As an additional added value, for each of 16 patients included in the study, three types of samples
15 (and corresponding images) were obtained and examined by three pathologists with no training on SRS-based
16 images: 1) virtually-H&E-stained SRS images from fresh tissue; 2) H&E images of the same specimen used for SRS
17 images, after adequate fixation by FFPE protocols and standard staining; 3) H&E-stained images from frozen
18 sections obtained during surgery, following the standard protocol used for intraoperative assessment in clinics
19 (**Fig. 36**). The reason and advantage of using two reference samples is that H&E images from fixed tissue (sample
20 n.2) represent the best diagnostic preparation considering image quality, used for routine diagnosis but not
21 compatible with intraoperative assessment, due to the long preparation time; on the other hand, H&E images
22 from frozen sections (sample n.3) represent the real SRS-image competitor, because they are the ones currently
23 used for intraoperative assessment even if they are of lower quality due to scarce fixation and fast staining.
24 Neuropathologists were able to detect histopathological features with almost perfect concordance (95%,
25 average relative accuracy) when compared with conventional modalities. Differential and final diagnosis were
26 performed with average accuracy of 94 and 86%, respectively. Noteworthy, this study also underlined the
27 additional diagnostic chemical information intrinsically generated by SRS, especially about lipid and protein
28 content, that cannot be extracted by the sole H&E images if not supported by additional labelling procedures
29 (immunostaining). Finally, this study also suggests that virtually stained H&E images, although very useful to
30 promote acceptance of SRS by the pathologists, are not always able to represent the chemical contrast, especially
31 the lipid content, revealed by SRS but not perfectly represented by H&E-based approaches, which are intrinsically
32 not optimized for the detection of lipids.

33



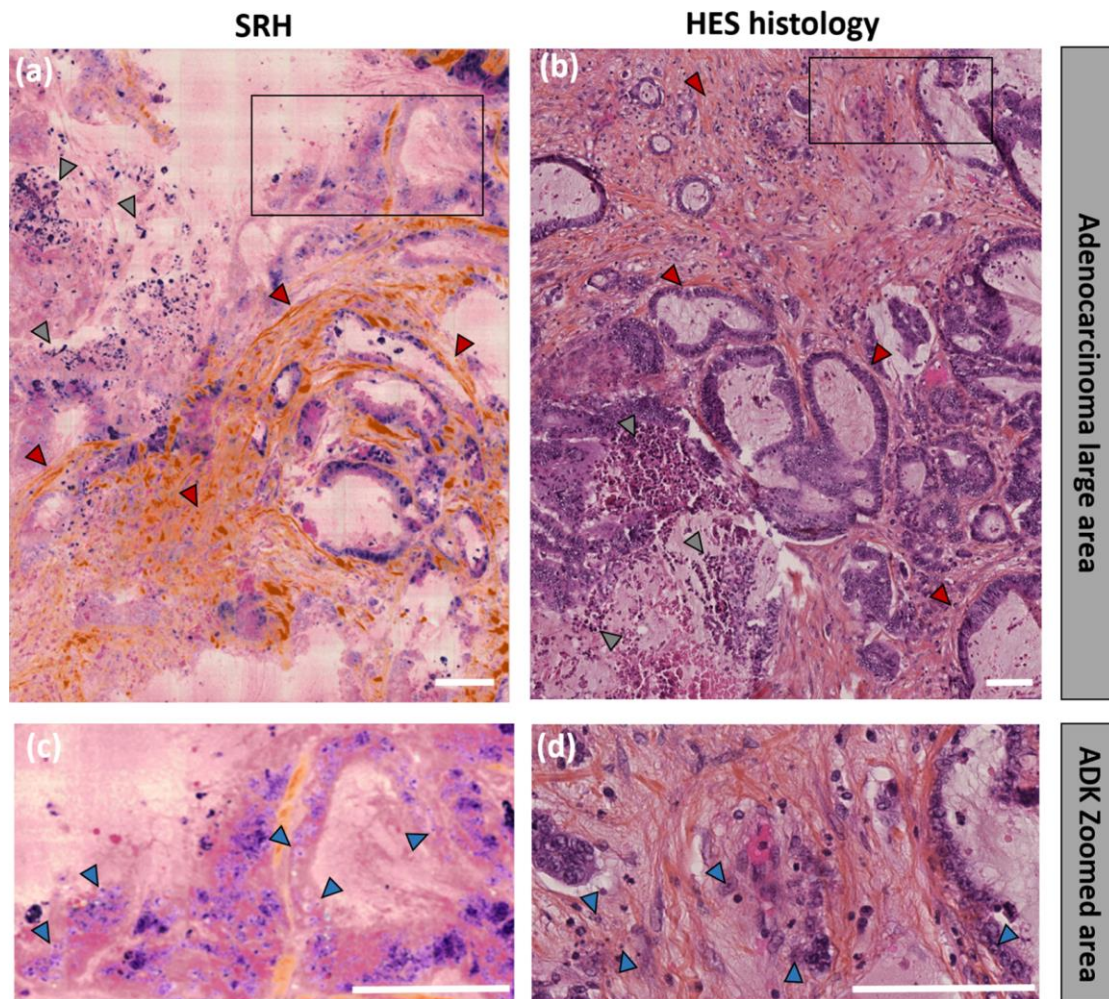
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2 **Fig. 36** Comparison of SRS-based histology (SRH) and H&E-stained slides prepared from frozen or formalin fixed paraffine
 3 embedded (FFPE) brain tissue samples. **a-c** SRS images produced by the integration of Raman bands of lipids and proteins,
 4 respectively, or by the subtraction of **b** from **a**, thus mainly showing cell nuclei (**c**). **d** multicolour image derived by the
 5 combination of **b** and **c**. **e** virtual staining applied to image **d**, to be compared to a similar section of brain tumour stained
 6 by H&E procedure (**f**). **g** mosaic image of several field of view of imaged tissue, including the field of view reported in panel
 7 **e** (dotted square). Scale bar: 100 μm . Adapted from [203] (CC-BY 4.0).

8 SRS-based spectral histopathology was also used by Ji and collaborators for the diagnosis of laryngeal squamous
 9 cell carcinoma, also thanks to the implementation of CNN approaches [204]. The system combined two-color
 10 SRS with SHG to mainly represent lipids (2845 cm^{-1}), proteins (2930 cm^{-1}) and collagen fibers (SHG). A total of 78
 11 patients were involved in the study and two types of samples were selected: a) 80 frozen sections ($20\text{ }\mu\text{m}$ thick,
 12 between two coverslips) accompanied by an equal number of adjacent H&E stained slices, were obtained from
 13 15 patients and b) 78 fresh tissue samples (0.5mm thick, between two coverslips) were obtained from all 78
 14 patients. Frozen sections were used to assess the concordance between SRS and H&E images ($k = 0.90$ and 94 ,
 15 respectively) as reported by three independent pathologists, and the diagnostic accuracy when using SRS-images
 16 only ($>90\%$). Fresh surgical specimens were used to evaluate the performance of SRS imaging on tissue samples
 17 free from freezing and sectioning, thus avoiding possible artifacts and/or alterations, and to mimic label-free and
 18 real-time intraoperative histology virtually excluding any tissue sample preparation. In this case, SRS images from
 19 fresh tissues were not directly compared with adjacent H&E images, as done for the frozen sections, but they
 20 were simply assigned as “normal” and “cancerous” according to the standard diagnosis (performed on separated
 21 and non-adjacent H&E tissue samples) and used to train and test the deep-learning-based (CCN) model. Then,
 22 45 out of 78 samples (both normal and cancerous) were used as model training and the remaining 33 were used

1 as test set. A total of 18750 small tiles from the first 45 samples were randomly divided in five groups. Four
2 groups were used for the training (15000) and the remaining one was used for validation (3750). A 5-fold cross-
3 validation was performed by repeating 5 times the classification/validation process selecting each time different
4 groups of data. The results showed an overall accuracy of 95.9%. Then, the remaining 33 untrained samples (test
5 set) were differentiated by the previously trained model with 100% accuracy.

6 With the goal to make SRS-based imaging faster and more compatible with clinical and diagnostic setting,
7 Rigneault and collaborators combined SRS, SHG and, eventually, CARS and TPEF, for the detection of colon and
8 pancreas tumors in patients samples [205]. The multimodal non-linear optical microscope was applied to both
9 fresh frozen thin (15 μ m) tissue slices and fresh tissue pieces (~1mm size) squeezed between two glass coverslips,
10 thus reaching a thickness of around 100nm. Authors used two imaging modalities. The first, named λ -switch, was
11 used to sequentially detect SRS signals related to lipids (2845 cm^{-1} , CH_2) and proteins (2930 cm^{-1} , CH_3),
12 respectively, and SHG signals. This configuration permitted to scan a 1mm x 1mm tissue region in around 50 min
13 (40 μ s pixel dwell time x 3 accumulations) with 0.4 μ m step size (**Fig. 37**). The second modality, named frequency
14 modulated-SRS (FM-SRS), permitted to detect, simultaneously, the signal corresponding to the nuclei (i.e. the
15 ratio between 2845 and 2930 cm^{-1} signal) combined with the signal from collagen, by SHG, and the signal related
16 to cell bodies (by TPEF or CARS), allowing to generate 1mm x 1mm tissue region in around 25 minutes. Also here
17 efforts have been spent to produce false color images to simulate histology staining, similar to what has been
18 proposed by Orringer and colleagues [200]. In this case, also collagen signals obtained by SHG were virtually
19 added as orange color thus mimicking hematoxylin, eosin and saffron (HES) staining, like standard H&E but also
20 able to distinguish collagen. In summary, this study reports the first application of stimulated Raman histology
21 on gastro-intestinal tissues and demonstrates the possibility to obtain virtual HES staining with timing almost
22 compatible with operator room workflow.



1

2 **Fig. 37** SRS-based histology (SRH) compared with haematoxylin, eosin and saffron (HES) histopathology. **a** SRH image of
 3 human colon adenocarcinoma compared to HES image from the same region **(b)**. **c,d** regions zoomed on the ROIs defined
 4 in **(a,b)**. Scale bar: 100 μ m. Adapted from [205] (CC-BY 4.0).

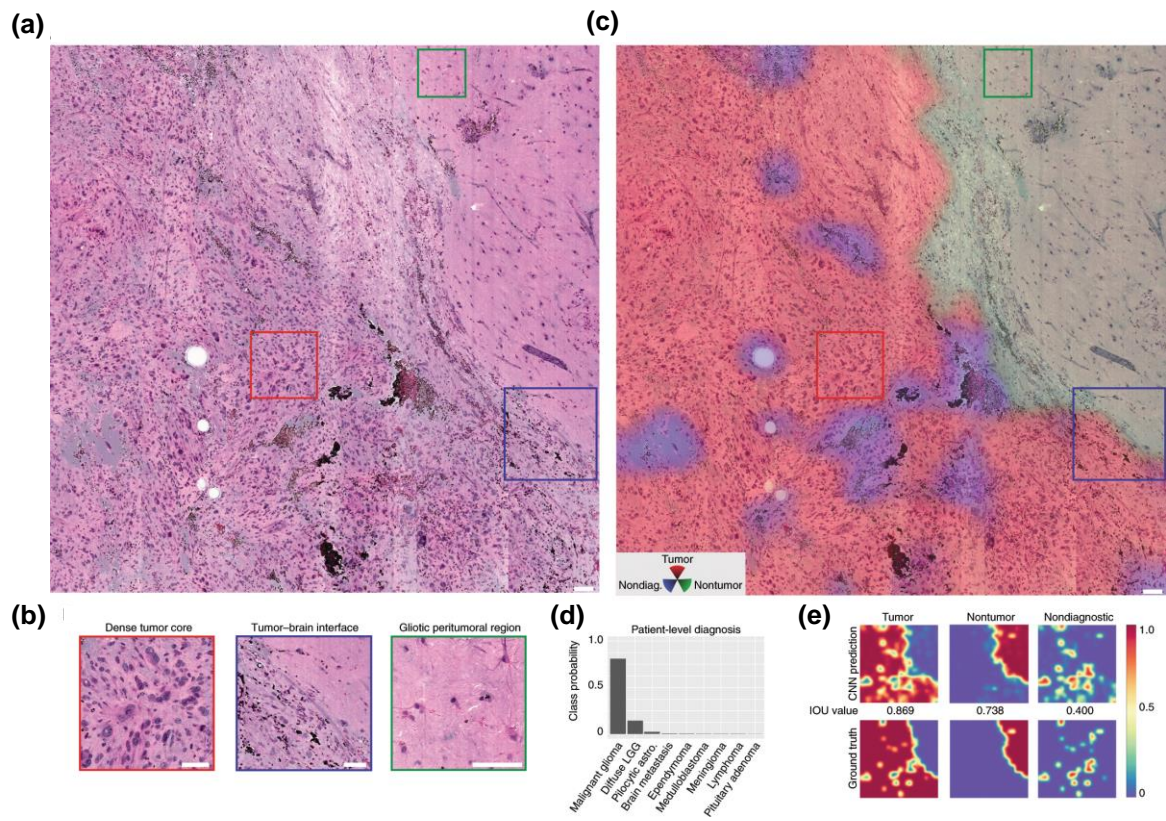
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6 As a final example we report here the current frontier of the clinical application of CRS imaging – and, more in
 7 general, of vibrational microscopy – represented by the study by Hollon et al, in collaboration with Invenio
 8 Imaging Inc., published in Nature Medicine in 2020 [206] (**Fig. 38**). Starting from an already described SRS-based
 9 FDA-registered technology able to be used in the operating room, making histological data available during
 10 surgery [200], here the authors moved a step forward to clinics. This was done by coupling SRS-imaging to deep
 11 CCN to automatically provide diagnosis at the bedside and in near-real time (<2.5 min), thus being an order of
 12 magnitude faster than standard procedures based on fresh frozen preparation and on the interpretation by
 13 pathologists (20-30 min). A total of 278 patients were included in a prospective, multicenter (4 US centers using
 14 4 different systems) and two-arms clinical trial, including a CNN training on >2.5 million SRS images. In details,
 15 for each patient, a fresh tumor specimen was collected, immediately split into sister samples, and randomly
 16 assigned to the control or experimental arm. The diagnostic accuracy of pathologists examining conventional
 17 H&E images from frozen sections (control arm) and SRS-based images directly obtained in the operating room
 18 on fresh and untreated sample and automatically classified by CNN, were compared. Overall diagnostic accuracy

1 was 93.9% for the standard H&E histology arm and 94.6% for the SRS+CNN arm, confirming the efficacy of the
2 approach considering both accuracy and timing criteria.

3 This study strikingly demonstrates how the information obtained by vibrational microscopy not only makes it
4 possible to reach the same (or even higher) diagnostic accuracy of standard human-based approaches, but also
5 drastically reduces time and practical pitfalls typically associated to sample preparation and visual examination.
6 This study also shows that moving to the clinics almost mandatorily requires the robust implementation of
7 artificial intelligence tools, the use of systems in compliance with the clinical workflow and rules, and rigorous
8 tests on large cohorts of patients.

9



10

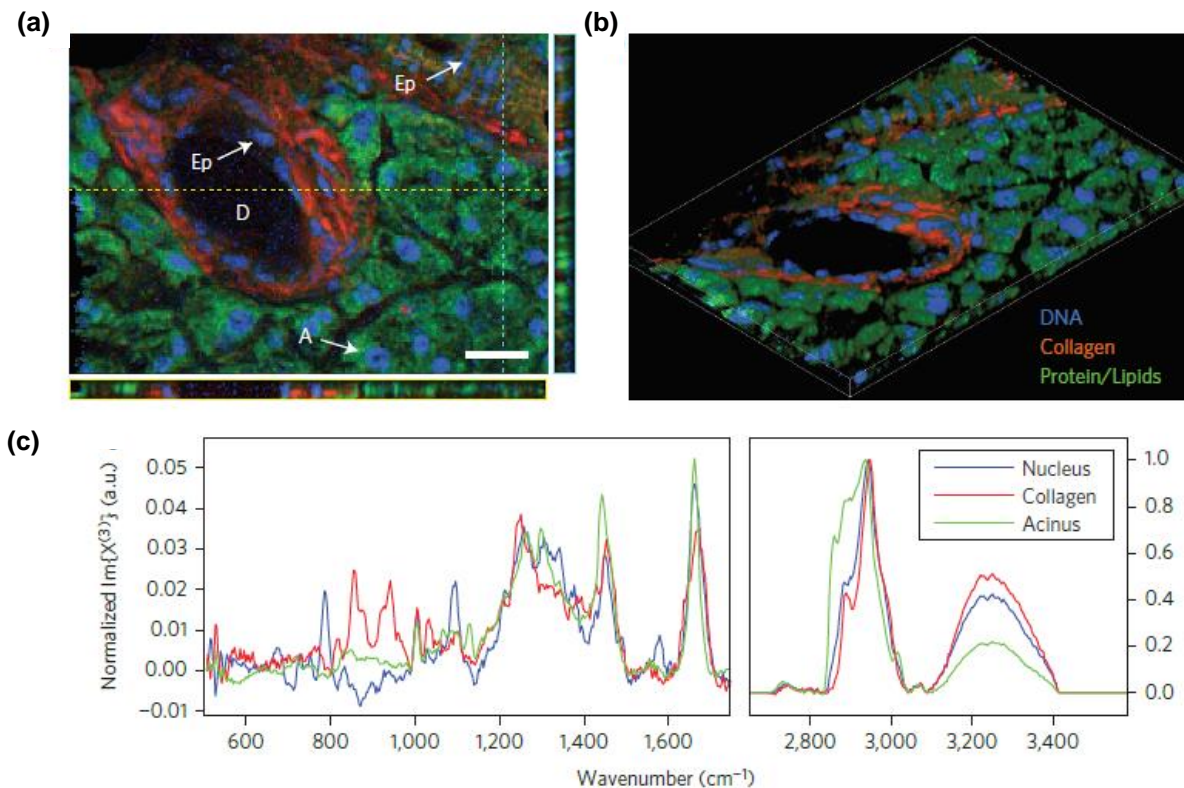
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12 **Fig 38** SRS-based histology (SRH) for the identification of tumour-infiltrated and diagnostic regions. **a** Full SRH mosaic of a
13 specimen collected at the brain–tumour interface of a patient diagnosed with glioblastoma. **b** zoomed regions on the ROIs
14 defined in (a). **c** zoomed regions on the ROIs defined in (a). **c** Three-channel CNN-based diagnostic prediction overlaid on
15 SRH image (Tumour (red), nontumour (green), nondiagnostic (blue)). **d** patient-level diagnostic class probabilities. **e** class
16 probability heatmaps for tumor, nontumor and nondiagnostic regions within the SRH image are shown with ground truth
17 segmentation. Scale bar: 50 μ m. Adapted with permission from [206].

18

19 Before to conclude this part related to CRS-based imaging approaches for cancer diagnosis, we would briefly
20 summarize the current early results and potentialities related to broadband SRS and CARS microscopy
21 approaches. As described in Section 2, and as reviewed in details in or recent review article [52], in the past 15

1 years several technological solutions have been proposed to extend the detection range from single frequencies
 2 to large spectral ranges, still maintaining high imaging speed. In this context, to the best of our knowledge, no
 3 broadband CRS studies have been yet applied to cancer assessment on human samples, but a few studies applied
 4 these new approaches for testing imaging performances on animal model tissues or for the study of
 5 neurodegeneration in human brain [61,77,207]. In particular, Cicerone and collaborators demonstrated the
 6 potentialities of a broadband CARS approach by studying fresh or frozen murine tissue samples to probe the
 7 entire biologically relevant spectral window (500-3000 cm^{-1}) with 10 cm^{-1} spectral resolution and 3.5 ms pixel
 8 dwell time (i.e. a few minutes per mm^2) [61] (**Fig. 39**). We believe that these preliminary results, and a relevant
 9 number of emerging technologies aiming to improve broadband CRS approaches for tissue imaging, will soon
 10 demonstrate significant advantages in the applied field of vibrational histopathology.



11
 12 **Fig. 39** Coherent Raman fingerprint imaging on biological tissues. **a** false colour map of murine pancreatic ducts showing
 13 nuclei (785 cm^{-1} , blue), collagen (855 cm^{-1} , red) and organic matrix (mainly proteins and lipids, 1666 cm^{-1} , green). D,
 14 exocrine duct; A, acinar cell; Ep, epithelial cell. **b** 3D reconstruction from the same tissue region, obtained by Z-stack
 15 images. **c** spectra obtained from single pixel obtained within specific tissue regions. Scale bar: 20 μm . Adapted with
 16 permission from [61].

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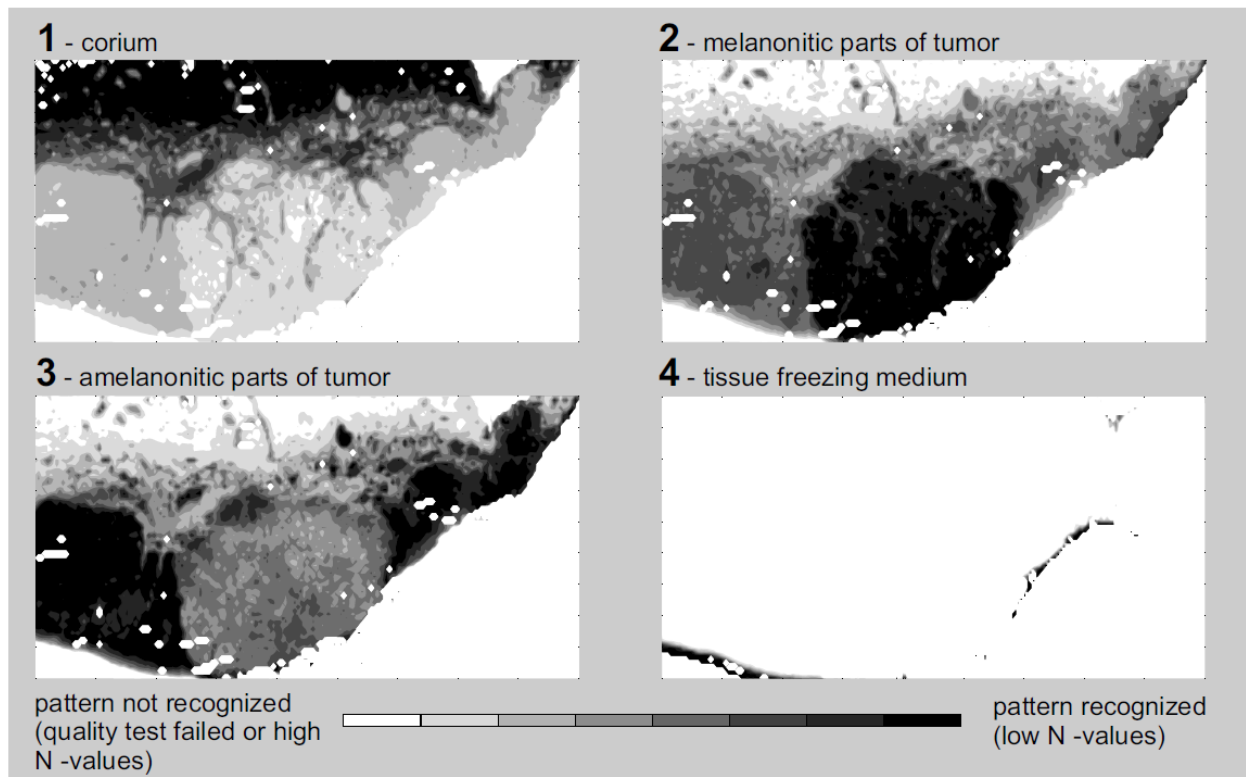
1 3.3 Infrared imaging

2 The relatively simple configuration and accessibility of commercial FT-IR spectrometers, and a significantly higher
3 signal to noise ratio if compared with SR spectrometers, combined with the numerous practical advantages of
4 vibrational spectroscopy (label-free and non-destructive), made IR spectroscopy a very powerful tool for the
5 biochemical characterization of biomolecules in the 20th century. The use of IR spectroscopy for the study of
6 cancer tissue samples was first attempted in 1949 [208,209] and was then followed by thousands of papers
7 between the 50's and the 90's aiming to explore the vibrational features of biomolecules, as extensively
8 summarized by several review papers and books [210–213].

9 Even considering the huge amount of knowledge about the biochemical characteristics of various samples and
10 molecules obtained with IR spectroscopy, the identification and classification of cancerous disease has been
11 made more reliable with the introduction of the imaging modality, as also occurred for Raman-based approaches.
12 As mentioned in the introduction to this section, this is due to the intrinsic spatial heterogeneity of tumor lesions
13 and to the fact that diagnostic decisions, especially related to cancer, are to this day based on the examination
14 of tissue morphology at microscopic level.

15 A step forward in the field of hyperspectral IR imaging for cancer assessment has been triggered by the
16 introduction in the 1980s of FT-IR spectrometers, which allow the collection of high quality spectra in a relatively
17 short time, and further supported by technological advances, such as sensitive detectors, chemometric
18 approaches and faster computers. For a review, see e.g. [214]. In parallel, P. Lasch and D. Naumann reported in
19 1998 the first high-resolution FT-IR images of tumor tissue [215] using a commercial FT-IR microscope coupled
20 with a software-controlled xy stage for point-mapping raster-scanning experiments with 80 μm step-size and a
21 nominal spectral resolution of 6 cm^{-1} . Melanoma and colon cancer frozen samples were used for these
22 preliminary FT-IR imaging experiments and, in addition to standard “chemical maps” produced by simply
23 integrating a single wavelength (related to a specific chemical component), the authors introduced for the first
24 time the use of cluster analysis, PCA and artificial neural networks (ANN) to produce false-colour IR-images (**Fig.**
25 **40**).

26



1

2 **Fig. 40** Early FT-IR images on human melanoma thin sections. Four different images were obtained by the scaled spatial
 3 distribution of four different spectral patterns (1-4), previously identified as reference spectra. Adapted with permission
 4 from [215].

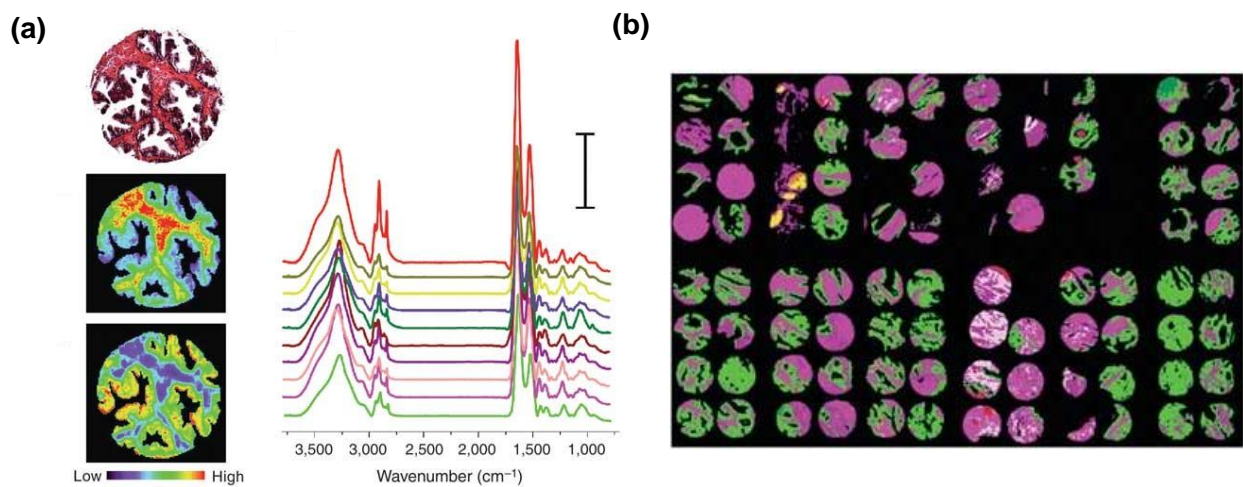
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6 A further revolution in the field of FT-IR imaging was made in the same period by the introduction of FPA
 7 detectors by I.W. Levin and collaborators (Bethesda, USA), [123,216], accompanied by early FT-IR imaging
 8 applications for the detection of silicon inclusions in breast samples [217]. FPAs coupled with an interferometer
 9 for FT detection enabled highly spatially resolved images (up to the diffraction limit) of large field of views
 10 (hundreds of μm^2) with acquisition times comparable to those required for the acquisition of a spectrum at a
 11 single point using single-element detectors. For example, Fabian and colleagues performed FT-IR images of
 12 breast cancer tissue slices showing that FPA-based instruments provide 4096 single pixel spectra in 5 min versus
 13 256 point spectra in around 4 hours when using a single-element detector [218].

14 To move FT-IR imaging closer to clinical diagnostics, validation on a relevant number of samples associated with
 15 rigorous clinical evaluations was a priority. In this context, the first efforts consisted in the study of 26 colorectal
 16 cancer samples resulting in promising accuracy performances (i.e., 95%) but still using single point spectral
 17 acquisitions [219]. In this modality, high-quality false colour images were produced and shown as proof-of-
 18 concept but not utilized to validate FT-IR imaging on relevant patient cohorts.

19

1 In 2005, R. Bhargava, I.W. Levin and collaborators applied FT-IR imaging to histopathology by analysing tissue
2 microarrays (TMAs), i.e. samples containing up to 96 tissue cores of around 0.6 mm in diameter, examining,
3 overall, 262 prostatic samples (i.e. tissue cores of around 0.6 mm diameter) from 40 patients (**Fig. 41**) [122]. All
4 samples were archival, FFPE samples collected during years and just treated for paraffin removal, demonstrating
5 the compatibility with standard routine diagnostic samples. This high-throughput FT-IR imaging strategy
6 produced ~3 million spectra with spatial resolution of 6.25 μ m and an acquisition time for each tissue core of
7 approximately 40 min. An initial univariate analysis (**Fig. 41a**) showed tissue differences but was not enough to
8 distinguish all histologic features; as a next step, ten typical histologic classes (normal epithelium, fibrous stroma,
9 mixed stroma, muscle, nerve, lymphocytes, stone, ganglion, endothelium and blood) (**Fig. 41b**) were defined and
10 further used for pattern recognition and subsequent automatic histopathologic characterization. After training
11 the classification model using 86 samples from 16 patients, probability maps were created for each histologic
12 class for all samples, achieving an accuracy between 90 and 99% for each class. A global validation was then
13 applied to individual samples and patients, aiming to distinguish benign versus cancer features obtaining very
14 good diagnostic performances, with an area under the curve (AUC) for the receiver operating characteristics
15 (ROC) curves greater than ≈ 0.99 .
16



17
18 **Fig. 41** FT-IR imaging and spectral features of prostate tissue. **a** H&E-stained biopsy section of human prostate tissue (top
19 left) accompanied by FT-IR images reporting protein (middle) and phosphodiester (bottom) concentrations from infrared
20 spectral absorbance at 1,545 cm⁻¹ and 1,080 cm⁻¹, respectively. Characteristic infrared absorbance spectra of ten histologic
21 classes comprising prostate tissue are (from bottom to top) from normal epithelium, fibrous stroma, mixed stroma, muscle,
22 nerve, lymphocytes, stone, ganglion, endothelium and blood, are reported in the right panel. The bar indicates an
23 absorbance of 0.2 absorbance units. **b** Example of high-throughput label-free FT-IR based automated and objective tissue
24 classification. The image shows a section of microarray containing different samples (i.e. tissue cores of around 0.6 mm
25 diameter) from different patients. Different colours represent different histological classes (showed in **a**). Adapted with
26 permission from [122].

27

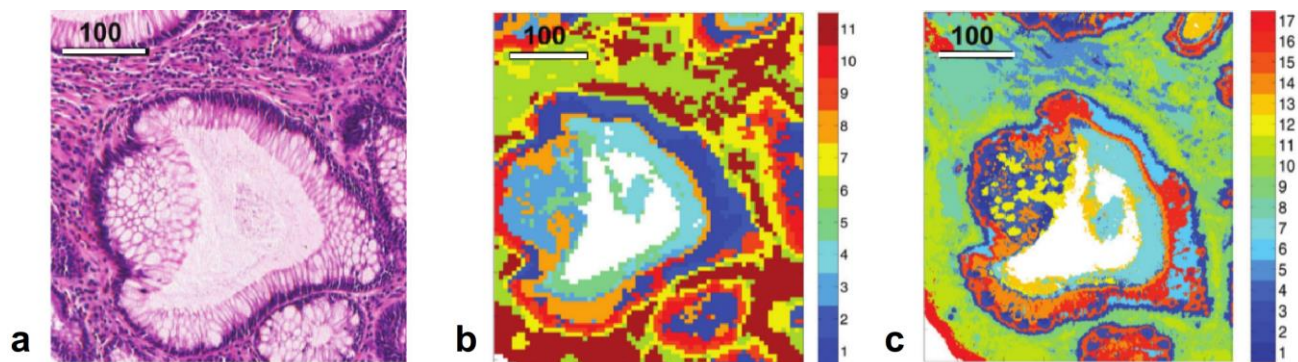
28 Leveraging the great improvements associated to FPA-based detectors, also other groups in Europe started to
29 apply FT-IR imaging to cancer studies. Krafft and collaborators (Jena, Germany) used FT-IR to distinguish cervical
30 carcinoma margins exploring the advantages and complementarities of different clustering approaches, namely,
31 fuzzy C-means clustering and hierarchical cluster analysis [220]. A single tissue sample from a patient with
32 squamous cell carcinoma was examined by collecting around 500000 spectra covering an overall area of 8.7 mm².

1 While a real diagnostic approach (i.e. by comparing normal vs. tumour samples) was not proposed, this study
2 reported the use of clustering approaches to describe in detail the spectral features of the complex histological
3 architecture that might be found in cancer samples.

4 In parallel to the increase of applications of FT-IR in the field of cancer diagnostics, new technological
5 improvements were introduced, including the use of attenuated total reflection (ATR)-based sampling modes
6 [221], as better detailed in **Section 2.3**. Briefly, compared to the more common transmission modality, the ATR
7 mode differs in that the IR beam does not pass through the sample, but undergoes total internal reflection within
8 an optical element with high refractive index (e.g., diamond, germanium, or silicon), thus allowing higher spatial
9 resolution (below 2 μm) if compared with a resolution limited to $\approx 5 \mu\text{m}$ for standard transmission-mode
10 instruments. Bhargava and collaborators compared the ATR and transmission modalities by studying breast
11 tissue samples, including malignant tumours [222]. As a result, the increased spatial resolution allowed by the
12 ATR sampling modality enabled the identification of specific cancer-related structures and cell subtypes relevant
13 for breast cancer diagnosis. Even if this approach has some drawbacks, including that the ATR element needs to
14 make contact with the sample and a limited sample area, it is a promising solution to complement standard FT-
15 IR systems when higher spatial resolution is required.

16 With similar aims, Stone and collaborators have taken advantage of the optical improvements of bench top FPA-
17 based instruments allowing an effective pixel size of $1.1 \times 1.1 \mu\text{m}^2$ instead of the typical $5.5 \times 5.5 \mu\text{m}^2$
18 configuration, thus passing from a “pixel-limited “ to a “diffraction-limited” configuration [126]. This, coupled
19 with oversampling and with multi-wavelength image analysis, permitted to identify typical cellular features of
20 colon tissue that were not previously detected by conventional FT-IR configurations [102,126]. To demonstrate
21 this improvement, **Fig. 42** compares three images of a sample of colon tissue, acquired by an optical microscope
22 and two FT-IR microscopes with conventional and high-resolution imaging modalities.

23



25 **Fig. 42** microscope images of the same colon tissue (with tubular adenoma), acquired with different techniques. (a) Optical
26 transmission image in the visible spectral range of the tissue, after H&E sample staining; (b-c) hyperspectral IR absorption
27 images; false colours are the clusters identified by cluster analysis on the measured hypercubes. (b) conventional imaging
28 set up with $5.5 \times 5.5 \mu\text{m}^2$ pixel-size, grouped into 11 spectral clusters; (c) high-resolution image by the optical high-
29 magnification scheme, corresponding to $1.1 \times 1.1 \mu\text{m}^2$ pixel size, and segmented into 17 spectral clusters. Adapted with
30 permission from [126].

31

32 In 2014, Goormaghtigh and collaborators used FT-IR imaging to investigate breast cancer features [223]. The
33 added value of this study is the detailed characterization of tissue components of breast tumour samples, also

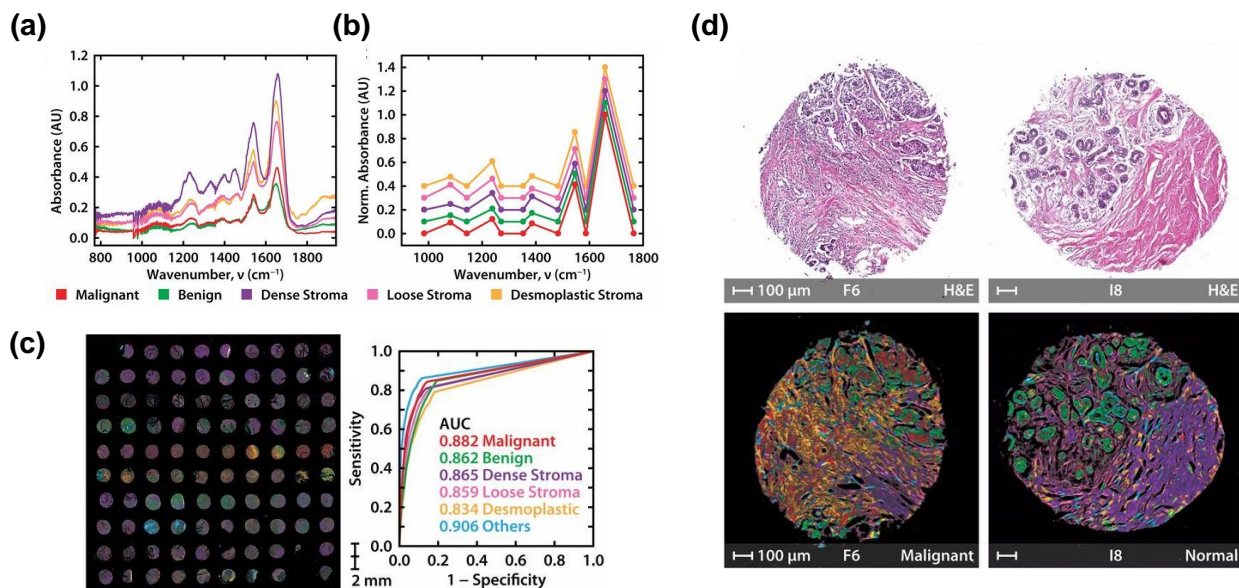
1 thanks to the comparison of spectral data originating from independent samples, not associated with breast and
2 tumours, aiming to determine cancer-related features of cellular or extracellular components contained in or
3 surrounding tumour samples. In details, authors reported that lymphocytes infiltrations observed in invasive
4 breast cancer are (spectroscopically) different from lymphocytes isolated from other organs (such as lymph
5 nodes and tonsils). Similarly, tumour associated stroma (i.e. the extracellular component of tumour, mainly
6 composed by collagen) showed spectral features different from collagen-containing tissue characterizing new
7 and old healed scar tissue (typically rich in collagen). This information is far from being obvious and suggests that
8 vibrational features of some components observed in tumour specimens (e.g. cancer-related immune cells
9 infiltration and cancer-related stroma) differ from the same components observed outside the tumour (i.e. in
10 healthy or non-tumour tissues). In other words, this suggests that the vibrational features observed in tumour
11 tissue may show tumour-specific rather than organ-specific signatures.

12 The most recent frontier in the field of IR imaging has been approached with the introduction of IR QCLs [224].
13 As detailed in **Section 2.3**, QCLs are broadly tuneable and bright light sources enabling the use of large size
14 uncooled FPA detectors. Among the first studies introducing QCL imaging of tissue samples for biomedical
15 purposes, P. Gardner and collaborators used a commercial QCL-based microscope measuring absorption at
16 discrete relevant frequencies (i.e. “multispectral imaging”), demonstrating the possibility to image a TMA of
17 around 2 x 2 cm² size in less than 10 minutes at a single frequency [225]. In this multispectral modality, QCL
18 systems showed to be much faster (>100 times) than standard FT-IR systems, which measure a continuous
19 spectrum in the fingerprint region in around 19 hours. Clearly, accurate description and diagnosis cannot be
20 performed using a single wavelength. In 2017, the Gardner group aimed to verify whether QCL imaging with
21 continuous spectra acquired in the fingerprint region was competitive for high throughput imaging [226] and
22 compatible with diagnostic accuracy, especially considering the impact of coherent sources on spectral quality.
23 A TMA consisting of 207 breast tissue samples, each from a different patient, was imaged by the same
24 commercial microscope mentioned above in the 1000-1800 cm⁻¹ region (pixel size of 4.2 μm) by collecting >33
25 million pixels in around 13 hours. As a result, malignant and non-malignant stroma were discriminated with
26 93.6% sensitivity and 85.7% specificity considering all spectra. On a patient basis, all malignant samples were
27 correctly identified (100% sensitivity) and non-malignant samples were classified as malignant in 13.3% of
28 patients (86.7% specificity). In terms of acquisition time, these results were obtained in around 13 hours (i.e. ≈4
29 min per patient sample), which is promising for translation into clinics but still not too far from the acquisition
30 time associated to conventional FT-IR systems (requiring around 19 hours for the same TMA [225]).

31 As also detailed in **Section 2.3**, Bhargava and collaborators reported improvements in the field of QCL-based IR
32 imaging by developing a home-built discrete frequency confocal IR microscope providing high-definition and
33 rapid spatial scanning, by sequentially acquiring 12 selected frequencies [128] (**Fig. 43**). In parallel to these
34 technological improvements, the authors also exploited the potential of IR-based chemical imaging by
35 characterizing the features of tumour microenvironment (i.e., cellular and extracellular components surrounding
36 tumour cells) and exploiting them for diagnostic purposes. This is remarkable if we consider that the tumour
37 microenvironment can hardly be described and used as diagnostic criterion by the sole H&E examination. First,
38 authors used conventional FT-IR imaging (i.e., with full continuous spectral information) to define 12 histological
39 classes (including 6 classes related to tumour microenvironment) able to describe the complexity of breast tissue.
40 After having optimized and tested the new confocal IR instrument, an entire TMA (1 cm²) containing 101 tissue
41 cores from 47 patients was then analysed in 8 hours (≈1 working day). According to the authors, this was around
42 50-fold faster than FT-IR imaging, that would need ≈50 days to obtain similar signal-to-noise ratio and a similar
43 number of spectra. Considering that the standard clinical practice in breast tumour diagnosis (and in several
44 other diseases) is the evaluation of needle biopsy sections (a few millimetres in size), authors tested the new

1 technology by imaging and classifying a full needle biopsy section (around 4x12mm²) in 3h, reporting the
 2 identification of malignant regions previously detected by pathologists on H&E contiguous slides. This study
 3 showed that, with the dramatic speed improvement afforded by QCLs, IR imaging has the possibility to come
 4 close to diagnostic workflow in clinics.

5

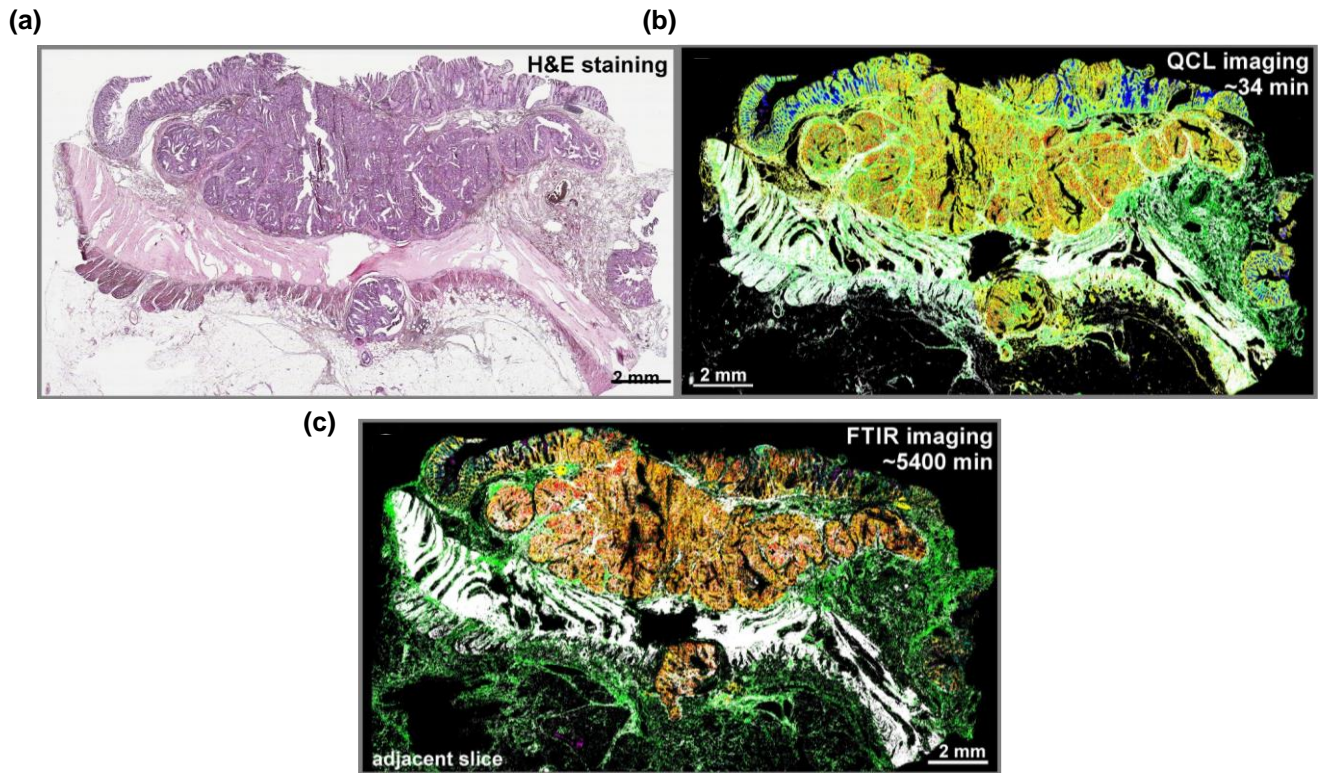


6

7 **Fig 43** QCL-based confocal infrared microscopy for molecular histopathology on breast tissue samples at discrete
 8 frequencies. **a** standard FT-IR spectra from five tissue types (see colour legend) at 1 cm⁻¹ spectral resolution. **b** data collected
 9 from the same tissue types by the new QCL-based confocal IR approach, at defined discrete frequencies. **c** tissue
 10 classification for cancer diagnosis on tissue microarray (left) with ROC curves reporting the accuracy for the identification of
 11 six relevant tissue types, including benign and malignant regions. **d** representative examples of malignant (left) and normal
 12 (right) tissue samples classified by the IR-based model (bottom), along with H&E stained images (top). Adapted from [128]
 13 (CC BY-NC-ND 4.0).

14

15 Simultaneously to Bhargava et al., Gerwert and collaborators reported the use of a commercial QCL-based IR
 16 microscope (the same used by Gardner and collaborators and previously mentioned, [225,226], but optimized
 17 to reduce coherence effects) to study whole thin sections (between 1-2 cm²) commonly used for clinical
 18 diagnosis [127]. In the configuration used for the study, the microscope collected 2x2mm² fields of view in 47s
 19 with 4.2- μ m step size and 2 cm⁻¹ spectral resolution from 950 to 1800 cm⁻¹, for a total of 850 wavenumbers (**Fig.**
 20 **44**). A single FFPE thin slice was measured in between 30 and 60 minutes, depending on size, thus permitting to
 21 analyse 120 clinical samples in 100 hours. This study showed that QCL-based microscopes can be >160 times
 22 faster than state-of-the-art FT-IR approaches with comparable spatial and spectral resolution. In addition, these
 23 were the first results reporting the use of IR-based microscopy to image a relevant amount of tissue samples
 24 (>100) in their standard format (i.e., whole microscope slides of a few cm²), thus overcoming the current
 25 limitation of most of vibrational based approaches for cancer diagnosis.



1

2 **Fig. 44** QCL-based IR histopathology compared with standard FT-IR imaging. **a** H&E-stained slice of colorectal cancer tissue
 3 used as reference. **b** QCL-based imaging. **c** FT-IR based imaging. The listed times illustrate the duration of the measurements.
 4 Red, pathological region comprising of tumorous regions and infiltrating inflammatory cells; white, muscles; green,
 5 connective tissue; cyan, crypts and blue, lumen. Adapted from [127] (CC-BY 4.0).

6

1 3.4 Photothermal imaging

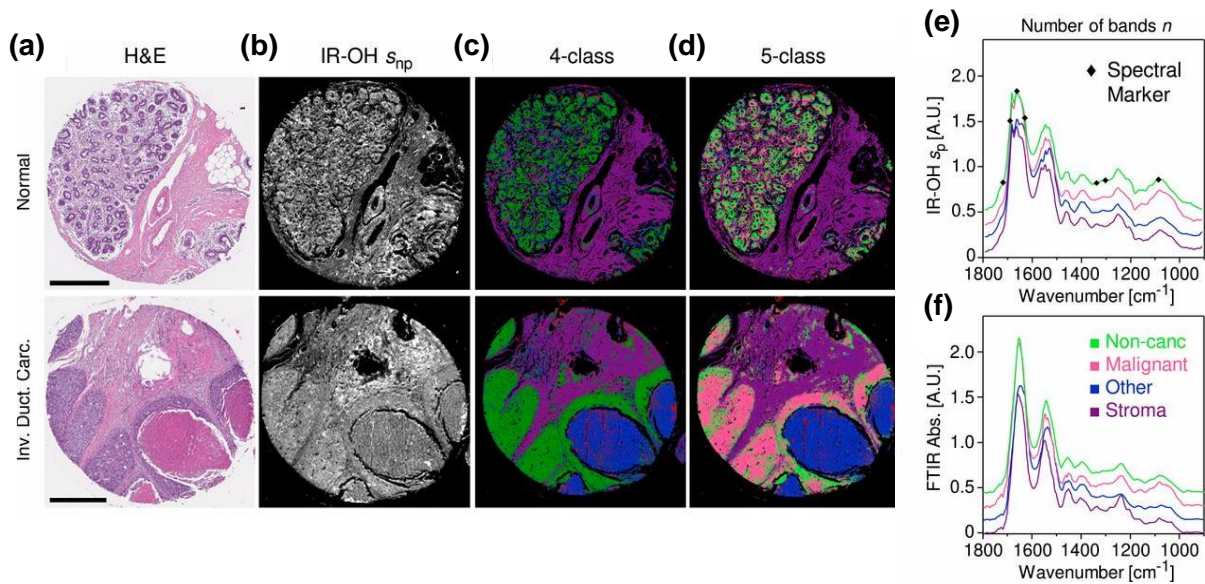
2 As described in the previous section, PT-IR is a very recent addition to the portfolio of vibrational techniques for
3 biomedical imaging and it has great potential for applications, considering both the study of cells and tissue,
4 including cancer diagnosis. The use of visible probes to record IR absorption spectra, which is at the basis of
5 modern PT-IR approaches, competes with both Raman and IR imaging tools, complementing the limitations of
6 both. In detail, PT-IR combines the high spatial resolution, usually guaranteed by Raman approaches based on
7 visible excitation sources, with the vibrational sensitivity (and associated acquisition speed) afforded by IR
8 approaches. Moreover, if compared with most CRS tools that are optimized for the imaging speed, PT-IR can
9 easily detect a broader range of vibrational features (i.e., at least the fingerprint region) which nowadays can be
10 reached only by recently proposed broadband CRS approaches, still associated with technological challenges
11 [52]. Furthermore, while water absorption in the IR significantly hampers the use of IR-based tools for the study
12 of living or fresh biological samples (due to the aqueous environment), its large thermal capacity reduces water-
13 induced index changes (and spectral interferences) that may overwhelm the photothermal signal of interest.

14 All mentioned advantages stand at the basis of recent proposed applications and proof of concept studies in the
15 biomedical field. High resolution photothermal imaging of living cells was first demonstrated in 2007, but this
16 was based on the detection of electronic transitions of specific components (mitochondria) thus reducing its
17 applicability for the detection of the biological complexity of disease, including cancer [139]. In parallel, first
18 proof-of-concepts experiments on tissue samples were reported by Mërtiri *et al.* in frozen brain slices but these
19 were based on the use of a mid-infrared pump – near-infrared probe photothermal microscope with intrinsically
20 low spatial resolution [227].

21 A relevant advance in the field has been reported in 2016 by Cheng and collaborators, who applied a home-made
22 PT-IR microscope for the study of living cells and nematodes, combining the rich chemical information afforded
23 by vibrational excitation in the IR with the diffraction-limited spatial resolution of the visible range [145]. After
24 proving the possibility to study single living cells and showing the detection of single lipid droplets and drug
25 molecules in cultured cancer cells, with sub-micrometer resolution, the authors applied the new microscope to
26 *C. elegans*, a millimeter size nematode. The possibility to detect distinct biochemical features (i.e. lipid and
27 proteins, at 1750 and 1655 cm^{-1} , respectively) over a relative large area with high spatial resolution and in a
28 reasonable time (i.e., 500 μs pixel dwell time) indicated compatibility of the method with the study of tissue
29 samples for diagnostic purposes. Following that pioneering result, some recent works reported the application
30 of PT-IR microscopy to the study of fixed and living cells [146,151,153,155,228], most likely because cell studies
31 are those for which the improved spatial resolution and water compatibility better emphasizes the added value
32 of this new imaging technique, especially if compared with standard FT-IR imaging approaches.

33 Up to now, very few PT-IR microscopy studies have been focused on tissue samples. With the exception of a few
34 proof-of-concept studies [227,229,230], only the group of Bhargava reported results in this direction, but with
35 very encouraging perspectives. Bhargava and collaborators proposed the so-called “IR-optical hybrid (IR-OH)
36 approach”, detecting IR absorption-induced thermo-mechanical expansion of the sample by a wide-field
37 interferometric photothermal configuration [154]. This configuration permits to combine high spatial resolution
38 and good signal-to-noise ratio with large fields of view (i.e. higher acquisition speed), thus being compatible with
39 histopathologic imaging. In details, the new microscope allows a 10-fold larger area if compared with standard
40 FT-IR imaging ($460 \times 460 \mu\text{m}^2$ vs $140 \times 140 \mu\text{m}^2$) and smaller pixel size ($0.32 \mu\text{m}^2$ vs $1.1 \mu\text{m}^2$). The new microscope
41 was applied to the study of breast tissues, with histologic cellular identification and cancer diagnosis using a TMA
42 of around 4 cm^2 consisting of a total of 101 cores (i.e. samples) from 47 patients (**Fig. 45**). Then, 22 discrete IR
43 frequencies were selected and used for the classification of malignant and non-cancerous subtypes. Considering
44 10 seconds per field of view (tile) for each frequency, a single tissue core of around 1mm^2 was imaged in 1.7h

1 and the entire TMA in 168h (7 days), equal to 24min/mm². Authors also showed that 7 discrete frequencies
 2 saturate the diagnostic performances at around 90% accuracy. In this configuration the acquisition time was
 3 reduced to less than 1h per sample and around 2.5 days for the entire array (9 min/mm²).
 4 These results represent the current state of the art in PT-IR microscopy for cancer assessment. Currently, the
 5 acquisition speed is significantly lower than in IR microscopy which, using QCL-based microscopes, is able to
 6 scan more than 1 cm² in around 30 minutes, even if at a significantly lower spatial resolution [127]. Therefore, a
 7 clear trade-off emerges between spatial resolution and acquisition speed, which may lead to the choice of PT-IR
 8 or IR as imaging technique. Further investigations will be required to determine whether the increased spatial
 9 resolution afforded by PT-IR justifies the increase in acquisition time for the application to histopathology.



10
 11 **Fig. 45** Photothermal-based IR-optical imaging of breast tissue for the assessment of cancer. **a** H&E-stained slice of
 12 normal and cancer (invasive ductal carcinoma). **b** IR-OH adsorption of adjacent sections at 1550 cm⁻¹. **c** four-class model
 13 (blood, epithelium, stroma, and other) classification based on five IR bands. **d** Epithelial classification (five-class model)
 14 for histologic cellular identification and recognition of cancer based on seven IR bands. **e, g** Representative class spectra
 15 obtained with IR-OH (with spectral marker reported on specific bands) and FT-IR, respectively. **g.** Adapted with permission
 16 from [154].

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1 4. Conclusion and perspectives

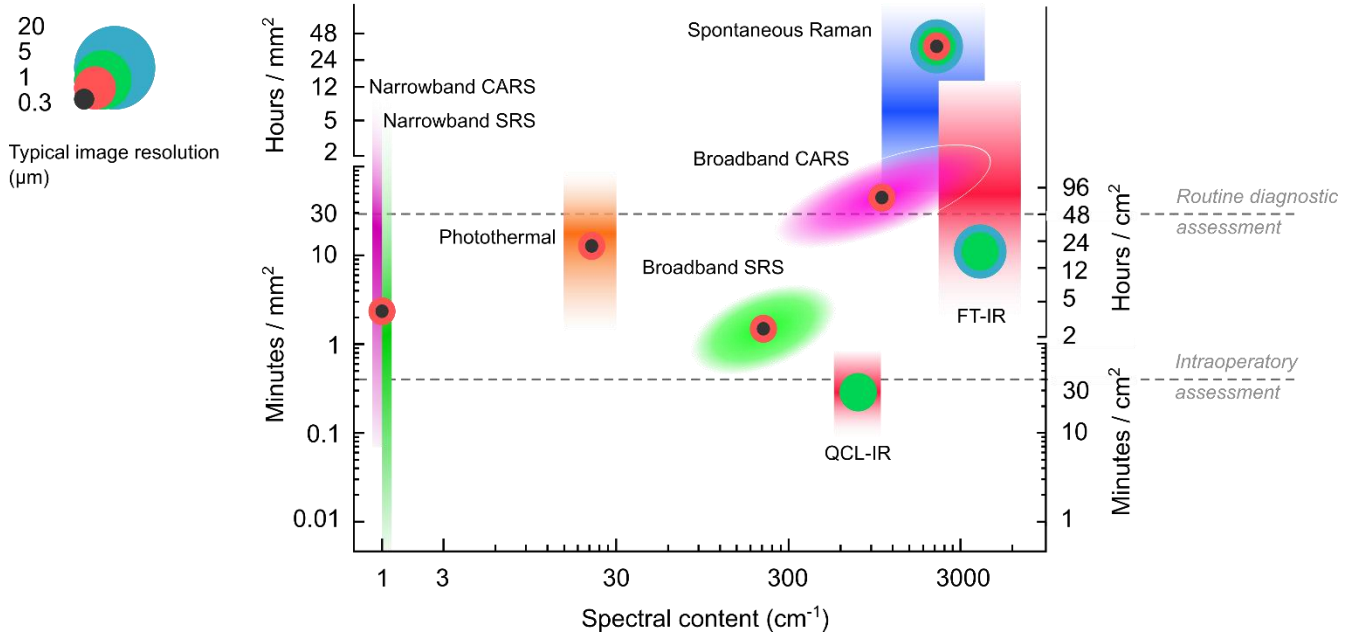
2 As emerging from the literature presented in the previous sections, in the last forty years exceptional efforts
3 have been invested to make possible the assessment of cancer on tissue samples using the intrinsic chemical
4 information revealed by label-free vibrational microscopies. Starting from pioneering Raman-based to IR-based
5 methods and going through the introduction of more recent technological evolutions of such approaches,
6 including coherent Raman microscopies, QCL-based infrared imaging and photothermal imaging, we have seen
7 a constant improvement of imaging and diagnostic performances.

8 As illustrated in **Figure 46**, three parameters are fundamental to evaluate vibrational imaging performances in
9 the biomedical context: spectral information, imaging speed, and spatial resolution of the image. An ideal label-
10 free imaging tool for histopathology should provide highly specific and highly informative data, at diffraction
11 limited resolution, and requiring less than the time taken today in the clinical practice for the preparation,
12 staining and observation of tissue samples with up to a few cm^2 area (i.e. between 20 to 40 minutes for
13 intraoperative assessment, between 24 to 48h for biopsy routine diagnosis assessment, considering tissue
14 fixation and embedding). The methods reported in literature to date commonly show good or exceptional
15 performances for only one or two of the above-mentioned requirements and, most of the time, one parameter
16 might need to be sacrificed to promote the others. For example, SR is the approach that currently better
17 combines high spectral information and high spatial resolution, but it is intrinsically limited by low imaging speed,
18 and the acquisition of images of tissue samples of some mm^2 may require days. This is the reason why the best
19 exploitation of SR approaches for image-based cancer diagnosis is the detailed characterization of relatively small
20 (pre-selected) tissue portions or the discovery of disease-related spectral features to be further detected with
21 faster approaches. Similarly, FT-IR microscopy is also highly informative and generally faster than SR but the
22 spatial resolution is intrinsically limited by the long IR wavelengths. Nevertheless, also FT-IR-based approaches
23 take many hours to produce false-colors images of tissue samples and are still far from the above-mentioned
24 ideal performances. In this context, QCL-based IR microscopy greatly improved imaging speed, up to $30 \text{ min}/\text{cm}^2$
25 thus beginning to become competitive with standard histological protocols. At the same time, current QCL-IR
26 approaches, still based on IR sources, are limited by a few μm lateral resolution and by the interference of water
27 bands, preventing intraoperative cancer assessment of fresh frozen samples. For what concerns spectral
28 information, the studies reported so far reach a coverage of $\approx 900 \text{ cm}^{-1}$, but recent development of QCL sources
29 is going to permit wider spectral windows for histological applications.

30 Coming back to Raman approaches, SRS and CARS imaging microscopes, employing narrowband (i.e. single
31 frequency) detection, perform very well in combining high imaging speed and imaging resolution. Such
32 approaches, especially SRS-based ones, can go below $1 \mu\text{s}$ pixel dwell time (i.e., a few minutes per mm^2), close to
33 diffraction limited resolution (i.e., 0.5 to $1.5 \mu\text{m}$), while still being fully compatible with fresh (or frozen) samples
34 without any sample preparation (or fixation) treatment (**Fig. 46**). On the other hand, narrowband SRS/CARS
35 methods are intrinsically limited to the detection of single wavenumbers (usually two bands, and usually in the
36 CH region) thus greatly restricting the biomolecular specificity of vibrational-based approaches. Consequently,
37 as reported in the previous section, recent successful approaches reaching clinical studies have used the spectral
38 information “only” to produce very accurate false color “virtual histopathology” images to be further processed
39 as images, and not as hyperspectral data, using AI approaches like those used for digital pathology. Even if this
40 methodology is very intriguing and the obtained images are well accepted by clinicians, the potential of using
41 the entire (or large part) of spectral and biomolecular information (i.e. “spectral histopathology”) can be even
42 more promising considering the amount of objective information that can be collected and used for tissue
43 classification. In this direction broadband CARS/SRS imaging tools may be a favorable approach to combine

1 imaging speed, spectral information, and high spatial resolution. The price here, at least in this early stage of
 2 development, is the technological complexity and the need of demanding data processing steps to retrieve
 3 accurate spectral features. Finally, in the previous section we also introduced PT-IR microscopy, which represents
 4 the most recent tool potentially able to answer current needs, by coupling IR-based excitation sources with
 5 visible detection, thus guaranteeing advantages of both Raman and IR approaches, still being compatible with
 6 water-containing samples. Application results are still to be evaluated, especially in the field of histopathology,
 7 but potentialities are clear and will probably be soon demonstrated in upcoming studies.

8



9

10 **Fig 46** Vibrational imaging performances of different approaches applied to cancer detection. Vertical axes indicate the time
 11 (minutes and hours, lower and upper sections, respectively) required to image area units (cm^2 and mm^2 , left and right,
 12 respectively) considering for each approach its common range of image resolution and confined between 0.5 to 20 μm
 13 between each pixel. The horizontal axis represents the average spectral window (and not the spectral resolution) covered
 14 by each vibrational approach, in standard setting for cancer imaging experiments, reported until now. Two horizontal broken
 15 lines approximately indicate the time commonly required to obtain intraoperative assessment of fresh-frozen samples
 16 (bottom line) and the time commonly required to obtain a routine diagnostic assessment from FFPE tissue samples (upper
 17 line). The coloured circles represent the allowed and most used pixel step-size for each approach. The coloured squares and
 18 ovals are representative and averaged performance ranges of imaging approaches used for cancer studies, mainly extracted
 19 from following selected studies: spontaneous Raman imaging [162,174,175]; FT-IR imaging [122,126,231]; QCL-IR imaging
 20 [127]; Photothermal imaging [154]; narrowband SRS [200,206]; narrowband CARS [197]; broadband SRS [207]; broadband
 21 CARS, from our preliminary data and from the available data on cancer tissue (non-human) [61].

22

23 For simplicity, and considering the scope of this review, here we mentioned three main criteria (i.e. imaging
 24 speed, spectral information and spatial resolution) to evaluate vibrational imaging approaches, but these
 25 aspects, strictly associated to technologies performances, are obviously not enough to understand what is
 26 missing to go from optical bench to clinical bedside. For instance, despite the enormous number of publications
 27 and patents in this field, the clinical translation of such approaches is still lacking, and this is one of the most

1 important aims and challenges for the scientific and industrial communities in these days. An increasing interest
2 has emerged on these aspects in the past two decades underlining causes, problems and needs concerning
3 clinical translation, as better detailed in recent documents and focal reviews [232–235]. Among the most urgent
4 needs we want to emphasize the importance of 1) establishing strong engagement between technology
5 providers and clinicians (final users), starting from the early maturation stage of technologies; 2) clearly
6 understand real needs and real constraints, also including those which apparently seem not strictly associated
7 to technological and scientific innovations (and high impact publications), including standard clinical and
8 laboratory procedures, routine workflow, regulatory aspects; 3) prioritize quality control of data, reproducibility
9 and large-scale validation.

10 At this concern the emerging of multimodal networks, such as “The International Society for Clinical
11 Spectroscopy” (CLIRSPEC) [236] and of “Raman4Clinics” (COST action) [237], permitted to establish the above
12 mentioned interactions between multiple stakeholders and also to organize large-scale cross-laboratory studies
13 [238,239] enabling to improve standardization and to define comparability parameters.

14 In conclusion, the continuous and dramatic technological progress in label-free vibrational microscopies, coupled
15 to an interdisciplinary effort to overcome barriers between technologists and clinicians and speak a common
16 language, promises to usher a new era in tumor diagnostics and in personalized, precision medicine.

17

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