Modal analysis of historical masonry structures: linear perturbation and software benchmarking

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8 Abstract

The mechanical behavior of masonry materials has a common feature: a nonlinear behavior with high compressive strength and very low tensile strength. 10 As a consequence, old masonry buildings generally present cracks due to per-11 manent loads and/or accidental events. Therefore, the characterization of 12 the global dynamic behavior of masonry structures should take into account 13 the presence of existing cracks. This paper presents a numerical approach 14 coupling linear perturbation and modal analysis in order to estimate the dy-15 namic properties of masonry constructions, taking into account the existence 16 of structural damage. First, the approach is validated on a masonry arch 17 subjected to increasing loads, via three FE codes. Then, the same procedure 18 is applied to a real masonry structure affected by a severe crack distribution. 19 *Keywords:* Masonry-like materials, masonry constructions, modal analysis, 20 numerical methods, nonlinear elasticity, linear perturbation 21

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22 1. Introduction

Safeguarding of cultural heritage is an acquired principle nowadays, widely 23 shared by all communities. Preservation of the past is an indispensable re-24 quirement for our society to foster knowledge, awareness of identity, and 25 ability to think of and plan the future. With regard to architectural her-26 itage, age-old buildings and monuments need to be preserved not only from 27 damage mechanisms and deterioration processes induced by anthropogenic 28 and environmental actions, but also from the aging effects they are exposed 29 to during their lifetime. Furthermore, ancient structures are particularly 30 vulnerable to seismic actions, whose consequences should be prevented - or 31 at least mitigated - with effective strengthening measures and maintenance 32 plans. For this purpose, Structural Health Monitoring (SHM) and Finite El-33 ement (FE) analysis represent complementary techniques which may help to 34 understand the complex dynamic behavior of ancient buildings and estimate 35 the mechanical properties of their constituent materials with use of limited 36 invasive testing procedures. In addition, if long-term monitoring protocols 37 are conducted, important information can be catched on the interactions be-38 tween the structure under consideration and the surrounding environment 39 [4], [44], as well as on the evolution of the structural health over time. In 40 fact, significant changes in the structure's dynamic properties can reveal the 41 presence of structural damage, as pointed out in [21], [40], [43], where de-42 creasing values of natural frequencies were measured at the onset of damage. 43 Moreover, dynamic monitorig can represent a valuable tool to assess the ef-44

fectiveness of strengthening interventions, as shown in [33], [34], [44], where
evident rising in the natural frequencies was observed in the monitored historical structures after restoration works.

Structural health monitoring is usually coupled with FE analysis via 48 model updating procedures [1], [2], [5], [10], [12], [46], [52], in order to de-49 rive realistic information about the boundary conditions and the mechani-50 cal properties of the structure's constituent materials, especially when more 51 invasive techniques are not viable as in case of heritage buildings. These 52 procedures typically consist in tuning some parameters of the FE model in 53 order to minimize the distance between numerical and experimental modal 54 properties (natural frequencies and mode shapes). 55

In this regard, it is worth noting that modal analysis is carried out within 56 the framework of linear elasticity. This setting could be unsuited for masonry 57 buildings, which may exhibit nonlinear behavior even for the self-weight and 58 sometimes show extended crack patterns. Therefore, the dynamic behavior 59 of these constructions should be analyzed by taking into account the existing 60 damage so as to avoid erroneous evaluations of the parameters, which may in 61 turn compromise the outcome of further numerical simulations. A common 62 approach to this problem consists in simulating the actual damage observed 63 on the structure by reducing the stiffness of those finite elements belonging 64 to the cracked or damaged parts [7], [10], [41], [43]. 65

In [23] a numerical procedure implemented in the non commercial FE software NOSA–ITACA (www.nosaitaca.it) is described. Here, the masonry

material is modeled via the masonry-like constitutive equation [14], [30]. 68 This procedure allows evaluating the natural frequencies and mode shapes 69 of masonry buildings in the presence of cracks, via linear perturbation anal-70 ysis and consists of the following steps: first, the initial loads and boundary 71 conditions are applied to the FE model and the resulting nonlinear equilib-72 rium problem is solved through an iterative scheme. Then, a modal analysis 73 about the equilibrium solution is performed, by using the tangent stiffness 74 matrix calculated in the last iteration before convergence is reached, thereby 75 allowing the user to automatically take into account the effects of the stress 76 distribution on the structure's stiffness. 77

Other applications of linear perturbation, sometimes referred to as prestressed modal analysis, are in the framework of large deformation problems [13], [24], [36], [53]. With regard to masonry buildings, an example is shown in [18], where linear perturbation is applied via a commercial code to a historic masonry building.

This paper focuses on the use of linear perturbation to evaluate modal 83 properties of ancient masonry buildings in the presence of cracks. The 84 method is described in Section 2 and applied to a masonry arch in Section 85 3, where the results obtained via different constitutive equations and FE 86 codes (DIANA, MARC, NOSA-ITACA) are compared and discussed. Then, 87 a real case application is presented in Section 4, where the Mogadouro clock 88 tower is analyzed via the NOSA-ITACA code, before and after the restora-89 tion works carried out in 2005. The paper demonstrates that, by adopting 90

the appropriate constitutive model, different FE codes do provide the same 91 modal features in the presence of a damaged structure. Moreover, making 92 use of the experimental results at the authors' disposal [44], [45], it is shown 93 that linear perturbation analysis combined with finite element modal updat-94 ing allows identifying the tower's material properties (i.e. Young's modulus 95 and tensile strength) that consistently reflect the damaged condition of the 96 structure before restoration as well as the increase of the structural stiffness 97 resulting from the subsequent strengthening intervention. 98

⁹⁹ 2. Constitutive equations, linear perturbation and modal analysis

In recent years the advancement of computer technology and introduc-100 tion of innovative mathematical models made it possible to assess the struc-101 tural safety of complex ancient masonry buildings by taking into account 102 the nonlinear behavior of masonry materials, whose response to tension is 103 completely different from that to compression and whose mechanical char-104 acteristics are the result of both their constituent elements and the building 105 techniques used. The numerous studies conducted in the last decades, aimed 106 at modeling the behavior of masonry structures, led to the formulation of 107 different constitutive laws that can be grouped into two main classes. The 108 first class includes those models in which the macroscopic behavior of the 109 masonry material is obtained from the micro-mechanical behavior of its sin-110 gular components [37], [50], [48], [26], [16], [17]. The second class contains 111 instead the so-called macro-mechanical models, in which the masonry mate-112

rial is modeled either as an equivalent continuum [6], [14], [30], [51], [35], or as an assembly of macro elements with few degrees of freedom characterized by certain global behaviors [25], [39], [49]. Models originally formulated for concrete and subsequently applied to masonry structures [9], [47], [11] can be included in this latter group. A comprehensive review of constitutive models for masonry falls outside the scope of this paper and the reader is referred to [27], [28], [29] and [42] for a thorough discussion.

When dealing with the analysis of ancient masonry buildings, constitutive 120 equations belonging to the second class are preferable. In fact, the applica-121 tion of micro-mechanical models is not straightforward, since it is difficult 122 to identify a homogeneous and/or periodic structure in historical masonries. 123 Moreover, the use of micro-mechanical models requires accurate knowledge 124 of several parameters related to mechanical properties of the masonry con-125 stituent elements, which can not be easily determined; furthermore, the em-126 ployment of the micro-mechanical models to complex structures calls for high 127 computational cost. On the other hand, the application of macro-mechanical 128 models does require the knowledge of a few parameters, which can be ob-129 tained from experimental tests, literature values or even from indications 130 provided by national building codes and regulations. 131

Among macro-mechanical models, the constitutive equation for low tension materials, implemented in MARC [32], and the Rankine model, implemented in DIANA [15], are largely adopted to simulate the structural behavior of masonry constructions. Along with these models, both based

on the theory of infinitesimal plasticity, the nonlinear elastic equation of 136 masonry-like materials [30] is able to realistically describe the behavior of 137 masonry buildings by taking into consideration their zero or low tensile 138 strength. This constitutive equation has been implemented in NOSA-ITACA 139 [8], [22], a finite element code developed and freely distributed by ISTI-CNR 140 (www.nosaitaca.it). Here, masonry is modeled as an isotropic nonlinear elas-141 tic material with zero tensile strength and infinite compressive strength [14]. 142 It is possible to prove that for every infinitesimal strain tensor \mathbf{E} , there exists 143 a unique triplet $(\mathbf{T}, \mathbf{E}^e, \mathbf{E}^f)$ of symmetric tensors such that **E** is the sum of 144 an elastic strain \mathbf{E}^{e} and a positive semidefinite fracture strain \mathbf{E}^{f} , and the 145 Cauchy stress **T**, negative semidefinite and orthogonal to \mathbf{E}^{f} , depends lin-146 early and isotropically on \mathbf{E}^{e} , through the Young's modulus E and Poisson's 147 ratio ν [14], [30]. 148

Masonry-like materials are then characterized by the stress function T 149 given by $\mathbb{T}(\mathbf{E}) = \mathbf{T}$, whose explicit expression is reported in [30], along with 150 its properties. In particular, \mathbb{T} is differentiable in an open dense subset of 151 the set of all strains [38] and the derivative $D_E \mathbb{T}(\mathbf{E})$ of $\mathbb{T}(\mathbf{E})$ with respect 152 to **E** is a positive semidefinite symmetric fourth–order tensor, whose explicit 153 expression is reported in [30]. The equation of masonry-like materials has 154 been then generalized in order to take into account a weak tensile strength 155 $\sigma_t \ge 0 \ [30].$ 156

¹⁵⁷ The constitutive law of low tensile materials implemented in MARC [32] ¹⁵⁸ is based on the nonlinear concrete cracking formulation described in [9]. Ma-

sonry is modeled as a nonlinear isotropic material in which a crack can de-159 velop orthogonal to the direction of the maximum principal stress, when it 160 exceeds the strength of the material σ_t . After the occurrence of the first 161 crack, a second crack may arise orthogonal to the first. In the same way, a 162 third crack could open perpendicularly to the first two. In this situation the 163 material loses all its load-carrying capacity across the crack, except when a 164 tension softening behavior is considered, which can have a linear trend with 165 slope equal to E_s . 166

The Rankine plasticity model implemented in DIANA [15] employes the Rankine yield criterion to simulate tensile cracking in concrete and rock under monotonic loading conditions. The yield function depends on both the maximum principal stress and a yield value $\tilde{\sigma}_t$ that describes the nonlinear exponential tensile softening behavior of the material, involving the tensile strength σ_t and the fracture energy $G_{\rm f}^{\rm I}$ [19].

Although the mechanical behavior of masonry constructions is clearly 173 nonlinear, modal analysis, which is based on the assumption that masonry 174 constituent materials feature a linear elastic behavior, is widely used in prac-175 tical applications. Indeed, it provides important qualitative information on 176 the global dynamic behavior of masonry structures, thereby allowing to as-177 sess their seismic vulnerability in compliance with the Italian and European 178 regulations. On the other hand, traditional modal analysis does not take into 179 account the influence that both the nonlinear behavior of the masonry mate-180 rial and the presence of cracked regions can have on the natural frequencies 181

of masonry structures. While the effects of cracks on the vibration frequencies are taken into account in different fields of mechanical and aerospace engineering through the so-called linear perturbation analysis, such effects are not fully explored yet as far as the civil engineering field is concerned.

In this paper the linear perturbation approach is coupled with modal 186 analysis, with the aim of assessing the dependence of the dynamic properties 187 of a masonry structure on the stress field and crack distribution induced by 188 the loads acting on the structure. Apart from the examples described in [23], 189 where a masonry beam, an arch on piers and the San Frediano bell tower in 190 Lucca have been analyzed, coupling linear perturbation and modal analysis is 191 far from being fully investigated, although it allows for calculating the natural 192 frequencies and mode shapes of a masonry body exhibiting a crack distribu-193 tion due to the applied loads. In this regard, the procedure implemented in 194 the NOSA-ITACA code consists in calculating the numerical solution to the 195 nonlinear equilibrium problem of a masonry structure discretized into finite 196 elements, subjected to given boundary and loading conditions, and then con-197 sidering the linear equation governing the undamped free vibrations of the 198 structure about the equilibrium state 199

$$M\ddot{u} + K_{\rm T}u = 0. \tag{1}$$

In equation (1) u is the displacement vector, which belongs to \mathbb{R}^n and depends on time t, \ddot{u} is the second-derivative of u with respect to t, and $K_{\rm T}$ and $M \in \mathbb{R}^{n \times n}$ are the tangent stiffness and mass matrices of the finiteelement assemblage. Note that $K_{\rm T}$ is symmetric and positive semidefinite, M is symmetric and positive definite. Equation (1) is similar to the equation of the motion of a linear elastic body, though here the elastic stiffness matrix, calculated using the elasticity tensor, is replaced by the tangent stiffness matrix $K_{\rm T}$, calculated using the solution to the equilibrium problem and then takes into account the presence of cracks in body.

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²¹⁰ By assuming that

$$u = \phi \sin(\omega t), \tag{2}$$

with ϕ a vector of \mathbb{R}^n and ω a real scalar, equation (1) can be transformed into the constrained generalized eigenvalue problem

$$K_{\rm T} \phi = \omega^2 M \phi, \tag{3}$$

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$$T\phi = 0, \tag{4}$$

with $T \in \mathbb{R}^{m \times n}$ and $m \ll n$.

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Condition (4) expresses the fixed constraints and the master-slave relations assigned to displacement u, written in terms of vector ϕ . The restriction of the matrix $K_{\rm T}$ to the null subspace of \mathbb{R}^n defined by (4) is positive definite.

Therefore, given the structure under examination, discretized into finite 219 elements, and given the mechanical properties of the constituent materials 220 together with the kinematic constraints and loads acting on the structure, 221 the procedure implemented in NOSA-ITACA consists of the following steps. 222 Step 1. A preliminary modal analysis is conducted by assuming the struc-223 ture's constituent material to be linear elastic, with stiffness matrix K. The 224 generalized eigenvalue problem (3)-(4) is then solved, with K in place of $K_{\rm T}$, 225 and the natural frequencies $f_{i,E} = \omega_{i,E}/2\pi$ and mode shapes ϕ_i^l calculated. 226

Step 2. The solution of the nonlinear equilibrium problem of the structure is found and the derivative of the stress function needed to calculate the tangent stiffness matrix $K_{\rm T}$ to be used in the next step is evaluated.

Step 3. The generalized eigenvalue problem (3)-(4) is finally solved and the natural frequencies $f_i = \omega_i/2\pi$ of the structure in the presence of cracks are estimated.

Similar procedures based on linear perturbation followed by modal analy-233 sis are implemented in MARC and DIANA. The three codes NOSA-ITACA, 234 MARC and DIANA, which adopt different constitutive equations for ma-235 sonry, have been used with the twofold aim of (1) studying the static behavior 236 of a masonry arch subjected to its own weight and a vertical concentrated 237 load and, after a linear perturbation, (2) assessing the dependence of the 238 natural frequencies and mode shapes on the crack distribution. The results 239 of this comparative study are reported in Section 3 and show that, in spite of 240

the different constitutive equations adopted, the dependence of the dynamical properties of the arch on the loads is very similar for the three codes.

²⁴³ 3. Application to a masonry arch and software benchmarking

The numerical method for modal analysis described in Section 2 is here 244 applied to the semi-circular masonry arch shown in Figure 1. The system is 245 fully clamped at the springings and its geometry features a mean radius of 246 0.77 m, a span of 1.50 m, a cross section of 0.16 m $\times 1$ m and a springing angle 247 of about 13°. The arch is subjected to a plane stress state due to its self-248 weight and to a concentrated load P applied at the extrados at a quarter of 249 the span. The arch is discretized into 784 8-node isoparametric quadrilateral 250 elements with quadratic shape functions (corresponding to element 2, 26 251 and CQ16M of the NOSA-ITACA [8], MARC [32] and DIANA [15] libraries, 252 respectively), for a total of 2565 nodes. Figure 2 shows the mesh generated 253 by NOSA-ITACA, later converted in the MARC and DIANA format. 254



Figure 1: Geometry of the arch (length in meters).



Figure 2: Mesh of the arch created by NOSA-ITACA code.

The numerical analyses conducted with NOSA-ITACA, MARC and DI-ANA have manifold goals. Firstly, they are aimed at analysing the static ²⁵⁷ behavior of the arch modeled by adopting three different constitutive equa-²⁵⁸ tions. Secondly they allow comparing the natural frequencies of the arch in ²⁵⁹ the linear elastic case with those in the presence of the damage induced by ²⁶⁰ the increasing vertical load. Several parametric numerical experiments have ²⁶¹ been carried out, as the tensile strength σ_t of the material varies, revealing ²⁶² that, in the presence of cracks, the values of the frequencies calculated by ²⁶³ the three codes are comparable.

A preliminary modal analysis (step 1, Section 2) was performed by assuming the arch made of a linear elastic material with Young's modulus $E = 3 \cdot 10^9$ Pa, Poisson's ratio $\nu = 0.2$ and mass density $\rho = 1930$ kg/m³. The first four corresponding natural frequencies $f_{i,E}$ (i = 1...4) (calculated by the three codes) are

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$$f_{1,E} = 92.33 \text{ Hz}; f_{2,E} = 163.64 \text{ Hz}; f_{3,E} = 266.95 \text{ Hz}; f_{4,E} = 297.95 \text{ Hz}.$$

Then, by following the procedure outlined in Section 2, step 2, damage was induced in the arch by applying the self-weight along with an incremental vertical load. At each increment the frequencies $f_{i,j}$ (the i-th frequency calculated by j-th code: N (NOSA-ITACA), M (MARC) and D(DIANA)) and the corresponding mode shapes were calculated.

In order to perform nonlinear static analysis in DIANA and MARC, the parameters $G_{\rm f}^{\rm I}$ and E_s (see Section 2) have to be assigned, in addition to the tensile strength σ_t , set to vary from 0 Pa to $5 \cdot 10^4$ Pa. The Mode-I fracture energy with $G_{\rm f}^{\rm I} = 25 \ {\rm Nm/m^2}$ was assumed in DIANA, while E_s was calculated, for each analysis performed in MARC, by imposing the equivalence between the areas below the softening curves of both codes.

The value of the vertical load applied to the arch was increased through eight increments from 0 kN to 4 kN. Each analysis was repeated by decreasing the value of σ_t from $5 \cdot 10^4$ Pa to $5 \cdot 10^3$ Pa. For values of σ_t lower than $5 \cdot 10^3$ Pa, only NOSA-ITACA and DIANA reach the convergence for any value of the vertical load.

It is pointed out that in terms of displacement, stress and cracking fields, 287 the results provided by the three codes show very good agreement for each 288 value of the vertical load up to a tensile stress of $5 \cdot 10^3$ Pa. Figures 3, 4, 289 5, 6 and 7 display for the three codes the plots relevant to the norm of dis-290 placements, the components of the Cauchy stress tensor and the maximum 291 eigenvalue of the fracture strain, calculated for $\sigma_t = 5 \cdot 10^3$ Pa and P = 4 kN. 292 Despite the different constitutive equations adopted, NOSA-ITACA and DI-293 ANA provide the same results, whereas the values obtained in MARC exhibit 294 an increment of about 5 - 10% with respect to the afore-mentioned codes. 295



Figure 3: Norm of displacement [m] (P = 4 kN, $\sigma_t = 5 \cdot 10^3$ Pa).



Figure 4: Cauchy stress component σ_x [Pa] (P = 4 kN, $\sigma_t = 5 \cdot 10^3$ Pa).



Figure 5: Cauchy stress component σ_y [Pa] (P = 4 kN, $\sigma_t = 5\cdot 10^3$ Pa).



Figure 6: Cauchy stress component τ_{xy} [Pa] (P = 4 kN, $\sigma_t = 5 \cdot 10^3$ Pa).



Figure 7: Maximum eigenvalue of the fracture strain tensor (P = 4 kN, $\sigma_t = 5 \cdot 10^3$ Pa).

Figures 8, 9, 10, 11 show the variation of the first four frequencies $f_{i,j}$ of the arch, calculated in the three codes via linear perturbation analysis, versus decreasing values of tensile strength σ_t for P = 3 kN (continuous line) and P = 4 kN (dashed line). The corresponding mode shapes for the linear elastic case are also shown. Tables 1, 2, and 3, 4 report, for the same load conditions P, the values of σ_t used in the different analyses along with the corresponding relative frequency errors $\delta_{i,j}$ defined by

$$\delta_{i,j} = \frac{(f_{i,E} - f_{i,j})}{f_{i,E}}, \text{ for } i = 1...4 \text{ and } j = N, M, D$$
 (5)

where $f_{i,E}$ is the i-th frequency calculated by standard modal analysis and $f_{i,j}$ the i-th frequency calculated by j-th code via linear perturbation analysis,

$_{305}\,$ (N stands for NOSA-ITACA, M for MARC and D for DIANA).



Figure 8: First frequency $f_{1,j}$ versus tensile strength σ_t for P = 3 kN (continuous line) and P = 4 kN (dashed line).



Figure 9: Second frequency $f_{2,j}$ versus tensile strength σ_t for P = 3 kN (continuous line) and P = 4 kN (dashed line).



Figure 10: Third frequency $f_{3,j}$ versus tensile strength σ_t for P = 3 kN (continuous line) and P = 4 kN (dashed line).



Figure 11: Fourth $f_{4,j}$ versus tensile strength σ_t for P = 3 kN (continuous line) and P = 4 kN (dashed line).

σ_t [Pa]	$\delta_{1,\mathrm{N}}[\%]$	$\delta_{1,\mathrm{M}}[\%]$	$\delta_{1,\mathrm{D}}[\%]$	$\delta_{2,\mathrm{N}}[\%]$	$\delta_{2,\mathrm{M}}[\%]$	$\delta_{2,\mathrm{D}}[\%]$
0	60.20	—	57.61	27.28	—	31.28
1000	49.80	—	49.13	19.09	—	19.47
2500	37.21	_	35.52	14.03	_	12.74
5000	25.93	29.35	26.68	9.06	11.45	9.63
7500	19.81	21.07	20.19	6.79	7.15	7.26
10000	15.80	16.77	16.26	5.32	5.60	5.75
17500	8.20	8.06	7.57	2.67	2.51	2.38
25000	3.56	3.06	2.89	1.14	0.95	0.95
50000	0.00	0.00	0.00	0.00	0.00	0.00

Table 1: $\delta_{i,j},\,i=1,2$; $j=N,\,M,\,D$; P=3 kN.

σ_t [Pa]	$\delta_{3,\mathrm{N}}[\%]$	$\delta_{3,\mathrm{M}}[\%]$	$\delta_{3,\mathrm{D}}[\%]$	$\delta_{4,\mathrm{N}}[\%]$	$\delta_{4,\mathrm{M}}[\%]$	$\delta_{4,\mathrm{D}}[\%]$
0	28.95	—	35.24	26.71	_	25.08
1000	22.86	-	20.45	19.43	_	14.92
2500	14.42	_	13.31	9.81	_	10.99
5000	8.36	10.21	8.17	5.66	5.88	5.56
7500	5.29	6.24	4.92	3.63	3.47	3.65
10000	3.52	4.30	3.19	2.69	2.54	2.77
17500	1.35	1.57	1.47	1.21	1.19	1.21
25000	0.60	0.70	0.39	0.50	0.41	0.45
50000	0.00	0.00	0.00	0.00	0.00	0.00

Table 2: $\delta_{i,j},\,i=3,4$; $j=N,\,M,\,D$; P=3 kN.

σ_t [Pa]	$\delta_{1,\mathrm{N}}[\%]$	$\delta_{1,\mathrm{M}}[\%]$	$\delta_{1,\mathrm{D}}[\%]$	$\delta_{2,\mathrm{N}}[\%]$	$\delta_{2,\mathrm{M}}[\%]$	$\delta_{2,\mathrm{D}}[\%]$
0	77.20	—	74.92	47.38	_	44.10
1000	66.79	_	67.90	36.94	_	35.28
2500	57.29	—	56.32	25.63	_	24.42
5000	44.50	55.15	44.38	16.19	21.67	15.91
7500	35.57	36.42	34.72	12.32	12.95	12.03
10000	29.27	29.94	28.12	10.32	10.50	9.76
17500	16.15	17.01	16.45	5.53	5.62	5.81
25000	9.42	9.80	9.66	3.19	3.20	3.28
50000	0.56	0.51	0.95	0.19	0.17	0.34

Table 3: $\delta_{i,j},\,i=1,2$; $j=N,\,M,\,D$; P=4 kN.

σ_t [Pa]	$\delta_{3,\mathrm{N}}[\%]$	$\delta_{3,\mathrm{M}}[\%]$	$\delta_{3,\mathrm{D}}[\%]$	$\delta_{4,\mathrm{N}}[\%]$	$\delta_{4,\mathrm{M}}[\%]$	$\delta_{4,\mathrm{D}}[\%]$
0	48.70	—	44.65	50.06	_	36.55
1000	40.01	_	34.17	37.21	_	29.39
2500	27.26	—	26.15	22.03	_	21.90
5000	18.79	26.05	17.98	11.59	13.52	12.88
7500	13.17	13.71	12.54	9.02	8.58	8.16
10000	9.26	9.82	8.84	5.62	5.83	5.60
17500	3.72	4.24	3.45	2.46	2.40	2.55
25000	1.79	1.76	1.70	1.35	1.34	1.43
50000	0.08	0.08	0.04	0.08	0.07	0.13

Table 4: $\delta_{i,j},\,i=3,4$; $j=N,\,M,\,D$; P=4 kN.

As expected, the figures highlight that the frequencies of the arch decrease 306 as the vertical load increases and the tensile strength decreases. As outlined 307 in Tables 1, 2, 3 and 4, regardless of the value of the vertical load, the 308 fundamental frequency falls faster than the other frequencies; approximately 309 27% against 9%, when P = 3 kN and $\sigma_t = 5 \cdot 10^3$ Pa, and 50% against 20%, 310 when P = 4 kN and $\sigma_t = 5 \cdot 10^3 \text{ Pa}$. This is due to the chosen vertical load 311 position, which induces a deformation in the arch similar to the first mode 312 shape (Figure 12, 13). 313

Figure 12 shows the mode shapes corresponding to the first four frequencies of the arch for $\sigma_t = 5 \cdot 10^3$ Pa and P = 3 kN. Figure 13 shows the same four mode shapes but for $\sigma_t = 5 \cdot 10^3$ Pa and P = 4 kN. The figures report the degree of consistency, expressed in terms of MAC, viz. Modal Assurance Criterion [31], calculated between the i-th mode shape of the damaged arch and the corresponding mode shape calculated via standard modal analysis. It is noticed that frequencies are much more sensitive than mode shapes to damage; for example when $\sigma_t = 5 \cdot 10^3$ Pa and P = 3 kN, the first frequency shows a relative variation of about 25% while the MAC value is equal to 0.99, whereas when $\sigma_t = 5 \cdot 10^3$ Pa and P = 4 kN, the first frequency has a relative downshift of about 50% (which indeed corresponds to a severe damage condition), but the MAC still continues to be rather high, showing values not lower than 0.90.



Figure 12: First four mode shapes of the damaged arch (P = 3 kN, $\sigma_t = 5 \cdot 10^3$ Pa).



Figure 13: First four mode shapes of the damaged arch (P = 4 kN, $\sigma_t = 5 \cdot 10^3$ Pa).

In order to validate the frequencies values calculated by the three FE codes, the load-displacement curves corresponding to $\sigma_t = 5 \cdot 10^3$ Pa were plotted (Figure 14) for nodes 755 and 673, positioned respectively at the application point of vertical load and the corresponding point at the intrados of the arch (Figure 2).



Figure 14: Vertical load versus displacement magnitude of node 673 (on the left) and node 755 (on the right), $\sigma_t = 5 \cdot 10^3$ Pa.

For each curve, its fourth-degree interpolating polynomial is determined and then the slopes $k_{T,P0}$ and $k_{T,P4}$ of the tangents at the origin and at P = 4 kN, (dashed lines in Figure 14) are calculated. The slope k_S of the secant passing for those points (dashed-dot lines in Figure 14) is also calculated. Since the loss of frequency is expected to be related to the square root of the loss of stiffness (mass being equal), the following quantities were calculated as for the first frequency, i.e. the one suffering a major decrease due to damage

$$\tilde{f}_{1,\mathrm{T}} = f_{1,\mathrm{E}} \cdot \sqrt{\frac{k_{\mathrm{T,P4}}}{k_{\mathrm{T,P0}}}},$$
(6)

$$\tilde{f}_{1,\mathrm{S}} = f_{1,\mathrm{E}} \cdot \sqrt{\frac{k_{\mathrm{S}}}{k_{\mathrm{T,P0}}}},\tag{7}$$

The results obtained are summarized in Tables 5 and 6 for all the three codes. It is worth noting that the first frequency $\tilde{f}_{1,T}$ calculated by using the tangent stiffness is a good approximation of the frequency $f_{1,j}$ computed via linear perturbation analysis, whereas the choice of the secant stiffness matrix would lead to an overestimation of the frequency of the damaged structure.

Code	P[kN]	$k_{\rm T} \; [{\rm kN/m}]$	$k_{\rm S} \; [{\rm kN/m}]$	$\tilde{f}_{1,\mathrm{T}}$ [Hz]	$\tilde{f}_{1,\mathrm{S}}$ [Hz]	$f_{1,j}$ [Hz]
N	0	254.48	1/13 52	50.87	69.34	51 24
11	4	77.26	140.02	50.01	05.04	01.24
М	0	260.23	133.68	41 76	66 18	41 41
111	4	53.23	199.09	41.70	00.10	71.71
D	0	254.48	1/13 55	50.88	60.34	51 35
D	4	77.28	140.00	50.00	05.54	01.00

Table 5: Comparison of the first frequency of the arch using the tangent stiffness $k_{\rm T}$ and the secant stiffness $k_{\rm S}$ evaluated in node 673 with the numerical frequency obtained via linear perturbation analysis.

Code	P [kN]	$k_{\rm T} \; [{\rm kN/m}]$	$k_{\rm S} \; [{\rm kN/m}]$	$\tilde{f}_{1,\mathrm{T}}$ [Hz]	$\tilde{f}_{1,\mathrm{S}}$ [Hz]	$f_{1,j}$ [Hz]
N	0	180.68	112 31	54 16	72.79	51 24
	4	62.16	112.01	01.10	12.15	01.24
М	0	173.20	133.68	46 54	70.75	41 41
111	4	53.23	100.00	40.04	10.10	71.71
D	0	180.68	11/ 60	54 78	73 56	51 35
D	4	63.61	114.05	04.10	10.00	01.00

Table 6: Comparison of the first frequency of the arch using the tangent stiffness $k_{\rm T}$ and the secant stiffness $k_{\rm S}$ evaluated in node 755 with the numerical frequency obtained via linear perturbation analysis.

³⁴⁴ 4. Application to a real case study: the Mogadouro clock tower

345 4.1. Description of the case study

The Mogadouro clock tower (Figure 15) is a historic masonry structure 346 located inside the castle perimeter of the homonymous town in the Northeast 347 of Portugal and likely built after 1559 to serve the neighbouring church as 348 a bell tower. The fabric features a rectangular cross section of 4.7 x4.7 m², 349 with masonry walls of about 1 m thickness, and a height of 20.4 m. The 350 central part of the walls is built of rubble stones with thick mortar joints, 351 whereas the corners are made of large granite units with dry joints. Eight 352 masonry columns support the roof body, forming two rectangular openings 353 of about $0.9 \times 2.0 \text{ m}^2$ per façade. 354



Figure 15: Clock tower and castle of Mogadouro.

Due to the lack of maintenance, the tower did appear in very poor condi-355 tions. Beyond material degradation and biological growth, out-of-plane dis-356 placements and cracks could be clearly observed. The most damaged parts 357 were the East and West façades, where two deep passing cracks were about 358 to separate the box cross section of the tower into two U halves (Figures 16, 359 17). As the structural safety was jeopardized, rehabilitation works aimed at 360 reinstating the sound condition of the structure were carried out in 2005. 361 The intervention included: lime grout injections for sealing and walls consol-362 idation, substitution of deteriorated material, and installation of pre-stressed 363 tie-rods to restrain cracks from possible reopening. 364



Figure 16: Damage in the tower: (a) South, (b) East, (c) North and (d) West façades; cracks on the (e) East and (f) West fronts; (g) inner crack in the West façade; and (h) example of material loss [44], [45].

365 4.2. Dynamic identification of the tower before and after rehabilitation

To evaluate the structural response pre- and post-rehabilitation, two campaigns of Ambient Vibrations Tests (AVTs) were carried out making use of ambient excitation sources, such as wind and traffic [44], [45]. The response of the tower was measured in 54 selected points distributed along three levels, according to the layout displayed in Figure 17. The dynamic equipment consisted of 4 uniaxial piezoelectric accelerometers with a bandwidth ranging from 0.15 to 1000 Hz (5%), a dynamic range of ± 0.5 g, a sensitivity of

10 V/g, $8\mu g$ of resolution and 0.21 kg of weight, connected by coaxial cables 373 to a front-end data acquisition system with a 24-bit ADC, provided with 374 anti-aliasing filters. The front-end was connected to a laptop by an Ethernet 375 cable. The accelerometers were bolted to aluminium plates, which were in 376 turn glued to the stones through an epoxy layer. As the acquisition system 377 was composed only by 4 channels, 27 test setups were necessary to record 378 the accelerations in all selected measurement points. A preliminary FE dy-379 namic analysis assisted in the selection of the acquisition parameters. Thus, 380 to ensure an acquisition time window 2000 times larger than the estimated 381 fundamental period of the structure, the output signals were recorded with 382 a sampling frequency of 256 Hz for a duration of about 11 minutes. Same 383 test planning and measurement points were adopted before and after the 384 reinstatement works. 385



Figure 17: Sensor layout for AVTs: (a) South, (b) East, (c) North and (d) West façades [44], [45].

For each structural condition (before and after rehabilitation), the modal 386 parameters were estimated by comparing the results from two established and 387 complementary OMA techniques: the Enhanced Frequency Domain Decom-388 position (EFDD) method and the Stochastic Subspace Identification (SSI) 389 method, both implemented in ARTeMIS software [3]. In total, seven modes 390 of vibration were identified in the frequency ranges 2-9 Hz and 2-17 Hz for 391 the damaged and undamaged conditions, respectively. Tables 7 and 8 sum-392 marize the obtained results in terms of natural frequencies $f_{i,exp}$, damping 393 ratios $\xi_{i,exp}$, Coefficient of Variation CV and percentage differences Δ before 394 and after rehabilitation. Mode shapes and MAC values are illustrated in 395

	Before		Aft	A [07]	
Mode	$f_{\rm i,exp}[{\rm Hz}]$	$\mathrm{CV}_f[\%]$	$f_{\rm i,exp}[{\rm Hz}]$	$\mathrm{CV}_f[\%]$	Δ_f [%]
1	2.15	1.85	2.56	0.21	+19.28
2	2.58	1.05	2.76	0.30	+6.70
3	4.98	0.69	7.15	0.27	+43.67
4	5.74	1.56	8.86	0.47	+54.37
5	6.76	1.13	9.21	0.21	+36.13
6	7.69	2.94	15.21	2.24	+97.87
7	8.98	1.21	16.91	1.40	+88.27
Avg	—	1.49	—	0.73	+49.47

Figure 18. For the sake of brevity, only the modal features identified by the 396 SSI are shown.

397

Table 7: Dynamic response of Mogadouro tower before and after rehabilitation in terms of frequencies [44], [45].

M. 1.	Before		Aft	A [07]	
Mode	$\xi_{ m i,exp}[\%]$	$\mathrm{CV}_{\xi}[\%]$	$\xi_{ m i,exp}[\%]$	$\mathrm{CV}_{\xi}[\%]$	Δ_{ξ} [%]
1	2.68	219.51	1.25	0.13	-53.26
2	1.71	94.02	1.35	0.17	-21.00
3	2.05	65.33	1.20	0.14	-41.32
4	2.40	24.27	1.31	0.13	-45.72
5	2.14	31.74	1.16	0.12	-45.65
6	2.33	55.98	2.54	0.24	+9.11
7	2.30	46.39	1.49	0.23	-35.07
Avg	2.23	76.75	1.47	0.17	-40.34

Table 8: Dynamic response of Mogadouro tower before and after rehabilitation in terms of damping [44], [45].



Figure 18: Experimental mode shapes and MAC values before and after rehabilitation works [44].

The comparison between the global parameters estimated before and after 398 the consolidation works revealed a significant increase of frequency values, 399 reading an average upshift of 50%, and a damping decrease of around 40%. 400 Such results consistently reflected the actual structural conditions of the 401 tower, i.e. a lower-stiffness system with ongoing non-linear phenomena effects 402 before rehabilitation and a higher-stiffness system with reduced non-linear 403 phenomena effects after rehabilitation. In what concerns the experimental 404 mode shapes, similar configurations were observed pre- and post-intervention 405 for the first five modes of vibration, identifying four dominant bending modes 406 in the two main planes of the tower (modes 1, 2, 4 and 5) and one torsional 407

mode (mode 3), whereas higher-frequency mode shapes (modes 6 and 7) 408 switched order after the works. Although comparable in configuration, the 409 presence of local damage mechanisms before the structural intervention did 410 likely induce local protuberances in the experimental mode shapes of the 411 damaged tower, especially in the upper part of the structure and in the areas 412 close to the cracks. Hence the poor degree of correlation characterizing the 413 mode shape vectors before and after (MAC < 0.65). On the contrary, the 414 structure featured a monolithic behaviour after the rehabilitation works. 415

416 4.3. Modal analysis with linear perturbation

In this subsection the linear perturbation analysis is applied to the Mo-417 gadouro clock tower. The analysis is performed by using only NOSA-ITACA 418 code for two reasons: (1) in DIANA, the Rankine plasticity model describing 419 the tensile regime of the material is implemented only for plane stress, plane 420 strain and axisymmetric elements, but not for brick elements, which are the 421 ones employed in modeling the tower; (2) the MARC code turned out to be 422 unable to reach the convergence for $\sigma_t = 0$ Pa, a value that is crucial for a 423 realistic modeling of eastern and western façades, where two passing cracks 424 were present before rehabilitation. 425

In [44] and [45] a FE model updating (based on standard modal analysis) is performed to tune the Young's modulus of different parts of the structure, in order to minimize the differences between numerical and experimental modal parameters (frequencies and mode shapes) of the tower after rehabili-

tation; subsequently, the Young's moduli obtained are reduced with the aim 430 of fitting the experimental frequencies and mode shapes of the tower before 431 rehabilitation. Here, a different approach is followed, based on model up-432 dating aimed at matching both fracture distribution and frequencies of the 433 tower. With the purpose of reproducing numerically the actual crack pattern 434 of the tower before rehabilitation and matching its experimental frequencies 435 as well, the scheme described in Section 2 (nonlinear static analysis 436 - linear perturbation – modal analysis) has been applied in an iter-437 ative way. In particular, once the solution to the equilibrium problem of the 438 structure subjected to its own weight is calculated along with the correspond-439 ing fracture distribution, linear perturbation analysis and modal analysis are 440 conducted to estimate frequencies and mode shapes of the tower in the pres-441 ence of cracks. The materials Young's moduli and tensile strengths are tuned 442 and their optimal values calculated in such a way as to match the crack 443 distribution and minimize the discrepancy between experimental 444 and numerical frequencies. The same procedure was then repeated to 445 tune the tensile strength of the repaired walls, keeping the Young's moduli 446 fixed and trying to match the experimental natural frequencies and mode 447 shapes of the tower after rehabilitation. 448

The FE mesh of the tower, shown in Figure 19, consists of 18024 isoparametric 8—node brick elements, 352 thick shell elements, used to discretize the roof, and 23467 nodes; the model includes also two meters of foundation [44], [45] with the same thickness as the façades. The tower is assumed to

be clamped at the base and constituted by the materials whose (optimal) 453 mechanical properties, calculated via model updating, are indicated in Table 454 9. The foundation is modeled by a linear elastic material, which is indeed an 455 acceptable assumption considering the high material compaction at the base 456 of the tower and the soil confinement. Regarding pillars and roof, the use of 457 a linear elastic material is suggested by the observation that these elements 458 do not affect the overall structural behavior of the tower. Indeed, the low 459 elastic modulus adopted for the roof does allow the tower cross section to 460 freely deform within its own plane. 461



Figure 19: Mogadouro tower, mesh and distribution of material properties (before rehabilitation).

Mat. n°	Tower's portion	$\varrho[kg/m^3]$	E[GPa]	$\sigma_t[kPa]$
1 (orange)	façades South and North (bottom)	2200	2.500	15.0
2 (green)	façades East, West and North (top)	2200	2.500	0.0
3 (red)	corners	2400	3.500	15.0
4 (indigo)	pillars	2200	1.210	_
5 (grey)	roof	2000	0.195	—
6 (cyan)	foundation	2200	3.500	—

Table 9: Optimal values of the material mechanical properties before rehabilitation.

Numerical solution to the equilibrium problem for the optimal values of the Young's moduli and tensile strengths in Table 9 yields the results reported in Figures 20, 21 and 22 that show, for each façade, the actual (on the left) and numerical (on the right) crack patterns before rehabilitation. The South wall is not reported because it shows no cracks (neither in the numerical model nor in the reality). A very good agreement can be observed between real and numerical fracture strains.



Figure 20: Mogadouro tower West façade, surveyed (on the left) and numerical (on the right) cracking pattern.



Figure 21: Mogadouro tower North façade, surveyed (on the left) and numerical (on the right) cracking pattern.



Figure 22: Mogadouro tower East façade, surveyed (on the left) and numerical (on the right) cracking pattern.

Table 10 summarizes the results of the modal analysis before rehabilitation in terms of experimental $(f_{i,exp})$ and numerical $(f_{i,N})$ frequencies, relative frequency error, and MAC values between experimental and numerical mode shapes (evaluated considering just the nodes monitored during the experimental campaigns [44], [45]). The four frequencies and the first two mode shapes are very well approximated, while the correlation of the third and fourth numerical mode shapes with their experimental counterparts is quite

low (particularly for the fourth mode). The poor match between the 476 third experimental and numerical mode shapes before rehabilita-477 tion is inherent to the adopted modeling strategy and likely due to 478 the fact that, as far as the numerical solution is concerned, pass-479 ing cracks in the East and West façades do not allow the tower's 480 section to undergo torsional deformations. On the contrary, in the 481 real case, such a deformation is made possible by interlocking ef-482 fect and friction between the units. It is also possible that other 483 (non-visible damage) can affect this mode. 484

Mode	$f_{\rm i,exp}$ [Hz]	$f_{\rm i,N}$ [Hz]	$\Delta_f[\%]$	MAC
1	2.15	2.15	0.00	0.94
2	2.58	2.60	-0.78	0.96
3	4.98	4.92	1.20	0.32
4	5.74	5.88	-2.44	0.01

Table 10: Comparison between experimental $(f_{i,exp})$ and numerical frequencies $(f_{i,N})$; relative frequency error $\Delta_f = (f_{i,exp} - f_{i,N})/f_{i,exp}$ and MAC values before rehabilitation.

Figure 23 shows the first four experimental and numerical (calculated by NOSA-ITACA) mode shapes of the Mogadouro tower before rehabilitation.



Figure 23: First four mode shapes of the Mogadouro tower before rehabilitation.

Subsequently, the same FE model is adopted to perform the analysis of the tower after rehabilitation, considering a tensile strength $\sigma_t = 10$ kPa for the restored walls (material 2 in Figure 19), while the other mechanical properties are kept fixed.

The results are summarized in table 11; Figure 24 shows the first four experimental and numerical mode shapes after rehabilitation. All frequencies increase with respect to the unreinforced case, consistently with the experimental results. In this case, a good approximation is achieved for all four mode shapes, and a very great accuracy is obtained in the assessment
of the first two frequencies.

Mode	$f_{\rm i,exp}$ [Hz]	$f_{\rm i,N}$ [Hz]	$\Delta_f[\%]$	MAC
1	2.56	2.59	-1.17	0.98
2	2.76	2.75	0.36	0.98
3	7.15	8.39	-17.34	0.97
4	8.86	9.32	-5.19	0.74

Table 11: Comparison between experimental $(f_{i,exp})$ and numerical frequencies $(f_{i,N})$; relative frequency error $\Delta_f = (f_{i,exp} - f_{i,N})/f_{i,exp}$ and MAC values after rehabilitation.



Figure 24: First four mode shapes of the Mogadouro tower after rehabilitation.

Table 12 recapitulates experimental and numerical results in terms of 497 natural frequencies, before and after rehabilitation of the tower, pointing out 498 that the linear perturbation analysis allows to catch the dynamic behavior 499 of the structure in damaged conditions with reasonable accuracy. The table 500 shows also that the numerical increase of the natural frequencies, due to 501 restoration of the tower and obtained in the numerical model through an 502 increase of tensile strength of the damaged walls, is in agreement with the 503 experimental results, apart from the third frequency, which is overestimated 504 by the code. 505

Mode	Before		After		$\Delta_f[\%]$	
Mode	$f_{\rm i,exp}$ [Hz]	$f_{\rm i,N} [{\rm Hz}]$	$f_{\rm i,exp}$ [Hz]	$f_{\rm i,N}$ [Hz]	exp	num
1	2.15	2.15	2.56	2.59	+19.28	+20.46
2	2.58	2.60	2.76	2.75	+6.70	+5.77
3	4.98	4.92	7.15	8.39	+43.67	+70.52
4	5.74	5.88	8.86	9.32	+54.37	+58.50

Table 12: Summary of the experimental and numerical results before and after rehabilitation.

For the sake of comparison, the optimal values of the Young's modulus $E_{\rm S}$ calculated via a model updating based on standard modal analysis [44], [45] are reported in table 13 together with the corresponding values $E_{\rm NL}$ obtained by a model updating based on linear perturbation analysis. As expected, in the standard modal analysis the lowest values of the Young's modulus are obtained in the cracked façades.

	Before		After		
	$E_{\rm S}[GPa]$	$E_{\rm LP}[GPa]$	$E_{\rm S}[GPa]$	$E_{\rm LP}[GPa]$	
South façade	0.687	2.500	1.974	2.500	
North façade	2.210	2.500	2.210	2.500	
West façade	0.302	2.500	1.075	2.500	
East façade	0.276	2.500	0.804	2.500	
Corners	3.870	3.500	3.875	3.500	

Table 13: Comparison between the optimal values of the Young's modulus $E_{\rm S}$ (standard modal analysis) and $E_{\rm LP}$ (linear perturbation and modal analysis).

Tables 14 and 15 show the frequencies and MAC values calculated via standard modal analysis and linear perturbation analysis, before and after rehabilitation; for the sake of completeness the experimental frequencies are reported as well.

Mada	f [II_]	Linear Perturbation			Standard		
mode	$J_{i,exp}$ [ΠZ]	$f_{\rm i}$ [Hz]	$\Delta_f[\%]$	MAC	$f_{\rm i}$ [Hz]	$\Delta_f[\%]$	MAC
1	2.15	2.15	0.00	0.94	2.07	3.72	0.97
2	2.58	2.60	-0.78	0.96	2.40	6.98	0.97
3	4.98	4.92	1.20	0.32	5.14	-3.21	0.96
4	5.74	5.88	-2.44	0.01	5.88	-2.44	0.73

Table 14: Comparison between the frequencies calculated via standard modal analysis and linear perturbation before rehabilitation.

Mode	$f_{\rm i,exp}$ [Hz]	Linear Perturbation			Standard		
		$f_{\rm i}$ [Hz]	$\Delta_f[\%]$	MAC	$f_{\rm i}$ [Hz]	$\Delta_f[\%]$	MAC
1	2.56	2.59	-1.17	0.98	2.54	0.78	0.99
2	2.76	2.75	0.36	0.98	2.68	2.90	0.99
3	7.15	8.39	-17.34	0.97	7.33	-2.52	1.00
4	8.86	9.32	-5.19	0.74	8.62	2.71	0.98

Table 15: Comparison between the frequencies calculated via standard modal analysis and linear perturbation after rehabilitation.

517 5. Conclusions

The present paper investigated the dependence of the dynamic properties 518 of masonry structures on the nonlinear behavior of the constituent materials. 519 As the mechanical response of masonry constructions is remarkably differ-520 ent in tension and in compression, and cracks may arise due permanent and 521 accidental loads, standard modal analysis may result unrealistic. In this 522 context, a linear perturbation approach must be used to adequately estimate 523 the dynamic properties of masonry constructions in the presence of cracked 524 regions. After a brief description of the constitutive equations and numer-525 ical procedures implemented in different FE codes (NOSA-ITACA, DIANA 526 and MARC), the proposed approach, which couples linear perturbation and 527 modal analysis, is described. The numerical procedure is then applied to 528 a masonry arch with the aim of comparing and cross-validating the results 529 obtained from the afore-mentioned FE codes in terms of natural frequencies 530 and mode shapes for decreasing values of tensile strength. It is demonstrated 531 that, despite the different constitutive equations the three codes rely on, the 532 dependence of the dynamic properties of the masonry arch on the applied 533 loads and induced crack distribution is consistent among the three of them, 534 showing comparable frequency downshifts and MAC values over the different 535 damage scenarios. Finally, with the purpose of validating the same approach 536 on a real case-study structure, the procedure is applied to a historic masonry 537 tower affected by a serious crack pattern. After solving the nonlinear equilib-538 rium problem of the structure subjected to its own weight and reproducing 539

the actual fracture distribution, a modal analysis about the equilibrium so-540 lution is carried out to estimate frequencies and mode shapes of the tower 541 in the presence of cracks as well as after the rehabilitation works. A FE 542 model updating is used to tune the optimal values for both Young's modu-543 lus and tensile strength in the different parts of the tower, according to the 544 observed structural conditions before and after the intervention. The com-545 parison between numerical and experimental results showed that 546 the combination of linear perturbation and modal analysis enables 547 to estimate with reasonable accuracy the first two frequencies and 548 mode shapes of the masonry tower in both damaged and reinforced 549 conditions. The method proposed seems to be promising and fur-550 ther applications are necessary to confirm the reliability of the 551 adopted approach for the solution of the dynamic problem in case 552 of structures built with masonry materials. 553

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