# Multilevel functional principal component analysis of façade sound insulation data

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#### Abstract

This work analyses data from an experimental study on façade sound insulation, consisting of independent repeated measurements executed by different laboratories on the same residential building. Mathematically, data can be seen as functions describing an acoustic parameter varying with the frequency. The aim of this study is twofold. On one hand, considering the laboratory as the grouping variable, it is important to assess the within and between group variability in the measurements. On the other hand, in building acoustics it is known that sound insulation is more variable at low frequencies (from 50 to 100 Hz), compared to higher frequencies (up to 5000 Hz), and therefore a multilevel functional model is employed to decompose the functional variance both at the measurement and at the group level. This decomposition also allows for the ranking of the laboratories on the basis of measurement variability and performance at low frequencies (relative high variability) and over the whole spectrum. The former ranking is obtained via the principal component scores and the latter via an original Bayesian extension of the functional depth.

Keywords: façade sound insulation; repeatability and reproducibility; multilevel functional data analysis; functional depth; Bayesian functional regression.

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### 1 Introduction

Building acoustic tests on samples, which are presumably made of the same materials, in identical conditions, generally do not give the same results. This condition is due to inevitable errors (systematic and random) in test procedures, caused by the difficulties in controlling the several factors that influence the test, such as acoustic instrumentation, acoustic method (microphones and sources position), context (regular rooms or semi-open space, with different dimensions), constructive details of the building (that could have effect on acoustic measurements) and workmanship and, concerning sound levels, influence of instrumentation operating conditions (repeat configuration).

In general, uncertainties should preferably be determined following the ISO/IEC Guide 98- 3.<sup>3</sup> This guide specifies a detailed procedure for the uncertainty evaluation that is based on a complete mathematical model of the measurement procedure. According to the current knowledge, it seems impossible to formulate these models for the different quantities in building acoustics. Therefore, to determine the uncertainty of building acoustics measurements, concepts as repeatability and reproducibility are needed. Repeatability (of results of measurements) is the closeness of the agreement between the results of successive measurements of the same measurand carried out under the same conditions of measurement. In statistical language, repeatability is quantified by the within-laboratory standard deviation. Reproducibility (of results of measurements) is the closeness of the agreement between the results of measurements of the same measurand carried out under changed conditions of measurement, quantified by the sum of the within-laboratory and of the between-laboratory variances, under square root. The best way to study the repeatability and reproducibility of building acoustics field measurements is to carry out a Round Robin Test (RRT), which consists of several independent measurements performed by different laboratories.

Each single measurement is summarized by an acoustic index, which is assumed as the response of a one-way random effects model. The general mean of all measurements provides an estimate of a reference value for this index, whereas the repeatability and reproducibility arrors are estimated by the usual formulae involving the within and between laboratory sums of squares. As pointed out by Scrosati et  $al.$ <sup>4</sup>, the uncertainty of field measurements, particularly in façade sound insulation, has not been investigated comprehensively in the past. In this work, we examine the information contained in the measurement in a more general approach, instead of analysing single-index summaries.

Each RRT measurement yields a value for each one of the 21 given frequency bands. And provides a discrete sampling from a function defined on frequencies domain. Therefore, because the data are functions (of the frequency), we utilize the Functional Data Analysis (FDA), as a suitable statistical framework. The FDA, firstly introduced by Ramsay and Silverman, defines a branch of statistics which has been receiving increasing interest in the last years. Functional data analysis is closely related to multivariate data analysis because it deals with highly multivariate objects. However, FDA mainly differs from multivariate data analysis for the intrinsic order of the observations, which can be related to time, space, as for time series or images, or frequency, which is our case. It regards data that are records of values reflecting a smooth variation so that their sampling intervals could be as small as desired. It is therefore natural to assume the existence of smooth functions (*functional data*) giving rise to the observed data. For an overview of the topic, see the two monographs by Ramsay and Silverman<sup>5,6</sup> and citations provided therein.

Two general areas can be considered in the framework of FDA: functional linear models, which include *Functional ANalysis Of VAriance* (FANOVA) and *Functional Principal Com*ponent Analysis (FPCA). FANOVA is useful when a natural hierarchy of units is present in order to obtain functional decomposition. A rich collection of inferential methods for functional linear models can be found in the statistical literature, as a result of a relevant methodological research effort. For instance, Brumback and Rice<sup>7</sup> introduce smoothing spline models for nested and crossed curves, Guo<sup>8</sup> discusses functional mixed effects models, Morris et al.<sup>9, 10</sup> propose Bayesian wavelets models, Bigelow and Dunson<sup>11</sup> introduce Bayesian adaptive regression splines, Baladandayuthapani et al.<sup>12</sup> analyze Bayesian models for spatially correlated functional data.

FPCA is aimed to identify the most important modes of variation in the data and it can also be useful for dimensional reduction. In a nutshell, a suitable orthogonal basis is built so that the coordinates of each functional datum represent the amount of variation in the functional principal directions. For further details about FPCA, see Ramsay and Dalzell,<sup>13</sup>

Silverman,<sup>14</sup> James et al.,<sup>15</sup> Yao et al.,<sup>16</sup> and also Hall and Hosseini–Nasab,<sup>17</sup> besides Ramsay and Silverman.<sup>6</sup>

Both these two general areas provide appropriate tools to fit the acoustic data in this paper. In particular, we expect higher variability on some sub–spectra of the frequency. As known in the engineering literature, acoustic indexes usually show the higher variability at the lower frequencies, high variability is also expected at some other specific frequency bands, due to the framework of the experiment (i.e. some particular features of the experimental building). FPCA is suitable to capture this behaviour. On the other hand, our data are characterized by a natural hierarchy due to RRT, which makes the FANOVA the routine choice. In fact, FANOVA can decompose the total covariance into the within laboratory and the between laboratory covariance. In this way, one can analyze reproducibility and repeatability as generally done in the engineering literature, but in a functional framework. In ligth of these considerations, a model is needed that is capable of tackling both aspects of the data. Such model should extend the classical FDA to the multilevel functional data analysis. This need has motivated a number of paper. See, for instance, Baladandayuthapani et al.,  $^{12}$  Di et al.,  $^{18}$ Guo,<sup>8</sup> Morris et al.,<sup>9</sup> Morris and Carroll,<sup>10</sup> Crainiceanu et al,<sup>19</sup> Staicu et al.<sup>20</sup>

Here, following Di et al.,<sup>18</sup> a Bayesian *Multilevel Functional Principal Component Analysis*  $(MFPCA)$  is implemented (see also Crainiceanu and Goldsmith<sup>21</sup>). Indeed, as argued by Crainiceanu and Goldsmith, $^{21}$  Bayesian analysis is particularly appropriate when dealing with mixed models representations. Moreover, Bayesian simulation algorithms work very well in the context of FDA due to the orthogonality of the principal components and the possibility to reduce the computational effort by using a Gibbs sampler (carried out within  $JAGS<sup>22</sup>$  to obtain posterior statistics.

Finally, the MFPCA is also used to rank the laboratories according to their estimated performances. Such performances are represented by the laboratory–specific mean functions. In particular, the depth concept is used to order curves from the center outwards. In this paper, the modified band depth of Lopez-Pintado and Romo<sup>23</sup> is generalized into a probabilistic setting to obtain a population version. The probabilistic modified band depth is then used to compute the functional  $p$ –th central region introduced by Sun and Genton.<sup>24</sup> To the best of our knowledge, there exists only a sample version of the modified band depth; the population version is needed for the posterior of the depths of the laboratory–specific means to be well defined and computed in a Bayesian framework. Moreover, depth is also used to define the credible posterior bounds of the functional parameters of interest.

The outline of this paper is as follows: Section 2 describes the data; Section 3 and 4 introduce FPCA and MFPCA, respectively; Section 5 deals with functional depths; Section 6 reports the data analysis; Section 7 presents the robustness analysis; Section 8 compares the point and functional approaches; Section 9 draws the conclusions of the analysis.

#### 2 Acoustic data

The RRT was carried out by nine teams on an existing experimental building located at ITC-CNR headquarters, made of prefabricated concrete panels. The tested building element is a prefabricated concrete façade with a 4 mm single glazing wood-aluminium frame window with a medium density fibreboard (MDF) shutter box. The façade is situated at the first floor and has a surface of 8.6 m<sup>2</sup>. The receiving room is a rectangular room of 54.5 m<sup>3</sup> volume.

Each team measured the standardised level difference of façade  $D_{2m,nT}$ , which is the level difference in decibels corresponding to a reference value of the reverberation time in the receiving room. The level difference is the difference (in decibels) between the outdoor sound pressure level 2m in front of the façade and the pressure level in the receiving room, averaged over time and space.

Each team was coordinated by ITC-CNR, but used its own procedures and equipment. However, a laboratory that showed a significant presence of stragglers and outliers in a previous analysis<sup>4</sup> was excluded.

Therefore the data consist of forty measurements of  $D_{2m,nT}$ : five measurements performed by each one of the eight certified teams involved in the RRT. Each measurement can be considered as the discretization of a function on the interval [50 Hz, 5000 Hz] (Fig. 1). In particular, 21 values at the 21 one-third/octave bands are taken (i.e., 50; 63; 80; 100; 125; 160; 200; 250; 315; 400; 500; 630; 800; 1000; 1250; 1600; 2000; 2500; 3150; 4000; 5000). In other words, these measureaments are regarded as multilevel functional data, constituting one of the motivations for multilevel principal component analysis already mentioned in the introduction.

### 3 Introduction to functional principal component analysis

To be self–contained, we now recall the mathematical theory on which the statistical models used in this paper are based. The mathematical basis for functional principal component analysis consists of two important results in functional analysis: Mercer's representation theorem and Karhunen–Loève expansion. Let I be a closed interval in R. Recall that  $L^2(I)$ is the space of Lebesgue square–integrable functions on  $I$ , i.e. of all functions  $f$  on  $I$  such that  $\int f(x)^2 dx$  exists and is finite. Moreover,  $L^2(I)$  is a Hilbert space with inner product  $\langle f, g \rangle = \int f(t)g(t)dt$ , and norm  $||f|| = \int_I |f(t)|^2 dt$ . Let  $X = \{X(t) : t \in I\}$  be a random element of  $L^2(I)$  such that

$$
\mathbb{E}\{\|X\|^2\} = \mathbb{E}\left\{\int_I X^2(t)\mathrm{d}t\right\} < \infty.
$$

Moreover let  $\mu(t) = \mathbb{E}\{X(t)\}\$ and  $K(s,t) = \text{Cov}\{X(s), X(t)\}\$ ,  $t, s \in I$ , be the mean function and the *covariance function*, respectively. The *covariance operator*  $C$  is defined as:

$$
C(f)(t) = \mathbb{E}\{\langle X - \mu, f \rangle(X(t) - \mu(t))\}
$$

$$
= \int_I K(s, t) f(s) \, ds,
$$

for every function f in  $L^2(I)$  and  $t \in I$ . By Mercer's theorem, the following spectral decomposition of the covariance function holds true:

$$
K(s,t) = \sum_{k=1}^{\infty} \lambda_k \varphi_k(s) \varphi_k(t), \qquad (1)
$$

where  $\varphi_k$  are the eigenfunctions of C and  $\lambda_1 \geq \lambda_2 \geq \ldots$  the corresponding eigenvalues, i.e. the  $\phi_k$ 's are orthonormal functions in  $L^2$  such that  $C(\varphi_k) = \lambda_k \varphi_k$ , for  $k \geq 1$ . The functions  $\varphi_k$ 's are the *principal components* of X. Indeed, (1) is equivalent to:

$$
C(f)(t) = \int \left(\sum_{k=1}^{\infty} \lambda_k \varphi_k(s) \varphi_k(t)\right) f(s) \mathrm{d}s = \sum_{k=1}^{\infty} \lambda_k \left(\int f(s) \varphi_k(s) \mathrm{d}s\right) \varphi_k(t).
$$

The following is the Karhunen–Loève representation for the random element X:

$$
X(t) = \mu(t) + \sum_{k=1}^{\infty} \xi_k \varphi_k(t),
$$
\n(2)

where

$$
\xi_k = \int \{X(t) - \mu(t)\} \varphi_k(t) dt \tag{3}
$$

are zero–mean uncorrelated random variables such that  $Var(\xi_k) = \lambda_k, k \ge 1$ , which are called *principal components scores*. The Karhunen–Loève representation  $(2)$  entails that:

$$
\int \text{Var}\{X(t)\} \mathrm{d}t = \sum_{k \ge 1} \text{Var}(\xi_k) = \sum_{k \ge 1} \lambda_k.
$$

#### 4 Multilevel functional principal component analysis

The multilevel functional principal component analysis, firstly introduced by Di et al.,<sup>18</sup> refers to the following functional random effects model:

$$
X_{i,j}(t) = \mu(t) + Z_i(t) + W_{i,j}(t),
$$

where  $X_{i,j}(t)$  is the j-th measurement of the *i*-th laboratory related to the t Hz frequency, for  $i \in \{1, ..., 8\}, j \in \{1, ..., 5\}, t$  ranges in the interval [50 Hz, 5000 Hz],  $\mu(t)$  is the overall mean function,  $Z_i(t)$  is the laboratory–specific deviation from the mean, and  $W_{i,j}(t)$  is the residual laboratory– and measurement–specific deviation from the laboratory–specific mean. The random processes  $(Z_i(t))_t$ ,  $(W_{l,j}(t))_t$  are mean–zero pairwise uncorrelated processes, for  $i, l \in \{1, ..., 8\}, j \in \{1, ..., 5\}.$  Let  $K_T(t, s) = \text{Cov}(X_{i,j}(t), X_{i,j}(s))$  be the total covariance,  $K_B(t,s) = \text{Cov}(Z_i(t), Z_i(s))$  the between covariance and  $K_W(t,s) = \text{Cov}(W_{i,j}(t), W_{i,j}(s))$ the within covariance. Of course,  $K_T(t, s) = K_B(t, s) + K_W(t, s)$ .

Level-one  $\phi_k^{(1)}$  $\chi_k^{(1)}(t)$  and level–two  $\phi_l^{(2)}$  $\binom{z}{l}(t)$  principal components are the eigenfunctions that arise from the spectral decomposition of the between covariance function:

$$
K_B(s,t) = \sum_{k=1}^{\infty} \lambda_k^{(1)} \varphi_k^{(1)}(s) \varphi_k^{(1)}(t),
$$

and the within covariance function:

$$
K_W(s,t) = \sum_{l=1}^{\infty} \lambda_l^{(2)} \varphi_l^{(2)}(s) \varphi_l^{(2)}(t),
$$

where  $\lambda_k^{(1)}$  $\lambda_l^{(1)}$  and  $\lambda_l^{(2)}$  $\ell_i^{(2)}$ ,  $k, l \geq 1$  are level–one and level–two eigenvalues, respectively. Note that  $\{\varphi_k^{(1)}\}$  $k^{(1)}_k : k \geq 1$ , { $\varphi_l^{(2)}$  $\ell_i^{(2)}$ :  $l \geq 1$  are orthonormal bases in  $L^2(T)$ , but are not required to be mutually orthogonal.

The Karhunen-Loève expansions of the functions  $Z_i$  and  $W_{i,j}$  are:

$$
Z_i(t) = \sum_{k=1}^{\infty} \xi_{i,k} \varphi_k^{(1)}(t), \qquad W_{i,j}(t) = \sum_{l=1}^{\infty} \zeta_{i,j,l} \varphi_l^{(2)}(t), \tag{4}
$$

for  $i \in \{1,\ldots,8\}, j \in \{1,\ldots,5\}$ . The corresponding eigenvalues are denoted by  $\lambda_k^{(1)}$  $k^{(1)}$  and  $\lambda_l^{(2)}$ <sup>(2)</sup>,  $k, l \geq 1$ . Level–one and level–two principal component scores are  $\xi_{i,k} = \int \phi_k^{(1)}$  $_{k}^{(1)}(t)Z_{i}(t)dt$ and  $\zeta_{i,j,l} = \int \phi_l^{(2)}$  $\chi_l^{(2)}(t)W_{i,j}(t)dt$ , respectively. Recall that  $\text{Var}(\xi_{i,k}) = \lambda_k^{(1)}$  $\lambda_k^{(1)}$  and  $\text{Var}(\zeta_{i,j,l}) = \lambda_l^{(2)}$  $\binom{2}{l}$ for every  $i, j, k, l$ . Moreover,

$$
\int \text{Var}(X_{i,j}(t))dt = \sum_{k\geq 1} \lambda_k^{(1)} + \sum_{l\geq 1} \lambda_l^{(2)},
$$

for every  $i, j$ . For each k and l, the proportions of the variance explained by the k–th level–one and the *l*-th level-two principal component are  $\lambda_k^{(1)}$  $_{k}^{\left( 1\right)}/\sum_{k\geq1}\lambda_{k}^{\left( 1\right) }$  $\lambda_l^{(1)}$  and  $\lambda_l^{(2)}$  $\lambda_l^{(2)}/\sum_{l\geq 1}\lambda_l^{(2)}$  $l^{(2)}$ , respectively. A natural measure of the variance explained by the between laboratories variability is the ratio:

$$
\frac{\int \text{Var}(Z_i(t))dt}{\int \text{Var}(Z_i(t))dt + \int \text{Var}(W_{i,j}(t))dt} = \frac{\sum_{k \ge 1} \lambda_k^{(1)}}{\sum_{k \ge 1} \lambda_k^{(1)} + \sum_{l \ge 1} \lambda_l^{(2)}},\tag{5}
$$

which is called *functional intra–cluster correlation*. Indeed, it measures how measurements made in the same laboratory are close to each other. Such value can be easily estimated plugging in the estimated values of the eigenvalues.

Denoting the observed data by  $Y_{i,j}(t)$  and introducing an uncorrelated noise component, as in Di et al., $^{18}$  we assume that

$$
Y_{i,j}(t) = X_{i,j}(t) + \varepsilon_{i,j}(t)
$$

holds, where  $\varepsilon_{i,j}(t)$  is a white noise process with variance  $\sigma^2$ . The covariance functions are then defined as follows:

$$
G_T(t,s) = \text{Cov}(Y_{i,j}(t), Y_{i,j}(s)),
$$
  
\n
$$
G_B(t,s) = \text{Cov}(Y_{i,j}(t), Y_{i,k}(s)).
$$

Hence

$$
G_T(t,s) = K_T(t,s) + \sigma^2 \mathbb{I}_{\{t=s\}}(t,s),
$$
  
\n
$$
G_B(t,s) = K_B(t,s).
$$

At this stage, without underlying the minor differences with the approach of Di et al.,<sup>18</sup> the details of our procedure are summarized in the following steps:

- 1. By penalized spline smoothing, we obtain the estimate  $\hat{\mu}(t)$  for  $\mu(t)$ ;
- 2. We obtain the estimates  $\hat{G}_T(t_s,t_r)$ ,  $\hat{G}_B(t_s,t_r)$  by the methods of moments, for  $s, r =$  $1, \ldots, 21$ , being  $t_1, \ldots, t_{21}$  the one-third/octave bands frequencies;
- 3. We obtain the estimate  $\hat{K}_B(t, s)$  by smoothing  $\hat{G}_B(t_s, t_r)$  (we fit semiparametric regression models using the mixed model representation of penalized splines via the SemiPar package of the  $R$  software);
- 4. We obtain the estimate  $\hat{K}_T(t,s)$  by smoothing  $\hat{G}_T(t_s,t_r)$  (as in the previous step) for  $t_s \neq t_r$ , i.e. dropping diagonal elements;
- 5. We obtain the estimate  $\hat{K}_W(t,s) = \hat{K}_T(t,s) \hat{K}_B(t,s);$
- 6. We use eigenanalysis on  $\hat{K}_B(t,s)$  to obtain  $\hat{\varphi}_k^{(1)}$  $_{k}^{(1)}(t)$ , and  $\hat{\lambda}_{k}^{(1)}$  $\binom{1}{k}$  (this is done by computing eigenvectors and eigenvalues of the matrix obtained evaluating  $\hat{K}_{B}(t, s)$  on a fine grid);
- 7. Similarly, we use eigenanalysis on  $\hat{K}_W(t,s)$  to obtain  $\hat{\varphi}_l^{(2)}$  $\hat{\lambda}_l^{(2)}(t)$  and  $\hat{\lambda}_l^{(2)}$  $\binom{2}{l}$  (remark: since  $\hat{K}_W$  is obtained by difference, it cannot be positive definite; we handle this problem by trimming eigenvalue–eigenvector pairs with negative eigenvalue – see, for instance,  $Hall<sup>25</sup>$ ).

Then, we select  $K_1$  level–one principal components to keep as follows

$$
K_1 = \min\{k : \rho_k \ge 0.99, \hat{\lambda}_k^{(1)} < 1/21\},\tag{6}
$$

where

$$
\rho_k = \sum_{h=1}^k \hat{\lambda}_h^{(1)} / \sum_{h \ge 1} \hat{\lambda}_h^{(1)}.
$$

In the same way, we employ  $\hat{\lambda}_l^{(2)}$  $\binom{2}{l}$  to calculate the number  $K_2$  of level–two principal components to keep.

Recall that  $\{\varphi_k^{(1)}\}$  $k^{(1)}_k : k \geq 1$ ,  $\{\varphi_l^{(2)}\}$  $\ell_i^{(2)}$  :  $l \geq 1$  are not required to be mutually orthogonal. This makes the score estimation more difficult for the multilevel model than for the basic model introduced in Section 3. The latter model allows for a straightforward estimation of scores on the basis of (3) simply by approximating the integral:

$$
\int \{X_i(t) - \hat{\mu}(t)\}\hat{\varphi}_k(t)dt
$$

where  $\hat{\varphi}_k(t)$ ,  $k = 1, \ldots, K$ , are the estimated principal components. In the multilevel model, eigenvalues are functionals of the processes  $Z_i(t)$  and  $W_{i,j}(t)$ , as derived after (4), which are not directly observed.

To estimate eigenvalues and scores we employ the following Bayesian model:

$$
Y_{i,j}(t) = \mu(t) + \sum_{k=1}^{K_1} \xi_{i,k} \varphi_k^{(1)}(t) + \sum_{l=1}^{K_2} \zeta_{i,j,l} \varphi_l^{(2)}(t) + \varepsilon_{i,j}(t),
$$

where  $\mu(t), \varphi_k^{(1)}$  $\chi_k^{(1)}(t)$  and  $\varphi_l^{(2)}$  $\hat{\mu}_{l}^{(2)}(t)$  are substituted by the previously derived estimates  $\hat{\mu}(t)$ ,  $\hat{\varphi}_{k}^{(1)}$  $_{k}^{(1)}(t)$ and  $\hat{\varphi}_{l}^{(2)}$  $\ell_l^{(2)}(t)$  and t ranges in the experimental set of the one-third/octave bands frequencies, i.e.,  $\{t_1, \ldots, t_{21}\}$ . The marginal prior of the vector of parameters is assessed according to the following conditionally independent hierarchical model, where the symbol ⊥⊥ denotes independence:

$$
\xi_{i,k} | \Lambda_k^{(1)} \stackrel{iid}{\sim} N(0, \Lambda_k^{(1)}) \perp \xi_{i,j,l} | \Lambda_l^{(2)} \stackrel{iid}{\sim} N(0, \Lambda_l^{(2)}),
$$
  
\n $i = 1, ..., 8; k = 1, ..., K_1; j = 1, ..., 5; l = 1, ..., K_2;$   
\n
$$
\Lambda_k^{(1)} \stackrel{iid}{\sim} \text{inv-gamma}(\alpha_{1,k}, \beta_{1,k}) \perp \Lambda_l^{(2)} \stackrel{iid}{\sim} \text{inv-gamma}(\alpha_{2,l}, \beta_{2,l}),
$$
  
\n $k = 1, ..., K_1; l = 1...K_2.$   
\n $\varepsilon_{ij}(t) | \sigma^2 \stackrel{iid}{\sim} N(0, \sigma^2), t = t_1, ..., t_{21}; i = 1, ..., 8; j = 1, ..., 5;$   
\n $\sigma^2 \sim \text{inv-gamma}(\alpha_3, \beta_3).$  (7)

The Bayesian model is fully specified by suitable choice of the hyperparametes, here we fixed:

$$
\alpha_{1,k} = (\hat{\lambda}_k^{(1)})^2 / \sigma_{\lambda}^2 + 2, \qquad \beta_{1,k} = \hat{\lambda}_k^{(1)} \cdot ((\hat{\lambda}_k^{(1)})^2 / \sigma_{\lambda}^2 + 1),
$$
  

$$
\alpha_{2,l} = (\hat{\lambda}_l^{(2)})^2 / \sigma_{\lambda}^2 + 2, \qquad \beta_{2,l} = \hat{\lambda}_l^{(2)} \cdot ((\hat{\lambda}_l^{(2)})^2 / \sigma_{\lambda}^2 + 1),
$$

while  $\alpha_3$  and  $\beta_3$  are chosen to fix a large prior variance for  $\sigma^2$  (non-informative prior). Under this setting, the prior means of the hyperparameters  $\Lambda_k^{(1)}$  and  $\Lambda_l^{(2)}$  are equal to the obtained eigenvalues of the between and within covariance functions, i.e.  $\hat{\lambda}_k^{(1)}$  $\hat{\lambda}_k^{(1)}$  and  $\hat{\lambda}_l^{(2)}$  $\binom{z}{l}$  $k = 1, \ldots, K_1, l = 1, \ldots, K_2$ , and their prior variance is  $\sigma_{\lambda}^2$ . The posterior distribution of  $(\Lambda_1^{(1)}, \ldots, \Lambda_{K_1}^{(1)})$  $\chi_1^{(1)}, \Lambda_1^{(2)}$  $\stackrel{(2)}{1},\ldots,\stackrel{(2)}{K_2}$  $K_{K_2}^{(2)}$  induces a posterior on  $K_B(s,t)$  and  $K_W(s,t)$  through the truncated spectral representation (1), having fixed the eigenfunctions as  $\hat{\varphi}_{k}^{(1)}$  $k^{(1)}$ ,  $k = 1, \ldots, K_1$ , and  $\hat{\varphi}_{l}^{(2)}$  $l_1^{(2)}$ ,  $l = 1, \ldots, K_2$ . In the following, when we use the Bayesian estimates (the posterior means)  $\tilde{\lambda}_k^{(1)}$  $\lambda_k^{(1)}$  and  $\tilde{\lambda}_l^{(2)}$  $\ell_l^{(2)}$ , these will be legitimately called the eigenvalues of the estimated covariance operators identified by equation (10).

#### 5 Functional depths

To rank functional data, functional depths have been introduced as measures of centrality (see for instance Fraiman and Muniz,  $2^6$  Lopez-Pintado and Romo,  $2^3$  Sun and Genton<sup>24</sup>). Among them, we refer in particular to the *modified band depth*, which has been introduced by Lopez-Pintado and Romo<sup>23</sup> and also studied by Sun and Genton.<sup>24</sup> The basic idea is based on a graphical approach. The band  $B(y_1, y_2)$  delimited in  $I \times \mathbb{R}$  by the two given curves  $y_1(t)$  and  $y_2(t)$  is defined as  $\{(t, y(t)) : \min\{y_1(t), y_2(t)\} \le y(t) \le \max\{y_1(t), y_2(t)\}\}.$ Given a random curve, i.e. a stochastic process,  $Y(t)$ , the band depth for a given curve  $y(t)$ is  $P(\{(t, y(t)) : t \in I\} \subset B(Y_1, Y_2)$ , where  $Y_1(t)$  and  $Y_2(t)$  are two independent copies of the stochastic process  $Y(t)$  generating the observations  $y_1(t), \ldots, y_N(t)$ . Here, we consider a more flexible definition based on the proportion of the domain I where a curve  $y(t)$  is in the band. Formally, we consider the set:

$$
A(y; y_1, y_2) = \{t \in I : \min\{y_1(t), y_2(t)\} \le y(t) \le \max\{y_1(t), y_2(t)\}\}.
$$

Hence, the modified band depth for a given curve  $y(t)$  can now be defined as:

$$
MBD(y) = \mathbb{E}\left(\frac{\lambda(A(y; Y_1, Y_2))}{\lambda(I)}\right),\tag{8}
$$

where  $\lambda$  is the Lebesgue measure. Letting T be an uniform random variable on I independent of  $Y(t)$ , (8) becomes:

$$
\text{MBD}(y) = P(\min\{Y_1(T), Y_2(T)\} \le y(T) \le \max\{Y_1(T), Y_2(T)\}).
$$

The depth defined by (8) is the probabilistic generalization of the sample modified band depth introduced by Lopez–Pintado and Romo, $^{23}$  which is:

MBD<sub>N</sub>(y) = 
$$
\frac{2}{N(N-1)} \sum_{1 \le i_1 < i_2 \le N} \frac{\lambda(A(y; y_{i_1}, y_{i_2}))}{\lambda(I)}
$$
.

Through functional depths, Sun and  $Genton<sup>24</sup>$  generalize the concepts of quantiles, interquantile range to the functional data setting. Moreover, they introduce the functional boxplot through the concept of central region introduced by Liu et al.<sup>27</sup> The idea of Liu et al.<sup>27</sup> about Euclidean spaces can be easily generalized to the functional setting as follows. Let us define the *p*–th central region, for  $0 < p < 1$ , as:

$$
C_p = \bigcap_t \{ R(t) : P(R(t)) \ge p \},\
$$

where  $R(t) = \{y \in L^2(I) : \text{MBD}(y) > t\}$  is the region enclosed by the contour of depth t. In other words,  $C_p$  is the smallest region enclosed by depth contours to amass probability p. Sun and Genton<sup>24</sup> use then the idea of Liu et al.<sup>27</sup> to define the sample  $50\%$  central region and to built functional boxplots. Given the observed curves,  $y_1, \ldots, y_N$ , we can order them on the basis of their depths  $y_{(1)}, \ldots, y_{(N)}$ . So,  $y_{(1)}$  is the deepest (most central) curve, which is referred to as the *median curve* in the literature and  $y_{(N)}$  is the most outlying curve. In general,  $y_{(i)}$  denotes the sample curve associated with the the *i*-th largest band depth value. Hence, the sample  $p$ -th central region can be defined as as the band delimited by the most central fraction  $p$  of the observed curves, that is:

$$
C_{N,p} = \left\{ (t, y(t)) : \min_{r=1,\dots,\lfloor Np \rfloor} y_{(r)}(t) \leq y(t) \leq \max_{r=1,\dots,\lfloor Np \rfloor} y_{(r)}(t) \right\},\tag{9}
$$

where  $x \mid x$  denotes the floor of x, i.e., the greatest integer smaller than or equal to x, for any real x. If  $p = 1/2$ , one obtains the 50% central region, which is the band delimited by the most deepest half of the observed curves. Such region is the analog to the "InterQuantile Range" (IQR) and gives a useful indication of the spread of the central 50% region of the curve.<sup>24</sup> Moreover, as one could expect, it will be crucial to construct functional boxplots. We point out that in order to define the  $50\%$  central region, the more intuitive choice of simply calculating the quantiles pointwise should be avoided. In this way, the information about the shape of the curves would be lost. The median curve, which can be obtained by joining the pointwise medians would be much more regular than and different from any observed curve. Moreover, the central curves obtained from pointwise boxplots would be narrower than those given by functional boxplots and fewer curves would be contained in the central region. Functional depths treat each curve as one observation. Therefore, it can be regarded as the most suitable approach in a functional data framework.

In our analysis, depths will be calculated to rank the estimated between effect functions and the estimated within effect functions. Moreover, we shall build functional boxplots associated with the posterior distribution of  $Z_i(t)$ , for each laboratory  $i = 1, \ldots, 8$ .

#### 6 Data analysis

In this section, we describe the results obtained by fitting the Bayesian model in (7) to the acoustic data of Section 2.

We have estimated principal components and scores by the procedure described in Section 4, by setting  $\sigma_{\lambda}^2 = 10^3$  and the hyperparameters of the inverse–gamma distribution of  $\sigma^2$  to 2 and 10<sup>−</sup><sup>3</sup> , respectively. In this way, we have obtained our smoothed data by means of the Karhunen–Loève expansion. Figure 1 displays raw and smooth data (on the log scale as well as all the other graphs in this paper). As expected, high variability is quite apparent at low frequencies.

We have determined the number of level–one and level–two principal components to be retained, as the minimum number of components which leaves a percentage of unexplained variance smaller than  $1/T$ , with  $T = 21$ . In other words, the number of grid points for each curve achieves a cumulative percentage of explained variance greater than 99%, according to (6). A further constraint on these numbers is that for each level, they must be greater than or equal to four. We then obtained  $K_1 = 6, K_2 = 5$ , i.e., we have kept six components for level–one and five for level–two. The scores have been estimated using the Bayesian procedure described in Section 4.

The Bayesian estimate (posterior mean) of the intra-cluster correlation index (5) is 0.884. In other words, 88.4% of variability is attributable to the laboratory level variability. This is quite clear if we examine the Bayesian estimates of between, within and total variances (see



Figure 1: Raw and smoothed data.

Fig. 2), obtained as the diagonals of the corresponding estimates of the covariance operators

$$
\tilde{G}_B(s,t) = \sum_{k=1}^{K_1} \tilde{\lambda}_k^{(1)} \hat{\varphi}_k^{(1)}(s) \hat{\varphi}_k^{(1)}(t),
$$
  
\n
$$
\tilde{G}_W(s,t) = \sum_{l=1}^{K_2} \tilde{\lambda}_l^{(2)} \hat{\varphi}_l^{(2)}(s) \hat{\varphi}_l^{(2)}(t) + \tilde{\sigma}^2 \mathbb{I}_{\{t=s\}},
$$
  
\n
$$
\tilde{G}_T(s,t) = \tilde{G}_B(s,t) + \tilde{G}_W(s,t),
$$
\n(10)

where  $\tilde{\sigma}^2$  is the estimated nugget effect. The between variance is always equal or greater than the within variance. Moreover, the between variance and the total variance have both a local maximum at 1163.6 Hz. In the first analysis of this dataset (Scrosati et al.<sup>4</sup>), a high between-laboratories variability was observed at the 1250 Hz one-third/octave band, corresponding to the critical frequency of the shutter box. To the best of our knowlege, there is only another work dealing with an RRT on façade sound insulation  $(Lang^{28})$ . Scrosati et al.<sup>4</sup> compared their data with the one of this RRT and found a particular behavior of the



Figure 2: Between (red dashed line), within (blue dotted line) and total variance (black solid line).

façade sound insulation RRTs that show higher variation in correspondence of the critical and resonance frequencies of their components.

Figure 3 shows the estimates of the corresponding between and within correlation functions  $\tilde{G}_B(s,t)$  and  $\tilde{G}_W(s,t)$ . We observe that the within correlation is generally low while the between correlation reaches higher values  $(> 0.8)$ . These peaks, represented by the darkest areas in the figure, are obtained around the diagonals and in the upper left and bottom right corners. This shows that those laboratories that overestimate (underestimate) the  $D_{2m,nT}$ index at low frequencies behave similarly at high frequencies, as confirmed by the analysis of the first level-one principal component.

Fig. 4 is a typical graph in functional data analysis: the first row displays the estimates of the level-one principal components; the second row displays the population mean function (solid line) and the functions obtained by adding (resp., subtracting) a suitable multiple of the eigenfunctions from the mean, represented by the lines with the plus (resp., the minus) symbol markers. More precisely, we have plotted the function  $\hat{\mu}(t)$  together with  $\hat{\mu}(t)$  +  $\sqrt{\tilde\lambda_k^{(1)}}$  $\hat\varphi_k^{(1)}$  $\hat{h}^{(1)}_{k}(t),\,\hat{\mu}(t)\,{-}\,\sqrt{\tilde{\lambda}^{(1)}_{k}}\hat{\varphi}^{(1)}_{k}$  $k_k^{(1)}(t)$ , for  $k = 1, \ldots, K_1$ . More than half  $(53, 15\%)$  of the between



Figure 3: Estimated between and within correlation functions (axis values are log– frequencies).

laboratories variability is explained by the first principal component. This component is negative over the whole frequency range, which indicates a shift of the laboratory–specific mean, with respect to the general mean, in the same direction throughout. It reaches a (negative) peak on the lowest frequencies whose magnitude is four times higher than any other peak. This means that the greatest variability between laboratories will be found by heavily weighting the lowest frequencies, with only a light contribution from the other frequencies. In short, the quantity  $D_{2m,nT}$  is more variable across laboratories on the lowest frequencies.

From the acoustic point of view, a possible explanation for the high values at the lowest frequencies (i.e. the 50, 63 and 80 Hz one-third/octave bands) could be found in the presence of the normal vibration modes, which are orthogonal to the propagation direction of the wave. For a room of the size of the receiving room, the analysis of these modes of vibration<sup>4</sup> confirms that, at the first three one-third octave bands, the measured levels can be strongly influenced by the microphone position.

The second level–one principal component has a negative peak at 69.13 Hz and two positive ones at 159.03 Hz and 1110.97 Hz. The former is quite sharp. Therefore, laboratories



Figure 4: Level-one principal components: estimated components (top row); effects of the components on the overall mean (bottom row).

with an high score  $\xi_{i,2}$  produce measures that are lower than the average at 69.13 Hz and higher at 159.03 Hz and 1110.97 Hz. This type of variability explains the 16.23% of the between laboratories variability mainly in the central part of the frequency spectrum as seen in Figure 4.

The other level-one principal components have an oscillatory behaviour, which is difficult to interpret. This is a problem that often arises in functional principal components analysis, but has small relevance here, as the remaining components leave out a small percentage of the variance.

For the level–two principal components, Fig. 5 shows little difference about the portion of within-laboratory variability between the first (48.54%) and the second (37.56%) component. The first one has effect only at low frequencies. In fact, it is close to zero for frequencies greater than 155 Hz. Instead, the main effect of the second one regards frequencies from



Figure 5: Level-two principal components: estimated components (top row); effects of the components on the overall mean (bottom row).

about 85.14 Hz to 1247.25 Hz and from about 1848.46 Hz to 3876.3 Hz, accounting for a deviation of the single measurement from the laboratory–specific mean in the same direction. The remaining components (the third one displayed in the figure, but also the fourth and the fifth) again exhibit an oscillatory behaviour that is difficult to interpret, but, on the other hand, account for a small proportion of the within–laboratory variability, and therefore their interpretation is not a concern.

Let us now look at the posterior distributions of level-one principal component scores, which have been estimated by our Bayesian model. Fig. 6 displays the boxplots of the posterior distribution of the scores. Let us recall that these scores express the weight given by the level-one principal components to each laboratory, with the first component staying away from zero especially at low frequencies. The first principal component score provides a way to rank laboratory performances at low frequencies, by highligthing what laboratories result

less accurate in their measurements because they show a larger discrepancy from the general mean. We can see that lab 3 has a negative first principal component score, which is the highest in absolute value. Therefore, we expect that for this laboratory measured values are much higher than the general mean at the lowest frequencies. In other words, lab 3 seems to be responsible of the worst systematical error, with a tendency to overestimate  $D_{2m,nT}$ . For the same reason laboratories lab 4 and lab 7 overestimate the quantity on the low frequencies. On the contrary, lab 5, lab 6 and lab 8 generally underestimate the quantity on such frequencies. Laboratories with smallest scores in absolute values, such as lab 1 and lab 2 are able to provide more accurate measureaments for the low frequencies than the other laboratories. These conclusions are confirmed by the plot of the posterior pointwise means of the functions  $Z_i$  that are the Bayesian estimates denoted by  $\tilde{Z}_i$ ,  $i = 1, \ldots, 8$  (Fig. 7). Compare for instance lab 1 and lab 3 to other ones at the lowest frequencies.



Figure 6: Posterior boxplot of the level-one scores:  $\xi_{i,1}$  (left),  $\xi_{i,2}$  (middle),  $\xi_{i,3}$  (right),  $i = 1, \ldots, 8.$ 

In Fig. 7, we have also obtained functional boxplots related to the posterior distributions of the deviation of the laboratory specific–means from the general mean. For each laboratory  $i = 1, \ldots, 8$ , our aim is to estimate the p-th central region  $C_p$  as defined in Section 5, where  $Y(t)$  is replaced by  $Z_i(t)$  with its posterior distribution. To this aim, we compute  $C_{N,0.5}$  by (9), where the observations  $y_1, \ldots, y_N$  are the MCMC sample from the posterior distribution of  $Z_i(t)$ . In this way, we obtain, for each laboratory  $i = 1, \ldots, 8$ , the measure of the area between the dashed lines, which is the 50% credible band of  $Z_i(t)$ . The border of the 50% central region is defined as the envelope representing the box in the classical boxplot. The most external dotted lines are equivalent to the "whiskers" in the classical boxplot, obtained by inflating the envelope of the 50% central region 1.5 times its range. The points in Fig. 7 are the observed deviations of the laboratory–specific means from the general mean.

Functional boxplots confirm what we have already observed, looking at level–one scores, about the variability at the low frequencies. For instance, lab 3 and 5 deviate from the general mean noticeably. In particular, lab 3 upwards, lab 5 downwards, whereas lab 1 and 2 are the closest ones to the mean. Looking at Fig. 7, one can assess that performance of  $Z_6(t)$  does not deviate significantly from zero. Nevertheless,  $Z_6(t)$  does not fit quite well the points representing the observed deviations from the mean due to a high internal variability.



Figure 7: Functional boxplot summarizing the posterior distributions of the laboratory deviations from the overall mean.

One of the main goals of this paper is to rank the global performances of the laboratories. To this aim, the smaller the laboratory–specific mean deviation  $Z_i(t)$ , the better the performance. Since these quantities are functions, we rank laboratories by the estimated depths of the  $Z_i$ 's, as described in Section 5. The greater the depth the more central the curve. Fig. 8 summarizes the posterior distribution of depth for each laboratory. The specific mean



Figure 8: Boxplot summarizing the posterior distribution of depth for each laboratory– specific mean.

deviation of lab 1 is the most central. This optimality comes out considering not only the posterior median of the depths but also the whole posterior distribution summarized through the boxplot. It is interesting to note that lab 1 is the laboratory who used the rotating microphone boom for the measurament of the space and time averaged pressure level in the receiving room, while all the other laboratories used fixed microphones positions.

We can also use depths to compare measurements on the basis of their within laboratory variability. Hence, we have computed the depths of  $\tilde{W}_{i,j}(\text{Table 1})$ . All measurements of lab 6 have the lowest depth. Hence, lab 6 has the highest within variability. This confirms our comment about the fitting of  $\tilde{Z}_6(t)$  while discussing Fig. 7.



Table 1: Depths of each  $\tilde{W}_{i,j}$ , i.e., each estimated deviation from the laboratory–specific mean.

#### 7 Robustness analysis

When we set up the Bayesian regression model introduced at the end of Section 4, one critical choice is the prior distribution for the mixed effect variances  $\tilde{\lambda}_k^{(1)}$  $\tilde{\lambda}_l^{(1)}$  and  $\tilde{\lambda}_l^{(2)}$  $\prod_l^{(2)}$ . The natural choice for the prior means are the eigenvalues of the covariance functions computed as reported in Section 4 (points 6 and 7) while no prior information is available on the variance  $\sigma_{\lambda}^2$ . To deal with this lack of information, we have conducted a robustness analysis, comparing the different estimates for level–one and level–two eigenvalues obtained as  $\sigma_{\lambda}^2$ varies in  $\{10^j, j = 1, \ldots, 4\}$ . Table 2 reports the eigenvalues of the between covariance matrix together with the mean and the median of the posterior distributions of  $\lambda_k^{(1)}$  $\binom{1}{k}$ , for  $k = 1, \ldots, K_1$ , for each one of the four different values of  $\sigma_{\lambda}^2$ . Our estimates for the  $\lambda_k^{(1)}$  $k^{(1)}$ 's are quite robust. Nevertheless, as the hyperparameter  $\sigma_{\lambda}^2$  increases, for each k, the posterior mean and the posterior median slightly increases and so does the difference between the two, with a tendency to a positive skew (i.e. to a longer tail on the right) for the posterior distribution of  $\lambda_k^{(1)}$  $\frac{1}{k}$ .

The estimates obtained for level–two eigenvalues can be found in Table 3. Here, we have disagreement between our Bayesian estimates and the empirical estimates based on the within covariance matrix. Indeed, according to the Bayesian model, the biggest eigenvalue is the one associated with  $\hat{\varphi}_2^{(2)}$  $2^{(2)}(t)$ , regardless of the choice of the hyperparameters.

		$\mathbf{1}$	2	$3 \qquad \qquad$	$\overline{4}$	$\overline{5}$	6
	$\hat{\lambda}_{k}^{(1)}$	298.973 81.562 50.765 45.135				20.438	5.842
$\sigma_{\lambda}^2 = 10^1$	mean	299.035	81.662		50.911 45.622 21.727		6.278
	median	299.111 81.617 50.771 45.458 21.431					5.724
$\sigma_{\lambda}^2 = 10^2$	mean	299.035	81.662		50.911 45.622	21.727	6.278
	median	299.111 81.617 50.771 45.458 21.431					5.724
$\sigma_{\lambda}^2 = 10^3$	mean	300.158	88.190	56.114	60.513	32.012	6.526
	median	297.947		83.983 52.455 54.858		28.949	5.714
$\sigma_{\lambda}^2 = 10^4$	mean	309.208	92.583	58.752	66.386	32.054	6.590
	median	294.639 82.934 51.987 59.180 28.396					5.567

Table 2: Estimated level–one eigenvalues varying the hyperparameter  $\sigma_{\lambda}^2$ .

As a final comment on this robustness analysis, we believe that the posterior estimates are quite stable and the prior setting does not substantially affect the statistical findings. We have reported in Section 6 the results obtained by  $\sigma_{\lambda}^2 = 10^3$ , being this value an usual choice for vague priors.

## 8 Comparison between the pointwise and the functional approaches

The study of the observation variability is the main goal of this analysis by taking into account the hierarchical structure of the data. The pratical properties of interest for engineers are usually the repeatability and reproducibility errors. The main aspect of the analysis conducted here is to consider the data as functional while the random effect regression model is usually fitted pointwise (i.e. at each frequency band, see for instance Scamoni et al.<sup>2</sup>). Clearly, the pointwise analysis is quite simple, but some information is lost. In fact, in the pointwise case, the frequency dependency of the response variable  $D_{2m,n}(t)$  is overlooked. To demonstrate this, we have estimated a Bayesian random effect model for each frequency, assuming independence between observations at different frequencies. In particular, for each

		$1 \qquad 2 \qquad 3 \qquad 4$		-5
	$\tilde{\lambda}_{k}^{(2)}$	20.251 18.425 1.481 1.147 0.267		
$\sigma_{\lambda}^2 = 10^1$	mean	21.832 22.654 7.368 2.014 0.179		
	median	21.520 22.380 7.015 1.535 0.139		
	mean	21.832 22.654 7.368 2.014 0.179		
$\sigma_{\lambda}^2 = 10^2$	median	21.520 22.380 7.015 1.535 0.139		
	mean	26.571 34.341 7.606 2.052 0.174		
$\sigma_{\lambda}^2 = 10^3$	median	25.487 32.713 7.233 1.572 0.135		
	mean	26.853 34.935 7.625 1.966 0.176		
$\sigma_{\lambda}^2 = 10^4$	median	25.838 33.602 7.263 1.485 0.136		

Table 3: Estimated level–two eigenvalues varying the hyperparameter  $\sigma_{\lambda}^2$ 

frequency t in  $\{50, 63, \ldots, 5000\}$ , we have fitted the following model:

$$
Y_{ij}(t) = \mu_0(t) + \gamma_i(t) + \varepsilon_{ij}(t), \quad i = 1, ..., 8, \ j = 1, ..., 5
$$
  
\n
$$
\gamma_1(t) \dots \gamma_8(t) | \sigma_\gamma^2(t) \stackrel{iid}{\sim} N(0, \sigma_\gamma^2(t))
$$
  
\n
$$
\varepsilon_{ij}(t) | \sigma_\varepsilon^2(t) \stackrel{iid}{\sim} N(0, \sigma_\varepsilon^2(t))
$$
  
\n
$$
\mu_0(t) \sim N(0, 1000)
$$
  
\n
$$
\sigma_\gamma^2(t) \sim \text{inv-gamma}(2, 0.1), \quad \sigma_\varepsilon^2(t) \sim \text{inv-gamma}(2, 0.001).
$$

The choice of priors is standard and represents vague prior information (see Gelman<sup>29</sup>).

The posterior pointwise estimations of the random effects  $\gamma_i$  are reported in Table 4. The posterior credible bands under the functional analysis are smaller than the pointwise ones. Indeed, by taking into account the frequency dependence, we obtain a more precise posterior estimation.

Moreover, we can compare estimates of  $\sigma_{\gamma}^2(t)$  with  $\tilde{G}_B(t,t)$  and  $\sigma_{\gamma}^2(t) + \sigma_{\varepsilon}^2(t)$  with  $\tilde{G}_T(t,t)$ . We do not report any pointwise estimate for brevity, while the functional counterparts are depicted in Fig. 2. We mention that estimates are similar almost on the whole frequency spectrum, apart from the 50 Hz frequency, where the pointwise estimates are much smaller than the functional ones. Consequently, in the pointwise analysis we observe a sharp increase of the estimated variances from 50 Hz to 63 Hz. This behaviour, which is difficult to interpret from an engineering point of view,<sup>4</sup> is mitigated by the smoothing effect of the functional framework.

### 9 Conclusions

In this paper, we have analyzed data coming from a RRT experiment conducted at ITC– CNR. Firstly we aimed at the identification of those frequencies at which measurements are more variable and at a decomposition of the total variance reflecting the hierarchical nature of the data. An important achievement is the capability of the proposed model of ranking the measurement perfomances of the laboratories, by taking into account the behaviour at low frequencies (high varibility) and the global perfomance. To rank laboratories according to the accuracy of their measurement at low frequencies we have considered the posterior of the scores of the first principal component at level–one (i.e. laboratory level), while the global performance has been evaluated according to the centrality of the estimated laboratory– specific deviation from the general mean,  $\tilde{Z}_i(t)$ . A natural tool to measure the centrality of the curves is the band depth. We have briefly discussed the probabilistic setting of the MBD depth and used this tool to achieve our ranking goal.

In the recent literature, there are several papers dealing with multilevel regression functional models. Among the others, we have seen the model proposed by Di et al.<sup>18</sup> fit to our aims. To make our exposition self–contained, we have briefly reviewed the model and we have explained in details our estimation procedure. All the analysis has been conducted using the  $R^{30}$  software and JAGS<sup>22</sup> when needed. Our model fits the data very well and it has proven an appropriate tool for our goals.

We have found several benefits using a functional approach: the estimated functional correlations among measuraments at different frequencies has provided additional insights into the data; the principal functional decomposition of the variance at both levels of the hierarchy matches the assumptions of the engineers on the functional directions of higher variability; the functional estimation of the random effects are more precise. In addition, the model is quite robust with respect to the hyperparameters of the scores priors.

From an acoustic point of view, the analyses illustrated in the paper has led to the following

findings. The first principal component, both for the first and the second level, reflects the low frequencies variability (from 50 to 100 Hz). Indeed, they both take high values (in absolute value) between 50 and 100 Hz, while they take values not far from zero at frequencies greater than 100 Hz. For each level, the first component explains a high percentage of the variability (55.23% for level–one and 48.54% for level–two). We have also been able to evaluate the proportion of the total variability due to the frequencies between 50 Hz and 100 Hz, by using the estimated intra–cluster correlation (88.4%). This can be determined at about  $54\%$ , derived as  $55.23\% \cdot 0.884 + 48.54\% \cdot (1 - 0.884) = 54.45\%.$ 

It has also been shown that the best laboratory (i.e. the laboratory with the most central mean on the basis of the MBD depth) is laboratory 1, that is the laboratory where the rotating microphone boom was used for the measurement of the space and time averaged pressure level in the receiving room, while all the other laboratories used the fixed microphones positions.

Finally, it has been found that a laboratory which tends to overestimate  $D_{2m,nT}$  at low frequencies will overestimate this index also at high frequencies and vice versa.

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Table 4: Comparison of pointwise and functional posterior quantiles for the effect of each laboratory Table 4: Comparison of pointwise and functional posterior quantiles for the effect of each laboratory