

Building Automated Survey Coders via Interactive Machine Learning

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Abstract. Software systems trained via machine learning to automatically classify open-ended answers (a.k.a. *verbatim*s) are by now a reality. Still, their adoption in the survey coding industry has been less widespread than it might have been. Among the factors that have hindered a more massive take-up of this technology are the effort involved in manually coding a sufficient amount of training data, the fact that small studies do not seem to justify this effort, and the fact that the process needs to be repeated anew when brand new coding tasks arise. In this paper we will argue for an approach to building verbatim classifiers that we will call “Interactive Learning”, and that addresses all the above problems. We will show that, for the same amount of training effort, interactive learning delivers much better coding accuracy than standard “non-interactive” learning. This is especially true when the amount of data we are willing to manually code is small, which makes this approach attractive also for small-scale studies. Interactive learning also lends itself to reusing previously trained classifiers for dealing with new (albeit related) coding tasks. Interactive learning also integrates better in the daily workflow of the survey specialist, and delivers a better user experience overall.

Keywords. Machine Learning; Automated Survey Coding; Artificial Intelligence; Verbatim Coding; Sentiment Classification.

1. Introduction

In fields such as market research, the social sciences, political science, and customer relationship management, data are often collected through surveys, conducted by a survey specialist and involving a number of respondents (de Vaus, 2014). Conducting a survey usually involves a questionnaire, i.e., a list of questions which respondents are asked to answer. The majority of questions to be found in questionnaires are of the “closed” type, where the respondent is required to tick one of a predefined set of answers. *Open* (a.k.a. “open-ended”) *questions* instead involve returning a textual answer, whose length is not specified a priori. When computing the results of the survey, closed answers and open answers require very different amounts of processing: while closed answers simply involve checking which (or how many) respondents have picked which predefined options, open answers require more complex analysis. In order to manage open answers, the survey specialist first defines a classification scheme, i.e., a set of classes of interest for the given application (e.g., ‘BadCustomer-Support’, ‘IssuesWithWebsite’, etc., for a customer satisfaction survey run by a telecom company), and then classifies (i.e., attributes one or more classes

* The order in which the authors are listed is purely alphabetical; each author has given an equally important contribution to this work.

from the classification scheme to) each answer based on its textual content. The results of the survey are then obtained by checking which (or how many) respondents' answers have been attributed which class.

In the language of survey specialists, classes are called *codes*; classification schemes are called *codeframes*, or *codebooks*; classification is called *coding*; human annotators are called *coders*; the answers returned to open-ended questions are called *verbatim*s; and the task of classifying open-ended answers is called *survey coding*, or *verbatim coding*. This is the terminology we will adopt in the rest of the paper.

Open questions have advantages and disadvantages with respect to their closed counterparts. On the plus side, it is generally acknowledged that answers returned to open questions are richer and more informative, since the respondent can express her thoughts more freely, not being constrained by *a priori* choices made by the survey specialist. On the other hand, managing open questions is more onerous, since manually coding them is a time-consuming task.

1.1. THE QUEST FOR AUTOMATED SURVEY CODING

In the attempt to make open questions more manageable for survey specialists, a number of researchers have proposed using software systems for coding open answers automatically. This paper looks at a specific type of survey coding systems, namely, those based on *machine learning* (ML – see (Murphy, 2012)). ML, a subfield of *artificial intelligence* (AI), has recently taken the IT world by storm, to the point that Andrej Karpathy, Director of AI at Tesla, has described neural networks (the current protagonists of ML) as representing “the beginning of a fundamental shift in how we write software”.¹

The most important form of ML is *supervised learning*, according to which a learning algorithm “trains” a software system to perform a certain task by showing it a number of correctly solved instances (called *training examples*) of this task; by analysing these instances and their correct solutions the system learns to solve new instances itself. This is called “supervised” learning, because the human operator who feeds the training examples to the learning algorithm plays the role of the “supervisor”. Among the tasks that can be solved via supervised ML, classification is certainly the most important, since many real-world problems that involve prediction of future or unknown events can be framed as classification problems.

The world of survey coding has not been immune to the ML revolution. ML-based software systems trained to automatically code verbatims are by now a reality; they have been described in a number of publications (see e.g., (Clarke and Brooker, 2011; Esuli and Sebastiani, 2010; Gamon, 2004; Giorgetti and Sebastiani, 2003; Giorgetti et al., 2003; Macer et al., 2007; Patil and Palshikar, 2013)), and are offered by several commercial vendors. A ML-based survey coding system learns, from sample manually coded verbatims (the training examples), the characteristics a new uncoded verbatim should have in order to be attributed a given code. The ML approach to building survey coding

¹ Andrej Karpathy, ‘Software 2.0’, *Medium*, November 11, 2017, <https://medium.com/@karpathy/software-2-0-a64152b37c35>

systems is advantageous with respect to the more traditional “rule-based” approach (Viechnicki, 1998), since it requires much less manpower (see (Esuli and Sebastiani, 2010) for a thorough discussion of this point).

However, notwithstanding their attractive properties, the adoption of ML-based systems in the survey coding industry has been less widespread than it might have been. Several factors have hindered a more massive takeup of this technology. One of these factors is the effort involved in manually coding an amount of training data sufficient to guarantee a good enough coding accuracy on the part of the trained system. A second reason is the fact that small studies (i.e., coding tasks in which the amount of verbatims that require coding is small) do not seem to justify this effort, since the amount of uncoded verbatims that need to be manually coded for use as training data is, for small studies, close to the size of the study itself. Yet another reason is the fact that the process needs to be repeated anew when brand new coding tasks arise; in other words, the training data generated for coding a given study cannot be reused when a new, different study comes up, unless the two studies share the same codeframe *and* consist of data from the same source.

1.2. WHAT THIS PAPER IS ABOUT

In this paper we argue for an approach to building verbatim classifiers which addresses the above problems, and which we call “Interactive Learning”. We show that, for the same amount of training effort, interactive learning delivers substantially better coding accuracy than standard “non-interactive” learning. This is especially true when the amount of data we are willing to manually code for training purposes is small, which makes this approach attractive also for small-scale studies. Interactive learning also lends itself to reusing previously trained classifiers for dealing with new (albeit related) coding tasks. Interactive learning also integrates better in the daily workflow of the user, and delivers a better user experience overall.

The rest of the paper is organized as follows. Section 2 discusses the interactive learning approach to survey coding and its rationale. Section 3 presents the results of a number of experiments on various datasets of open-ended answers, in which we compare the accuracy and the efficiency of a verbatim coding system built via interactive learning, with those of a more traditional machine-learned system. Section 4 looks, with the support of experimental data, at how systems built via interactive learning lend themselves to “classifier reuse”, i.e., to leveraging, for solving a given coding task, a classifier previously trained for a different but related coding task. In Section 5 we look at related work in the area of automated verbatim coding, and discuss differences between our approach and other published work. Section 6 sums up our discussion, pointing at avenues for further development.

2. Interactive Machine Learning for Automated Verbatim Coding

Before discussing interactive learning we define some standard machine learning terminology for classification tasks.

There are different classification problems of applicative interest, based (a) on how many classes the codeframe \mathcal{C} contains, and (b) on how many of the classes in \mathcal{C} can be legitimately attributed to the same item (in our case: to the same verbatim). Both (a) and (b) are not designer choices, but are imposed by the application. Following standard mathematical notation, we denote by $|\mathcal{C}|$ the number of codes which \mathcal{C} consists of. We characterize classification problems as follows:

1. *Single-Label* classification is defined as classification when each item must belong to exactly one of the classes in $\mathcal{C} = \{c_1, \dots, c_m\}$.
2. *Multi-Label* classification is defined as classification when the same item may belong to any number of classes (zero, one, or several) in $\mathcal{C} = \{c_1, \dots, c_m\}$.
3. *Binary* classification may alternatively be defined
 - a) as single-label classification with $|\mathcal{C}| = 2$ (in this case $\mathcal{C} = \{c_1, c_2\}$ and each item must belong to either c_1 or c_2).
 - b) as multi-label classification with $|\mathcal{C}| = 1$ (in this case $\mathcal{C} = \{c\}$ and each item either belongs or does not belong to c).
4. To distinguish it from binary classification, single-label classification with $|\mathcal{C}| > 2$ is called *Single-Label Multi-Class* (SLMC) classification.
5. To distinguish it from binary classification, multi-label classification with $|\mathcal{C}| > 1$ is called *Multi-Label Multi-Class* (MLMC) classification.

MLMC classification can be reduced to (i.e., solved in terms of) binary classification. In fact, one may trivially solve a MLMC problem by independently training m binary classifiers, one for each code c_i in \mathcal{C} . Once trained, the binary classifier for code c_i will be entrusted with the task of deciding whether c_i applies to item d or not. So, by running the m binary classifiers (conceptually) in parallel, zero, one, or several codes at the same time can be assigned to d . The classifier for code c_i is trained by using the training examples labelled by c_i as the “positive training examples”, and the training examples *not* labelled by c_i as the “negative training examples”. The SLMC case cannot instead be recast into the binary case or into the MLMC case.

For reasons that will be made clear in Section 3, from here on we will assume we are dealing with binary classification. Given what we have said above, this also implicitly addresses MLMC classification.

In order to explain the notion of “interactive learning”, we now move to discussing two dichotomies well-known in the field of machine learning.

2.1. ACTIVE LEARNING OR PASSIVE LEARNING?

The first dichotomy we illustrate is the one between *active learning* (AL) and *passive learning* (PL), and refers to the role that the system plays in the choice of the items that should be manually coded, in order for them to play the role of training data. “Standard” machine-learning-based verbatim coding systems (such as, e.g., the one of (Giorgetti et al., 2003)) rely on PL, since it is the user who chooses the examples that, once manually coded, will be used as training data. Instead, in AL it is the system that provides the user with the verbatims to manually code. Existing AL algorithms differ in terms of the policies they adopt for choosing the items that the user should manually code; finding the policies that, for a certain *annotation budget* (i.e., the number of items that the user is willing – or paid – to manually code), maximise the accuracy of the resulting classifier, is the main goal of AL as a discipline (Cohn, 2011). Some such policies allow providing the user with “artificial” (i.e., completely made up) uncoded items (this is called *constructive active learning*). However, the by-now most frequently used approach to AL is *pool-based* AL, according to which the system chooses the items that the user should manually code from a “pool” of available (and non-artificial) uncoded items. Rather than choosing a subset of the items in the pool, most pool-based AL algorithms *rank* the items in the pool, implying that the user should start coding from the top of the ranked list and proceed down the ranking until the annotation budget is over. Ranking all the elements in the pool, rather than choosing a subset thereof, has the advantage that the available annotation budget does not need to be determined in advance.

Rather than for training a classifier from scratch, AL is often used for *improving* an existing classifier originally trained via PL (see e.g., (Esuli and Sebastiani, 2010)), by asking the user to “validate” (i.e., manually code, thereby confirming or disconfirming the class provisionally assigned to) a number of automatically coded (“autocoded”) items. In this paper we will explore a different avenue, i.e., *one in which AL is used right from the beginning, and in which PL thus plays no role*.

2.2. BATCH LEARNING OR INCREMENTAL LEARNING?

The second dichotomy we touch upon is that of *batch learning* (BL) vs. *incremental learning* (IL – a.k.a. *online learning*), and refers to the way the training items are provided to the learning algorithm. In BL the training items are provided to the learning algorithm all at the same time, and the algorithm generates a trained classifier after analysing them collectively. In IL (Auer, 2011) the training items are instead provided to the learning algorithm one at a time. One application scenario where this is useful is, e.g., when the training items are not all available right from the beginning, and instead become available over time.

In IL the input to the learning algorithm is *not* a set of training items, but a previously trained classifier plus one single training item. What the algorithm does is “update” the existing classifier by bringing to bear the information

obtained from the new training item; training a classifier is thus accomplished in a step-by-step fashion, by carrying out as many classifier update operations as there are training items.

Unlike in the AL vs. PL dichotomy, where the same learning algorithm could be trained either via AL or via PL, the BL vs. IL dichotomy translates into a sharp distinction between (a) algorithms that only handle BL (which thus take as input a set of training items) and (b) algorithms that only handle IL (which thus take as input a previously trained classifier and a single training item).

2.3. INTERACTIVE LEARNING!

In this paper we argue for an approach to building verbatim classifiers based on “interactive learning”. So, where does interactive learning stand with respect to the two dichotomies illustrated in Sections 2.1 and 2.2? Simply stated,

$$\begin{aligned} &\textbf{Interactive Learning} \\ &= \\ &\textbf{Active Learning} + \textbf{Incremental Learning} \end{aligned}$$

With respect to the standard way machine-learning-based verbatim coders are built, interactive learning thus takes opposite stands with respect to both dichotomies; while the former are built via batch passive learning, we now argue for systems built via a combination of active learning and incremental learning.

The difference between the “classic” verbatim coding systems and the ones we envisage here is best illustrated in Figure 1, where part (a) illustrates the typical workflow of a classic system and part (b) illustrates instead the workflow of an interactive-learning-based system.

Let us look at Figure 1(b) in more detail. The process starts with the system generating a random classifier. This classifier is used to autocode all the uncoded verbatims, after which the system chooses (according to a policy that we will discuss), among all the autocoded verbatims, the one that it expects to be, once validated, the most informative (when used as a training example) for the training process. The chosen verbatim is fed to the user to validate, after which the cycle starts again. The net effect is that control passes from user to system and from system to user each time a new verbatim is validated; this frequent switch, with user and system working in tightly-bound mode, justifies the name of “interactive learning”.

Therefore, at each iteration, (i) the verbatim that the user should validate is chosen by the system and not by the user, (ii) the classifier is immediately updated (rather than retrained from scratch) to reflect the contribution of the new training verbatim, and (iii) all the uncoded verbatims (with the exception of those which have been validated already) are autocoded.

The user terminates the loop when the annotation budget is over, or when she believes that the trained classifier has become accurate enough.

Note that all the uncoded verbatims that have not been validated

- are autocoded over and over again, at each iteration. While some of them will be assigned the same code in two or more successive iterations, some

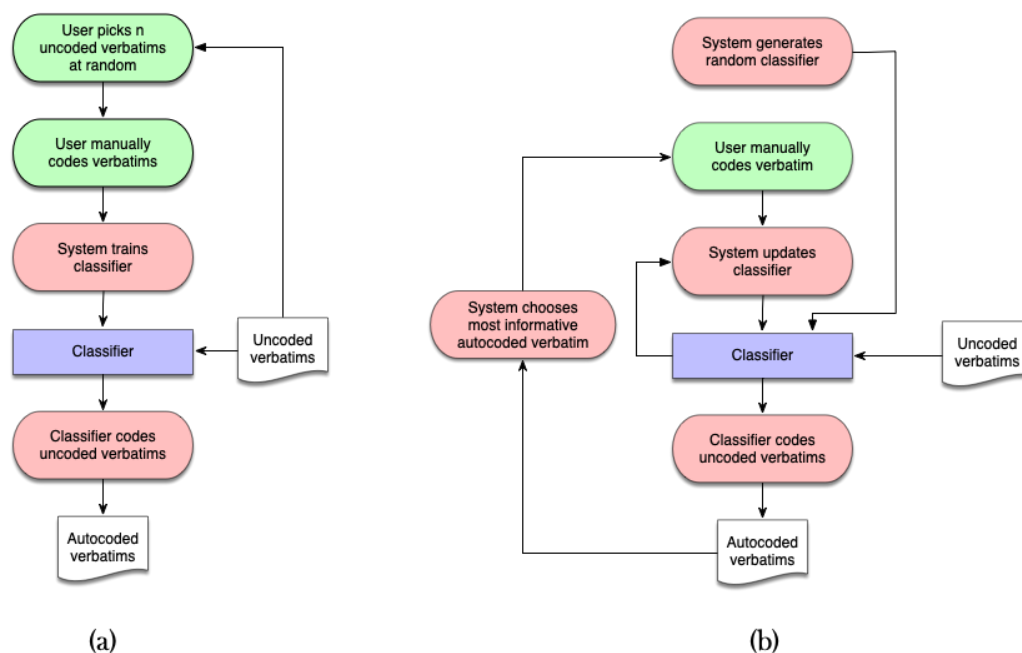


Figure 1. Workflows for automated verbatim coding based on (a) standard (i.e., batch passive) learning, and (b) interactive (i.e., incremental active) learning. Green indicates user actions, while red indicates system actions.

others might not, due to the fact that the classifiers employed in the different iterations are different, with the more recent one usually being more accurate;

- are evaluated over and over again, at each iteration, for allowing the system to choose the one to be fed to the user for validation. Again, a verbatim that has not been deemed useful in a previous iteration might be deemed useful in a subsequent one, since the classifiers that need to be improved upon are different.

2.4. THE RATIONALE FOR INTERACTIVE LEARNING

What is the rationale for switching from batch passive learning to incremental active (i.e., “interactive”) learning? The main reason behind our proposal is that *not all training items are created equal*. In other words, assuming we can choose, from a pool of available verbatims, a subset of n verbatims to be used as training data, different subsets will lead to classifiers characterized by different levels of accuracy. AL is a set of technologies concerned with making an *informed* such choice, i.e., one that results in classifiers as accurate as possible. Therefore, the main rationale behind our move is to have such choice be performed by the system (which we can instruct to make informed choices) instead of the user (whom we cannot assume to be able to make informed choices). The higher accuracy that AL can bring about thus *justifies switching from PL to AL*.

When using AL, the classifier is retrained every time k new training items are available, and all AL techniques allow setting a desired value for k . Which value of k is the best? Experiments in different applicative scenarios – see also Section 3.4 – indicate that *the smaller the value of k , the better the resulting accuracy*. To see why this is the case, assume we have chosen k to be 10: while choosing 10 informative verbatims from our pool (and having them validated) may indeed improve accuracy, it is intuitive that an even higher improvement can be obtained by first choosing 5 of them, retraining, and *only then* choosing the next 5, since the choice of these latter *can be informed by the knowledge of the effects that the previous 5 have brought about*. For instance, when using $k = 10$ we might not realize that some information contained in the first 5 chosen verbatims is duplicated, or nearly duplicated, by information contained in the last 5. If we instead choose $k = 5$, we retrain after the first 5 verbatims have been validated, and the 5 verbatims chosen in the next round will likely not include duplicates of the previous 5.

This line of reasoning implies that the best possible value of k is 1, i.e., retraining is performed every time a new training verbatim becomes available. However, when using traditional batch learning, the problem with using small values of k is the computational load involved, since in batch learning the computational cost of training is a linear (or supra-linear) function of the number of training examples: just picture the case of having a classifier trained on 1,000 training examples, and (assuming we have chosen $k = 5$) retraining it *from scratch* with 1,005 examples, with 1,010 examples, etc. In incremental learning, instead, a classifier is not retrained from scratch, but simply *updated* with the information provided by one single additional training example; in the example above, updating a classifier trained on 1,000 training examples, thus bringing to bear the 1,001st example, requires a tiny fraction of the time that retraining from scratch on 1,001 examples would require, because the original 1,000 examples are no more involved. The desirability of using $k = 1$ in an active learning context thus *justifies switching from batch learning to incremental learning*.

2.5. CHOOSING THE MOST INFORMATIVE VERBATIM

The last important aspect we want to touch upon is the policy according to which the autocoded verbatim is chosen (for the user to validate and for the learning algorithm to subsequently use as a training example). While many different policies might be concocted, we here focus on discussing three simple ones:

- RANDOM: we choose a random verbatim from the pool.
- MINMAX: on odd-numbered (resp., even-numbered) iterations we choose the verbatim which the classifier is most certain to be (resp., not to be) an instance of the code.
- UNCERTAIN: we choose the verbatim for which the classifier is most uncertain whether it should be attributed the code or not.

The RANDOM policy is not a policy we might realistically consider, and we will only use it for comparison purposes. The other two policies are based on the fact that modern classifiers, when coding an uncoded verbatim, output not only a binary decision (indicating whether to attribute the code to the verbatim or not), but also a confidence score, indicating how certain the classifier is of its decision; usually, a score of 1 indicates total certainty that the verbatim should be attributed the code, a score of 0 indicates total certainty that the verbatim should *not* be attributed the code, while a score of 0.5 indicates total uncertainty as to which between the two is the case.

The rationale of the MINMAX policy is that, by alternating between examples likely to belong to the class and ones likely *not* to belong to the class, we are likely to generate a set of positive and negative training examples of the code as balanced as possible, which should result in an accurate classifier. The rationale of the UNCERTAIN policy, instead, is that a verbatim that the current classifier cannot code with confidence is likely to be informative (once validated by the user), since it is likely to help the classifier code correctly examples on which the classifier is currently uncertain about. In Section 3 we will present the results of experiments in which we comparatively run the three policies, and which will help us in clarifying which policy is the best.

3. Experiments

In this section we describe the results of experiments in which we have tested the accuracy and the efficiency of both traditional (i.e., batch passive) learning and interactive learning on a number of datasets of manually coded verbatims.

An experiment consists in training the classifier on a subset of the verbatims in the dataset (which are thus called the “training examples”), using the trained classifier in order to code all the other verbatims in the dataset (the “test examples”), and evaluating how accurately the entire set has been coded as a result of this process. Here, “accuracy” means adherence to the manually assigned codes, which are assumed to be correct; see Section 3.4 for details on how this adherence is computed.

All the discussion in this paper, and the experiments we describe, focuses on the *binary* case, i.e., on training classifiers that decide whether a item should be assigned or not a given code. The reason is that some of the datasets we will use are binary while the other are multi-label multi-class ones, and we have seen at the beginning of Section 2 that MLMC classification can be recast as binary classification. We do not run single-label multi-class experiments, one of the reasons being that SLMC is a rare occurrence in survey coding (almost all cases that arise in practice are either of the binary or of the MLMC type); however, everything we say in this paper readily applies to the SLMC case too.

3.1. DATASETS

A *binary dataset* is a set of texts manually coded to indicate whether, for a given code c , they belong to c or not. A *MLMC dataset* is instead a set of texts

manually coded to indicate whether, for each code c in a codeframe \mathcal{C} with $|\mathcal{C}| > 1$, they belong to c or not. As already discussed in Section 2, working on a MLMC dataset characterized by a codeframe with m codes is equivalent to working on m binary datasets, since multi-label classification is accomplished by deploying m independent binary classifiers, one for each code in the codeframe.

In our experiments we use the following datasets, or groups thereof²:

1. **LL-ACE**: this is a set of 3 multi-label datasets (called LL-A, LL-C, LL-E) of 201 verbatims each, returned in response to market research surveys conducted around 2009 by Language Logic LLC (now called Ascribe³), a US-based company specializing in software platforms for market research and active in the US since 2000; their codeframes contain 16, 20, 39 codes, respectively.⁴ These datasets are from one wave of a continuous (“tracking”) survey that the company used to code 12 times a year, which consisted of “semi-open” brand questions (i.e., questions – such as “What is your favourite soft drink?” – that, although in principle eliciting a textual response, usually generate many responses consisting of only the name of a product or brand, with this name coming from a small set of such names. However, the answers have the typical features of textual answers, such as, e.g., different variants of the same brand name (e.g., Coca Cola or Coke), padding text (e.g., “My all-time favorite is”), and typos.
2. **LL-BDFGHIL**: this is a set of 7 multi-label datasets (called LL-B, LL-D, LL-F, etc.) of 501 verbatims each, returned in response to market research surveys also conducted by Language Logic LLC; their codeframes contain 26, 21, 38, 82, 64, 52, 50 codes, respectively. These datasets are from a large consumer packaged-good study, with both open-ended and brand-list questions.
3. **Egg**: these are 2 sets of 2 multi-label datasets each ($\{\text{EggA1}, \text{EggA2}\}$ and $\{\text{EggB1}, \text{EggB2}\}$); each of the 4 datasets consists of 926 verbatims returned in response to a customer satisfaction survey conducted by Egg PLC⁵, a large online bank active in the UK since 1998; the codeframe for EggA1 and EggA2 contains 21 codes while the codeframe for EggB1 and EggB2 contains 16 codes. For both sets of datasets, which were collected in the context of two different surveys, respondents were answering the question “Have we done anything recently that has especially disappointed you?”.

² Groups 1, 2, and 4, were originally described and used in (Esuli and Sebastiani, 2010), and are also used in (Berardi et al., 2014). Of group 3, the $\{\text{EggB1}, \text{EggB2}\}$ datasets are the same as described in (Berardi et al., 2014), while $\{\text{EggA1}, \text{EggA2}\}$ are random subsets of the datasets of the same name used in (Berardi et al., 2014). The reason for taking *subsets* of the original $\{\text{EggA1}, \text{EggA2}\}$ is to have all datasets in the same group contain the same number of verbatims;.

³ <http://goascribe.com/>

⁴ Throughout this section, by the number of codes contained in a codeframe we actually mean the number of codes in the codeframe *that have at least 1 instance* in the corresponding dataset; we thus ignore the codes that are never instantiated.

⁵ <https://www.ybs.co.uk/help/online/egg.html>

4. **ANES-L/D**: this is a set of 2,665 verbatims returned in response to a political survey conducted several years ago by the American National Election Studies (ANES)⁶, a US-based project that has been running national surveys of voters since 1948. It consists of two mutually disjoint subsets of verbatims: the ones in the first subset were returned as an answer to the question “Is there anything in particular about Mr. Clinton that might make you want to vote for him? If so, what is that?” while the ones in the second subset were returned as an answer to the question “Is there anything in particular about Mr. Clinton that might make you want to vote against him? What is that?”. Our coding task consisted in guessing whether the verbatim belongs to the first subset (code ‘Like’) or to the second subset (code ‘Dislike’).

Note that all the datasets in the same group contain the same number of verbatims. This is intentional, i.e., we have grouped the datasets in such a way (see also Footnote 4) that this property holds: since in the rest of the paper we will sometimes (e.g., in Figure 2) report the average accuracy of a given system across all datasets in the same group, this property will prevent us from comparing apples to oranges.

None of the datasets above is publicly available, and we are using them under tight non-disclosure agreements imposed by the companies / institutions that own them. Since we know of no publicly available dataset of answers to open-ended questions, in the interest of reproducibility we also present results on other datasets that, while consisting of texts other than answers to open-ended questions, are nonetheless publicly available. They are⁷:

5. **MDS**: this is a set of 4 binary datasets (called DVDs, Electronics, Kitchen, Books) each consisting of 2,000 Amazon product reviews (of DVDs, home electronics items, kitchen appliances, and books) coded by sentiment (‘Positive’ vs. ‘Negative’);
6. **Reuters-21578(10)**: this is a multi-label dataset of 10,788 Reuters newswire stories, coded according to a codeframe consisting of 10 economy-related codes (such as ‘Earnings’, ‘Acquisitions’, etc.). The codeframe of the original dataset (known as Reuters-21578) actually contains 115 codes, but many of them are extremely infrequent (some codes have just 1 positive training example); as a result, following many other authors in the text classification literature, we here only use the 10 most frequent codes..

Table I recapitulates the main characteristics of the 6 groups of datasets.⁸ Note that, as from the descriptions above, groups 1, 2, 3, 6 are MLMC datasets and

⁶ <http://www.electionstudies.org/>

⁷ Each dataset in group 5 is a randomly chosen subset of a dataset available from <https://www.cs.jhu.edu/~mdredze/datasets/sentiment/> (again, subsets were taken in order to have all datasets in the same group consist of the same number of items). Dataset 6 is available from https://raw.githubusercontent.com/nltk/nltk_data/gh-pages/packages/corpora/reuters.zip.

⁸ In this table the “total number of binary codes” should be interpreted as the total number of binary distinctions that need to be captured, or binary classifiers that need to be trained.

Table I. Main characteristics of the 6 groups of datasets we use for experimentation. The last 5 columns indicate the number of verbatims contained in the dataset, the number of codes the codeframe consists of, the average and median length of the verbatim (i.e., number of non-unique words contained in it), and the average number of codes per verbatim.

	Group of datasets	Type	# verbatims per dataset	Tot # binary codes	Avg # words per verbatim	Median # words per verbatim	Avg # codes per verbatim	Avg # positive verbatims per code
1	LL-ACE	market research	201	75	1.80	1	1.22	9.76
2	LL-BDFGHIL	market research	501	333	5.56	3	1.26	13.27
3	Egg	customer sat	926	74	26.97	22	1.74	90.60
4	ANES-L/D	political survey	2,665	1	26.88	21	0.52	1396.00
5	MDS	product reviews	2,000	4	129.74	84	0.50	1000.00
6	Reuters-21578(10)	newswires	10,788	10	127.76	84	0.93	997.90
Tot →				497				

are about classification by topic, while groups 4 and 5 are binary datasets and are about classification by sentiment.

Groups 1 to 6 account for a total of 497 binary classification experiments, which qualifies as a fairly substantial experimentation.

3.2. LEARNING ALGORITHMS

As noted at the end of Section 2.2, batch learning and incremental learning require different learning algorithms. For our batch passive learning experiments we have chosen *Support Vector Machines* (SVMs) (Zhang, 2011), a state-of-the-art learning algorithm that has consistently delivered top-notch accuracy throughout the text classification literature⁹.

This means that, e.g., for the ANES-L/D dataset this number is just 1, since one just needs a classifier to tell code ‘Like’ from code ‘Dislike’; in other words, the assignment of code ‘Dislike’ should be more properly seen as the non-assignment of code ‘Like’, i.e., ‘Dislike’ should not be seen as a proper code. For the very same reason, for group MDS 4 classifiers need to be generated, i.e., a ‘Positive’ vs. ‘Negative’ classifier for each of the 4 datasets in the group.

⁹ For our SVMs we have used a linear kernel since (a) it is the fastest kernel to train, (b) it has fewer parameters requiring optimization than other kernels (such as the polynomial or RBF kernels), and (c) it is the one that usually works best when classifying textual objects, since text generates very-high-dimensional representations that are often linearly separable.

Table II. The four-cell contingency table for code c resulting from an experiment.

Code c	coder says	
	YES	NO
system	YES	TP FP
says	NO	FN TN

For our incremental active learning experiments we have instead chosen an algorithm called *Passive Aggressive* (PA – (Crammer et al., 2006)), also a state-of-the-art incremental learning algorithm. PA shares many underlying design principles with SVMs, and (to a first approximation) may be considered as an “incremental version of SVMs”; this makes it particularly suitable to our comparison.

Note that the specific choice of SVMs and PA to play the roles of the batch algorithm and the incremental algorithm, respectively, is inessential to our argument, since what we say in this paper is largely independent of the specific batch and incremental algorithms we use. That is, our argument is that using passive learning with a batch algorithm X delivers inferior quality with respect to active learning with an incremental equivalent of X ; other algorithms we might have as well chosen to exemplify this could have been, say, batch (Schapire and Singer, 1999) and incremental (Oza and Russell, 2001) versions of AdaBoost.

3.3. EVALUATION MEASURES

As our accuracy measure we use the well-known F_1 measure (sometimes informally called “the F-score”, or “the F-measure” – see (Esuli and Sebastiani, 2010) for a detailed discussion), defined as

$$F_1 = \begin{cases} \frac{2 \cdot TP}{2 \cdot TP + FP + FN} & \text{if } TP + FP + FN > 0 \\ 1 & \text{if } TP = FP = FN = 0 \end{cases} \quad (1)$$

where by TP , FP , FN , TN , we indicate, as customary, the number of true positives, false positives, false negatives, true negatives, obtained by checking the automatically attributed codes against the true codes (see Table II); F_1 values range from 0 (worst) to 1 (best).

3.4. RESULTS

Figure 2 represents the results of a number of experiments that we will discuss more in depth in Section 3.4.1; for the moment being this figure will only serve the purpose of illustrating how we display the results of experiments. Each among the 5 plotted curves represents the accuracy (expressed in terms of the

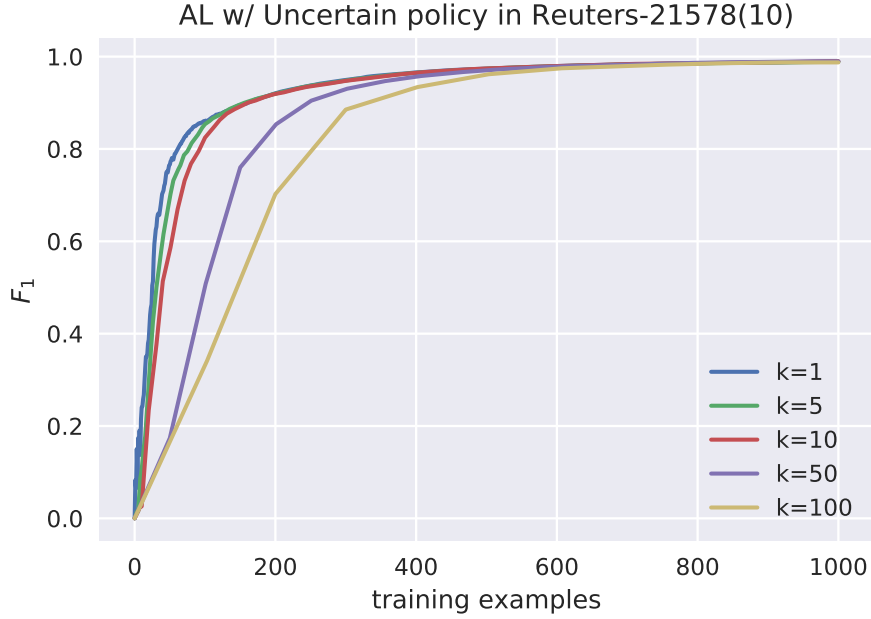


Figure 2. Experiments testing the impact of the value of k on the accuracy (measured via F_1) deriving from active learning (here: using the SVM learning algorithm, the UNCERTAIN policy, and the Reuters-21578(10) dataset).

F_1 function of Equation 1) of a given automated coding system on a given group of datasets (here: the Reuters-21578(10) group) as a function of the number of training examples used. Higher curves represent better systems, and the reported accuracy is the average value of F_1 across all the datasets (10, in this case) in the group. If the dataset consists of N verbatims, each point in the curve represents the result of training on X verbatims, autocoding the remaining ($N - X$), and computing the overall accuracy across all the N verbatims. This is intended to simulate a real scenario in which a user is interested in obtaining an accurate coding of a set of N verbatims, and for doing it (a) she manually codes X of them for training a coding system, and (b) autocodes the remaining ($N - X$) via the trained system.

Note that curves tend to be increasing from left to right: this depends on the facts that (a) the higher the number X of training examples, the more accurate the trained system tends to be, and this impacts on how accurately the remaining ($N - X$) verbatims are coded; (b) the X verbatims chosen as training examples are manually (thus: correctly) coded, so the higher their number, the higher their impact on the accuracy of the entire set. This latter aspect also explains why accuracy is 1 when $X = N$, for all curves: in this case all verbatims in the dataset have been *manually* coded, no document requires autocoding, and accuracy is thus maximum.

Note that all our experiments have a random component, since (a) the batch passive learning experiments involve the random choice of a set of X

training examples, and (b) the incremental active learning experiments involve the random choice of the initial classifier. As a consequence, we have carried out each of our 497 binary classification experiments by running 10 different trials for each system setup. The curve that describes a system setup thus results from averaging across (a) the 10 curves corresponding to the 10 individual trials, and (b) the binary codes that compose the codeframe.

3.4.1. *What is the best value of k ?*

In this experiment we assume we want to train our classifier via active learning, and we want to establish what is the value of k that leads to the best accuracy. The plot in Figure 2 reports the results of a sample experiment in which we have tested the effect of different values of k (namely, those in $\{1, 5, 10, 50, 100\}$); the learning algorithm used is, of course, SVMs, since PA cannot use values of k higher than 1. The sample experiment has been carried out using the UNCERTAIN policy and the Reuters-21578(10) dataset; other choices of policy and/or dataset have returned similar results¹⁰, and will not be explicitly reported here for reasons of space.

The experimental results confirm what we had anticipated in Section 2.4, i.e., that the smaller the value of k is, the better active learning works; the optimal value of k is thus 1. In the experiments that follow we will thus fix the value of k to 1; this will prompt us to use an incremental (instead of a batch) learning algorithm, thus giving rise to what we call “interactive” learning.

3.4.2. *What is the best active learning policy?*

In order to let us appreciate the relative merits of batch passive learning and interactive (i.e., incremental active) learning, Figure 3 displays the results of running four different systems (batch passive learning, plus interactive learning instantiated with three different policies – RANDOM, MINMAX, UNCERTAIN). The curves represent F_1 as a function of the percentage of the dataset that has been used as training set, and report average F_1 across all our 6 groups of datasets. Note that, with $k = 1$, with batch passive learning we retrain the classifier *from scratch* every time a single training example is added to the training set, thus resulting in a considerable computational load.

There are a few conclusions that we may draw from these results:

1. In general, *batch passive learning is clearly inferior to interactive learning*, since the latter outperforms the former across the board (aside from the case in which interactive learning is run with the RANDOM policy, which we here only include as a reference and not as a serious contender). This means the ability, if using interactive learning, to obtain the same accuracy as batch passive learning with much less training effort (or: to obtain much higher accuracy for the same training effort), and to obtain this for any amount of training effort.

¹⁰ The exception is the RANDOM policy, whose accuracy is by and large independent of the value of k . This should come to no surprise, since with this policy the classifier does not influence the choice of verbatims to validate.

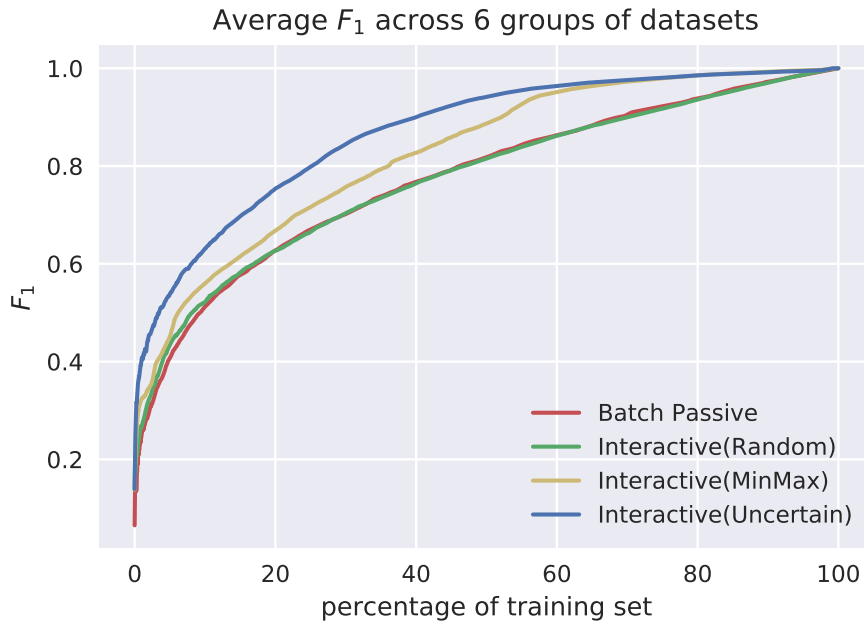


Figure 3. Accuracy, as a function of the percentage of the entire dataset that is used as training set, of (a) batch passive learning and (b) interactive learning using the 3 different policies of Section 2.5. Each point on a curve represents average accuracy across our 497 binary codes \times 10 random trials.

2. Batch passive learning has a similar performance as interactive learning (to the point that the two curves can be barely distinguished) when this latter is run with the RANDOM policy. This should come as no surprise, since both systems are based on a random (i.e., non informed) choice of training examples. When it comes to interactive learning, any policy that has a somehow intuitive rationale can be expected to outperform a “non-policy” such as RANDOM.
3. The UNCERTAIN policy performs substantially better than the MINMAX policy. This outcome is less obvious, but can be explained by the fact that verbatims on which the classifier is uncertain are, once validated, very informative, because they help the classifier handle the verbatims that it does not classify confidently, and would otherwise be most likely to misclassify. In contrast, the verbatims selected by the MINMAX policy (i.e., those on which the classifier is already confident) are less informative, since they merely have the function to reinforce beliefs that the classifier already firmly holds. In a sense, by being fed the training examples selected by the MINMAX policy, the classifier “keeps living in its own bubble”. As a recent article titled, “If you’re not outside your comfort zone, you won’t learn anything”.¹¹

¹¹ Andy Molinsky, “If you’re not outside your comfort zone, you won’t learn anything”, *Harvard Business Review*, July 29, 2016. <http://bit.ly/2ajjIzR>

3.4.3. Batch Passive Learning vs. Interactive Learning

We have thus determined that, when active learning is used, (a) $k = 1$ is the best setting (see Section 3.4.1) and (b) UNCERTAIN is the best policy for choosing the verbatim that the user should validate (see Section 3.4.2); in the interactive learning experiments reported from now on we will always stick to these two design choices.

Figure 4 experimentally compares batch passive learning with interactive learning on the six groups of datasets presented in Section 3.1. All of the

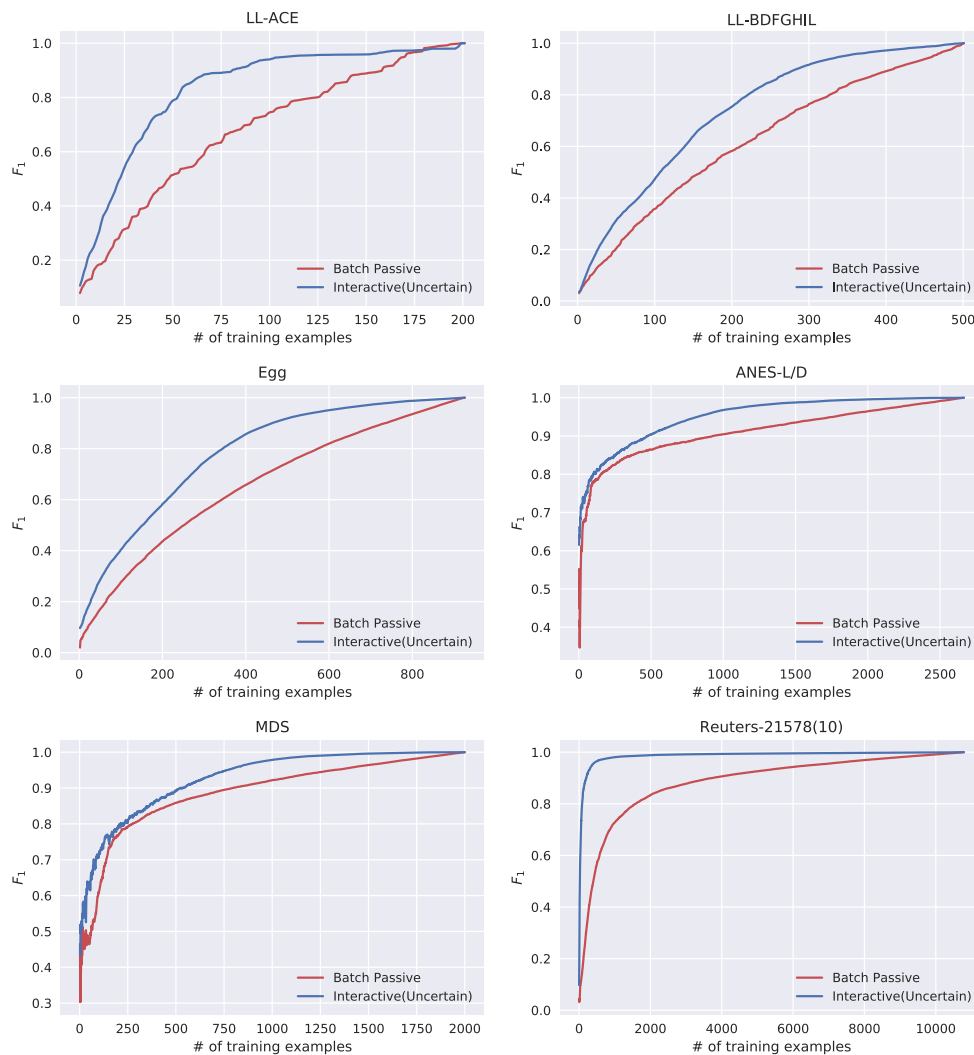


Figure 4. F_1 , as a function of the percentage of the entire dataset used as training set, of batch passive learning vs. interactive learning using the UNCERTAIN policy and $k = 1$. The six figures represent the six groups of datasets introduced in Section 3.1.

six subfigures of Figure 4 unequivocally confirm the superiority of interactive learning with respect to batch passive learning, which was the main working hypothesis of this paper. This means better accuracy with the same amount

of training effort, or less training effort in order to obtain the same level of accuracy.

Incidentally, this also means that the use of automated verbatim coding systems based on machine learning may become attractive even for small-sized studies (i.e., when the number N of verbatims that require coding is small). For instance, the top left subfigure of Figure 4, which is about the LL-ACE group of datasets (all consisting of 201 verbatims), shows that manually coding 75 of the 201 examples would result in approximately $F_1 = 0.62$ when using traditional (i.e., batch passive) learning; in this case, the effort of generating the training set arguably outweighs the benefits of having the rest of the dataset autocoded. When using interactive learning, instead, the same amount of effort leads to approximately $F_1 = 0.88$, which definitely makes automated coding more attractive.

3.5. EFFICIENCY

An important question that the very notion of interactive learning raises is that of efficiency, since it is of key importance that the entire sequence of steps of which one iteration consists (from user validating a verbatim to user receiving the next verbatim to validate) can be carried out in real time. Indeed, this problem is a potential show-stopper, since one iteration requires no less than (a) the classifier to be updated so as to incorporate the contribution of the validated verbatim, (b) all the (not-yet-validated) autocoded verbatims to be autocoded again by the newly updated classifier, and (c) all these verbatims to be evaluated so that the most promising one can be singled out for validation by the user in the next iteration.

In order to answer the question above, in Figure 5 we report, for each among the 6 groups of datasets, the maximum time that an iteration has requested for any dataset in the group¹². The histogram shows that execution times vary a lot across groups of datasets, even by two orders of magnitude; this is intuitive, since the number of verbatims that need to go through steps (b) and (c) of the above description varies a lot, from 201 (LL-ACE) to 10,788 (Reuters-21578(10)).

Still, the key observation is that these times are all very low; thanks to a highly optimized implementation, the *highest* execution time (required at the very beginning of the process – when practically all the verbatims in the dataset need to go thorough steps (b) and (c) – in processing Reuters-21578(10), a dataset of 10,788 verbatims) is about 0.02 seconds, which is fast enough for allowing a smooth interaction between user and machine. Since computation times are essentially linear in the number of verbatims that need coding, this would mean that with a dataset 50 times as large (i.e., $10,788 \times 50 = 539,400$ verbatims) we would still be able to run each iteration in under one second.

¹² The experiments were run on a commodity machine equipped with an 8-core processor AMD FX™-8350 with 32 GB of RAM under Ubuntu 16.04 (LTS).

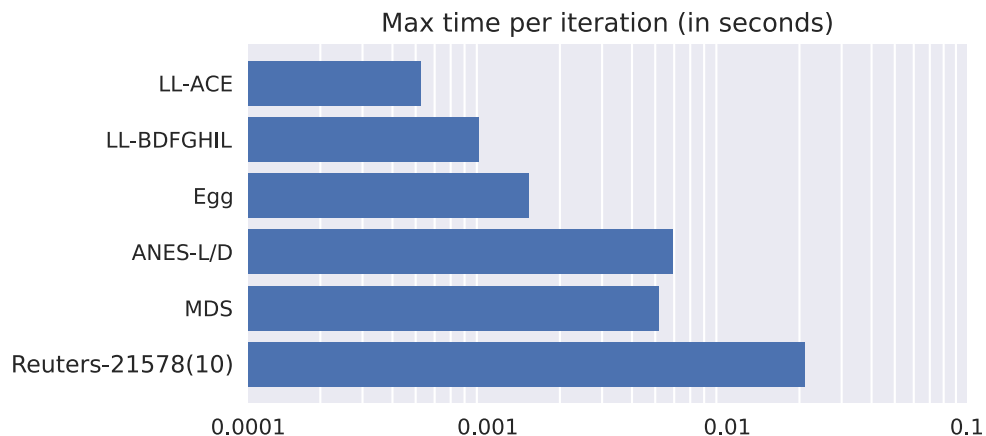


Figure 5. Maximum execution time (in seconds) of a single iteration of interactive learning for each of the 6 groups of datasets.

4. Classifier Reuse via Interactive Learning

The use of interactive learning is also beneficial for the purpose of reusing classifiers previously trained for different (albeit related) tasks. To see how, suppose we need to generate a classifier that codes verbatims as ‘Positive’ or ‘Negative’ (i.e., a sentiment classifier), where the verbatims have been returned following a specific question (hereafter called the *target* question – say, how the respondent liked a given restaurant). Suppose we already have (from a previous study) a classifier that also codes verbatims as ‘Positive’ or ‘Negative’, but trained on verbatims returned following a different question (the *source* question – say, what the respondent thinks about a given camera).

Given that the codes are the same, should we reuse the “source” classifier for coding our “target” verbatims? Just relying on the source classifier seems risky, since the two domains (restaurants and cameras) are presumably characterized by fairly different ways to express sentiment. However, since *some* ways of expressing sentiment can indeed be used for both domains (e.g., adjective “disastrous” conveys the same sentiment in both domains), it would seem attractive to reuse the source classifier and tailor it to the target question with target-specific training examples, instead of training a classifier from scratch by just using the target-specific training examples. But this is something we cannot do if our learning technology is of the “batch learning” type, since for training a classifier that uses both source and target information we would still need to access the source training examples, which may not be available anymore.

If our technology is of the “interactive learning” type, though, we can take the source classifier and incrementally update it by leveraging the target training examples. In doing so, we may expect the source classifier to provide an initial, suboptimal solution we can start from, and we may expect this solution to improve as the target-specific training examples are employed to refine it.

In order to check if this approach makes sense, we have run experiments on the four sentiment classification binary tasks (DVDs, Electronics, Kitchen, Books) of the MDS group of datasets mentioned in Section 3.1; the results are reported in Figure 6. For instance, in the ‘DVDs’ experiment (top left subfigure),

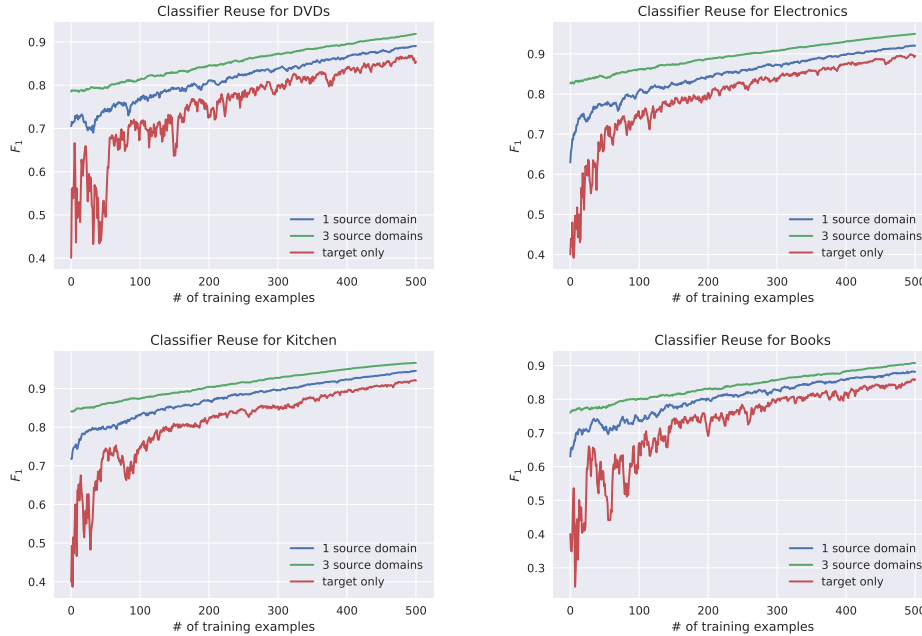


Figure 6. Experiments testing the impact of reusing classifiers trained on one or more (“source”) domains for performing sentiment classification on another (“target”) domain. The plot shows accuracies for the first 500 (out of a total of 2,000) target training examples only.

by using interactive learning we have

- trained a classifier using only ‘DVDs’ examples, resulting in the curve labelled “target only”;
- (a) trained three classifiers (one on ‘Electronics’, one on ‘Kitchen’, one on ‘Books’ – each of them using all the available verbatims from the respective datasets), (b) updated each of them incrementally by bringing to bear, one by one, the ‘DVDs’ examples, (c) evaluated the resulting accuracies on the remaining ‘DVDs’ examples, and (d) obtained the curve labelled “1 source domain” as the average of the three resulting curves;
- (a) trained a classifier on the union of the ‘Electronics’, ‘Kitchen’, and ‘Books’ verbatims, (b) updated it incrementally by bringing to bear, one by one, the ‘DVDs’ examples, (c) evaluated the resulting accuracy on the remaining ‘DVDs’ examples, resulting in the curve labelled “3 source domains”.

It is immediate to notice from the ‘DVDs’ subfigure of Figure 6 that (a) reusing a classifier previously trained on a different source domain (curve “1 source

domain”) may be highly beneficial, notwithstanding the semantic difference among the source and target domains, and (b) reusing a classifier previously trained on *several* different source domains at the same time (curve “3 source domains”) may be even more beneficial. For instance, if we had to start from scratch by using only target-specific training examples (curve “target only”), only by deploying the first 300 of them we would reach the accuracy that just using a classifier previously trained on three different source domains grants us. In other words, the source classifiers give us a very good base to begin with (with F_1 accuracy on the target data between 0.70 and 0.78), and updating them interactively by means of the target training examples allows accuracy to smoothly and systematically increase. The accuracy of the system that does not reuse any previous classifier rises more briskly, but (while getting close to it) is never able to reach the accuracy of the systems that do reuse previous classifiers. The ‘Electronics’, ‘Kitchen’, and ‘Books’ subfigures of Figure 6 essentially confirm the intuitions obtained from the results of the ‘DVDs’ experiment. Figure 7 reports the results of averaging across the four cases reported in Figure 6.

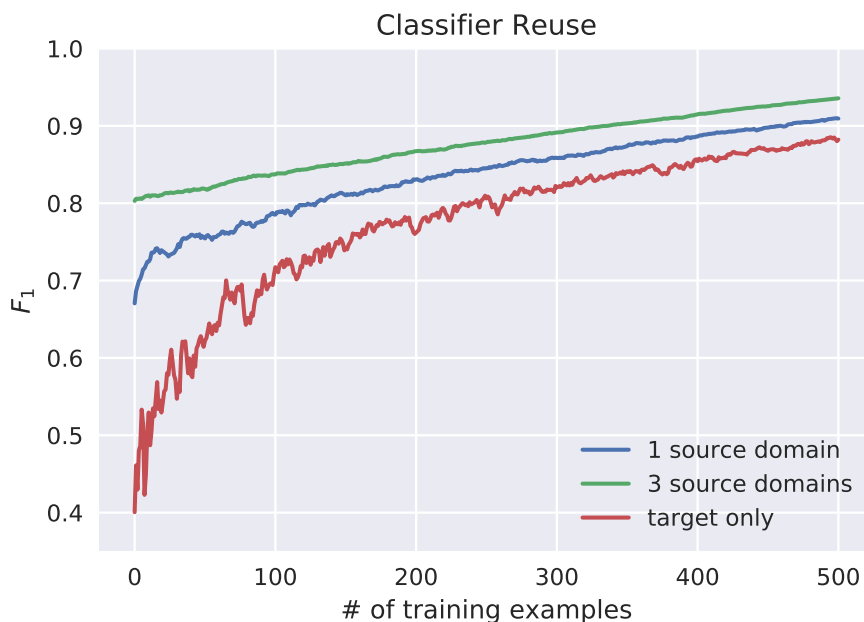


Figure 7. Experiments testing the impact of reusing classifiers; each curve is the average of the four corresponding curves in Figure 6.

Note that in order to reuse a classifier in the way exemplified here, what we only need is that the binary distinctions addressed in the source and target tasks are the same. While we have here exemplified this process in the case of classification by sentiment (‘Positive’ vs. ‘Negative’), we can do the same for classification by topic. For instance, the source task could consist in coding whether the reason for unhappiness of the customers of an online bank is or not the quality of the website, while the target task could consist of the same

for the customers of a telecom company. We plan to address the potential of classifier reuse more thoroughly in a future paper.

5. Related work

Automated survey coding. The use of computer systems that automatically code verbatims is widespread in market research practice; still, the literature on this topic is extremely scarce, which unfortunately indicates that little published experimental evidence exists as to which among the different approaches on the market is the best. Earlier attempts at automating the survey coding process were based on classifiers that were not machine-learned, but human-engineered; examples of this approach are the systems described in (Baek et al., 2011; Macchia and Murgia, 2002; Patil and Palshikar, 2013; Viechnicki, 1998). Manually engineering verbatim classifiers is disadvantageous, since manually writing the classification rules (or the dictionary entries) which are the essential building blocks of these classifiers is onerous, and is not necessarily conducive to high classification accuracy. As a result, the current tendency is to rely on the supervised machine learning approach.

Machine learning for automated survey coding. The idea to apply supervised machine learning to automating survey coding was first presented in (Giorgetti et al., 2003; Giorgetti and Sebastiani, 2003); these two papers discuss a single-label multi-class survey coding system based on support vector machines, and present experimental results obtained on data from the General Social Survey carried out by the US National Opinion Research Center (NORC). The same research group later introduced the first commercially available survey coding system based on machine learning, and discussed its application to coding verbatim answers obtained as a result of customer satisfaction surveys (Macer et al., 2007), market research surveys, or political surveys (Esuli and Sebastiani, 2010). Systems along the lines of the one of (Giorgetti and Sebastiani, 2003) are described in (Clarke and Brooker, 2011; Gamon, 2004; Mantecon et al., 2018; Spasić et al., 2018).

In (Berardi et al., 2014), the authors introduce a “semi-automated coding” system, i.e., a system in which coding by a machine-learned classifier is followed by a phase in which a user validates the verbatims that, when validated, bring about the highest expected improvement in the overall accuracy of the entire set; a utility-theoretic framework tailored on the adopted accuracy measure is employed to determine these expected improvements. Semi-automated coding is also discussed in (Schonlau and Couper, 2016); however, these authors rely on the user to decide the threshold that separates the verbatims that should be validated from the ones which should not, and this may exceed what should reasonably be expected from users. A semi-automated approach analogous to the latter is applied to occupation coding in (Schierholz, 2014).

All of the above works employ a traditional “batch learning” method, i.e., one in which the classifier is generated non-incrementally (the entire set of training examples are used in one shot) and via “passive learning” (i.e., the verbatims are chosen by the user, and not by the system).

Active learning and incremental learning. While the joint application of active learning and incremental learning in a survey coding scenario is new, neither active learning nor incremental learning *per se* are new in the field of machine learning. In particular, active learning goes back at least to (Angluin, 1988), and both the UNCERTAIN and MINMAX policy can be traced back to (Lewis and Gale, 1994); incremental learning, instead, even goes back to (Rosenblatt, 1958).

The use of active learning in automated survey coding was first proposed in (Esuli and Sebastiani, 2010). Differently from the present paper, and due to the use of a batch learning algorithm, in that work classifier retraining is performed anew every time an additional batch of k autocoded verbatims (instead of just a single autocoded verbatim) have been validated by the user. Additionally, in (Esuli and Sebastiani, 2010) active learning is used to improve a classifier originally trained on a batch of (randomly selected) verbatims, and not to generate the classifier right from the start. Another work in which active learning is used to improve a classifier (previously generated via batch learning) for responses to open-ended questions is (Patil and Ravindran, 2015).

We are not aware, instead, of any previous attempt to use incremental learning for survey coding applications.

6. Discussion and conclusions

When building an automatic verbatim coding system, interactive learning provides several advantages with respect to the “classic” learning metaphor based on passive learning + batch learning.

The use of active learning (instead of passive learning), i.e., the idea that it is the system’s (instead of the user’s) responsibility to decide which verbatims should be manually coded in order for them to be used as training data, delivers (for the same amount of training effort) substantially better accuracy, since the system can ask the user to manually code exactly those verbatims that, when used as additional training data, are estimated to provide the highest benefit to classifier retraining.

We have seen that the increase in accuracy (with respect to non-interactive learning systems) is especially high when the number of training items is low. Aside from showing that this allows automatic classifiers to perform respectably just after a few training examples have been provided, this also means that interactive learning is especially attractive for studies in which the annotation budget is low. This is the case, for instance, of small studies, since in studies characterized by a low number of verbatims that require coding, the number of training verbatims that are needed to bring about sufficient coding accuracy may be close (if “classic” systems are used) to the effort needed to manually code the entire set. In other words, interactive learning has the potential to make machine-learned classifiers amenable to dealing also with small studies, which is not the case in the realm of batch passive learning.

The accuracy of classifiers trained via active learning increases, quite obviously, with the frequency of retraining operations. Most active learning litera-

ture assumes that retraining is performed every time k new training examples are available, with k usually in the dozens or in the hundreds; retraining every time a single new training example is available is the ideal situation for active learning (we might view this as a form of “extreme active learning”), but incurs severe computational costs when traditional “batch learning” technology (that retrains the classifier anew from the entire training set) is used. The adoption of incremental learning technology makes it straightforward to retrain every time a new training item is available, since incremental learning is exactly about updating a previously trained classifier by bringing to bear a single new training example. Our experiments, which we have carried out across a set of binary datasets and multi-label multi-class datasets, have shown consistent and substantive accuracy improvements with respect to “standard” batch passive learning. While we have not run tests on single-label multi-class classification, everything we have said about interactive learning straightforwardly extends to it.

Interactive learning can be efficient: we have shown that the entire cycle triggered by the validation of the chosen autocoded example (i.e., “update classifier” → “autocode all uncoded verbatims” → “choose autocoded verbatim for the user to validate”) can be performed (on datasets of several thousands verbatims) in a fraction of a second, thus allowing the user to carry on her validation activity smoothly, and without even realizing that uncoded verbatims are all re-coded every time she validates a verbatim. The result is a “train-while-u-code” system, i.e., a learning process that integrates much better in the typical workflow of the survey specialist, which may perform her manual coding activity without even realizing that a machine learning process is ongoing. Rather than a “human in the loop” computerized system, interactive learning implements a “machine in the loop” workflow for the survey specialist, who thus remains at center stage.

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